

# Tiva™ C Series TM4C123x

**ROM USER'S GUIDE** 

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# **Revision Information**

This is version 818 of this document, last updated on May 14, 2014.

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# 1 Introduction

#### Note:

This document describes the complete set of TM4C123x APIs. Not all API functions are supported in all devices. Refer to the datasheet for your specific device to determine which peripherals / APIs are supported for your device.

The TM4C123x ROM contains the TivaWare<sup>TM</sup> Peripheral Driver Library and the TivaWare Boot Loader. The peripheral driver library can be utilized by applications to reduce their flash footprint, allowing the flash to be used for other purposes (such as additional features in the application). The boot loader is used as an initial program loader (when the flash is empty) as well as an application-initiated firmware upgrade mechanism (by calling back to the boot loader).

There is a table at the beginning of the ROM that points to the entry points for the APIs that are provided in the ROM. Accessing the API through these tables provides scalability; while the API locations may change in future versions of the ROM, the API tables will not. The tables are split into two levels; the main table contains one pointer per peripheral which points to a secondary table that contains one pointer per API that is associated with that peripheral. The main table is located at  $0 \times 0100.0010$ , right after the Cortex-M4 vector table in the ROM.

The following table shows a small portion of the API tables in a graphical form that helps to illustrate the arrangement of the tables:

ROM_APITABLE (at 0x0100.0010)		
[0] = ROM_VERSION		
[1] = pointer to ROM_UARTTABLE		
[2] = pointer to ROM_SSITABLE		
[3] = pointer to ROM_I2CTABLE		
[4] = pointer to ROM_GPIOTABLE	$\implies$	ROM_GPIOTABLE
[5] = pointer to ROM_ADCTABLE		[0] = pointer to ROM_GPIOPinWrite
[6] = pointer to ROM_COMPARATORTABLE		[1] = pointer to ROM_GPIODirModeSet
[7] = pointer to ROM_FLASHTABLE		[2] = pointer to ROM_GPIODirModeGet

From this, the address of the ROM\_GPIOTABLE table is located in the memory location at  $0 \times 0100.0020$ . The address of the ROM\_GPIODirModeSet() function is contained at offset  $0 \times 4$  from that table. In the function documentation, this is represented as:

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].
ROM_GPIODirModeSet is a function pointer located at ROM_GPIOTABLE[1].
```

The TivaWare Peripheral Driver Library contains a file called <code>driverlib/rom.h</code> that assists with calling the peripheral driver library functions in the ROM. The naming conventions for the tables and APIs that are used in this document match those used in that file.

The following is an example of calling the ROM GPIODirModeSet() function:

```
#define TARGET_IS_BLIZZARD_RB1
#include <stdbool.h>
#include <stdint.h>
#include "inc/hw_memmap.h"
#include "driverlib/gpio.h"
#include "driverlib/rom.h"
```

```
int
main(void)
{
    // ...
    ROM_GPIODirModeSet(GPIO_PORTA_BASE, GPIO_PIN_0, GPIO_DIR_MODE_OUT);
    // ....
}
```

See the "Using the ROM" chapter of the *TivaWare Peripheral Driver Library User's Guide* for more details on calling the ROM functions and using driverlib/rom.h.

The API provided by the ROM can be utilized by any compiler so long as it complies with the Embedded Applications Binary Interface (EABI), which includes all recent compilers for the Cortex-M4 microcontroller.

# **Documentation Overview**

The ROM-based TivaWare Boot Loader is described in chapter 2, and the ROM-based TivaWare Peripheral Driver Library is described in chapters 3 through 25.

# 2 Boot Loader

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# 2.1 Introduction

The ROM-based boot loader is executed each time the device is reset when the flash is empty. The flash is assumed to be empty if the first two words are all ones (since the second word is the reset vector address, it must be programmed for an application in flash to execute). When run, it will allow the flash to be updated using one of the following interfaces:

- UART0 using a custom serial protocol
- SSI0 using a custom serial protocol
- I2C0 using a custom serial protocol
- USB using DFU protocol

The USB portion of the boot loader must run with the main PLL enabled which requires not only that the boot loader detect if a crystal is present, but also determine the frequency of the attached crystal to properly configure the main PLL. This crystal detection algorithm is only run when the boot loader does not find a valid application and is not run when the boot loader is called from an application. The device is configured to run from the PLL when there is a valid external crystal for USB operation as specified in the data sheet.

The LM Flash Programmer GUI can be used to download an application via the boot loader over the UART or USB interface on a PC. The LM Flash Programmer utility is available for download from www.ti.com/tiva-c.

# 2.2 Serial Interfaces

The serial interfaces used to communicate with the boot loader share a common protocol and differ only in the physical connections and signaling used to transfer the bytes of the protocol.

# 2.2.1 UART Interface

The UART pins **U0Tx** and **U0Rx** are used to communicate with the boot loader. The device communicating with the boot loader is responsible for driving the **U0Rx** pin, while the microcontroller drives the **U0Tx** pin.

The serial data format is fixed at 8 data bits, no parity, and one stop bit. An auto-baud feature is used to determine the baud rate at which data is transmitted. Because the system clock must be at least 32 times the baud rate, the maximum baud rate that can be used is 500 Kbaud (which is 16 MHz divided by 32).

When an application calls back to the ROM-based boot loader to start an update over the UART port, the auto-baud feature is bypassed, along with UART configuration and pin configuration.

Therefore, the UART must be configured and the UART pins switched to their hardware function before calling the boot loader.

### 2.2.2 SSI Interface

The SSI pins **SSIFss**, **SSICIk**, **SSITx**, and **SSIRx** are used to communicate with the boot loader. The device communicating with the boot loader is responsible for driving the **SSIRx**, **SSICIk**, and **SSIFss** pins, while the microcontroller drives the **SSITx** pin.

The serial data format is fixed to the Motorola format with SPH set to 1 and SPO set to 1 (see the data sheet for more information on this format). Since the system clock must be at least 12 times the serial clock rate, the maximum serial clock rate that can be used is 1.3 MHz (which is 16 MHz divided by 12).

When an application calls back to the ROM-based boot loader to start an update over the SSI port, the SSI configuration and pin configuration is bypassed. Therefore, the SSI port must be configured and the SSI pins switched to their hardware function before calling the boot loader.

### 2.2.3 I2C Interface

The I2C pins I2CSCL and I2CSDA are used to communicate with the boot loader. The device communicating with the boot loader must operate as the I2C master and provide the I2CSCL signal. The I2CSDA pin is open-drain and can be driven by either the master or the slave I2C device.

The I2C interface can run at up to 400 KHz, the maximum rate supported by the I2C protocol. The boot loader uses an I2C slave address of 0x42.

When an application calls back to the ROM-based boot loader to start an update over the I2C port, the I2C configuration and pin configuration is bypassed. Therefore, the I2C port must be configured, the I2C slave address set, and the I2C pins switched to their hardware function before calling the boot loader. Additionally, the I2C master must be enabled since it is used to detect start and stop conditions on the I2C bus.

### 2.2.4 Serial Protocol

The boot loader uses well-defined packets on the serial interfaces to ensure reliable communications with the update program. The packets are always acknowledged or not acknowledged by the communicating devices. The packets use the same format for receiving and sending packets. This includes the method used to acknowledge successful or unsuccessful reception of a packet. While the actual signaling on the serial ports is different, the packet format remains independent of the method of transporting the data.

The following steps must be performed to successfully send a packet:

- 1. Send the size of the packet that will be sent to the device. The size is always the number of bytes of data + 2 bytes.
- 2. Send the checksum of the data buffer to help ensure proper transmission of the command. The checksum is simply a sum of the data bytes.
- 3. Send the actual data bytes.

4. Wait for a single-byte acknowledgment from the device that it either properly received the data or that it detected an error in the transmission.

The following steps must be performed to successfully receive a packet:

- 1. Wait for non-zero data to be returned from the device. This is important as the device may send zero bytes between a sent and received data packet. The first non-zero byte received will be the size of the packet that is being received.
- 2. Read the next byte which will be the checksum for the packet.
- 3. Read the data bytes from the device. There will be packet size 2 bytes of data sent during the data phase. For example, if the packet size was 3, then there is only 1 byte of data to be received.
- 4. Calculate the checksum of the data bytes and ensure that it matches the checksum received in the packet.
- 5. Send an acknowledge (ACK) or not-acknowledge (NAK) to the device to indicate the successful or unsuccessful reception of the packet.

An acknowledge packet is sent whenever a packet is successfully received and verified by the boot loader. A not-acknowledge packet is sent whenever a sent packet is detected to have an error, usually as a result of a checksum error or just malformed data in the packet. This allows the sender to re-transmit the previous packet.

The following commands are used by the custom protocol:

```
COMMAND_PING = 0x20
```

This command is used to receive an acknowledge from the boot loader indicating that communication has been established. This command is a single byte.

The format of the command is as follows:

```
uint8_t pui8Command[1];
pui8Command[0] = COMMAND_PING;
```

COMMAND\_DOWNLOAD = 0x21

This command is sent to the boot loader to indicate where to store data and how many bytes will be sent by the COMMAND\_SEND\_DATA commands that follow. The command consists of two 32-bit values that are both transferred MSB first. The first 32-bit value is the address to start programming data into, while the second is the 32-bit size of the data that will be sent. This command also triggers a mass erase of the flash, which causes the command to take longer to send the ACK/NAK in response to the command. This command should be followed by a COMMAND\_GET\_STATUS to ensure that the program address and program size were valid for the microcontroller running the boot loader.

The format of the command is as follows:

```
uint8_t pui8Command[9];
pui8Command[0] = COMMAND_DOWNLOAD;
pui8Command[1] = Program Address [31:24];
pui8Command[2] = Program Address [23:16];
pui8Command[3] = Program Address [7:0];
pui8Command[4] = Program Address [7:0];
pui8Command[5] = Program Size [31:24];
pui8Command[6] = Program Size [23:16];
pui8Command[7] = Program Size [15:8];
pui8Command[8] = Program Size [7:0];
```

 $COMMAND_RUN$ = 0x22

This command is sent to the boot loader to transfer execution control to the specified address. The command is followed by a 32-bit value, transferred MSB first, that is the address to which execution control is transferred.

The format of the command is as follows:

```
uint8_t pui8Command[5];
pui8Command[0] = COMMAND_RUN;
pui8Command[1] = Run Address [31:24];
pui8Command[2] = Run Address [23:16];
pui8Command[3] = Run Address [15:8];
pui8Command[4] = Run Address [7:0];
```

COMMAND\_GET\_STATUS = 0x23

This command returns the status of the last command that was issued. Typically, this command should be received after every command is sent to ensure that the previous command was successful or, if unsuccessful, to properly respond to a failure. The command requires one byte in the data of the packet and the boot loader should respond by sending a packet with one byte of data that contains the current status code.

The format of the command is as follows:

```
uint8_t pui8Command[1];
pui8Command[0] = COMMAND_GET_STATUS;
```

The following are the definitions for the possible status values that can be returned from the boot loader when COMMAND\_GET\_STATUS is sent to the the microcontroller.

```
COMMAND_RET_SUCCESS
COMMAND_RET_UNKNOWN_CMD
COMMAND_RET_INVALID_CMD
COMMAND_RET_INVALID_ADD
COMMAND_RET_FLASH_FAIL
```

COMMAND\_SEND\_DATA = 0x24 This command should only follow a COMMAND\_DOWNLOAD command or another COMMAND\_SEND\_DATA command, if more data is needed. Consecutive send data commands automatically increment the address and continue programming from the previous location. The transfer size is limited by the maximum size of a packet, which allows up to 252 data bytes to be transferred at a time. The command terminates programming once the number of bytes indicated by the COMMAND\_DOWNLOAD command has been received. Each time this function is called, it should be followed by a COMMAND\_GET\_STATUS command to ensure that the data was successfully programmed into the flash. If the boot loader sends a NAK to this command, the boot loader will not increment the current address which allows for retransmission of the previous data.

The format of the command is as follows:

```
uint8_t pui8Command[9];
pui8Command[0] = COMMAND_SEND_DATA
pui8Command[1] = Data[0];
pui8Command[2] = Data[1];
pui8Command[3] = Data[2];
pui8Command[4] = Data[3];
pui8Command[5] = Data[4];
pui8Command[6] = Data[5];
pui8Command[7] = Data[6];
pui8Command[8] = Data[7];
```

COMMAND\_RESET = 0x25

This command is used to tell the boot loader to reset. This is used after downloading a new image to the microcontroller to cause the new application to start from a reset. The normal boot sequence occurs and the image runs as if from a hardware reset. It can also be used to reset the boot loader if a critical error occurs and the host device wants to restart communication with the boot loader.

The boot loader responds with an ACK signal to the host device before actually executing the software reset on the microcontroller running the boot loader. This informs the updater application that the command was received successfully and the part will be reset.

The format of the command is as follows:

```
uint8_t pui8Command[1];
pui8Command[0] = COMMAND_RESET;
```

The definitions for these commands are provided as part of the Tiva Peripheral Driver Library, in boot loader/bl commands.h.

# 2.3 USB Interface

The USB boot loader allows programming the flash over USB using the standard USB DFU update method. To use the USB boot loader, the system running the boot loader must be capable of acting as a USB device and have the proper USB B or USB AB connector. The boot loader does not support firmware update of systems which operate solely as USB hosts. The USB update mechanism allows the boot loader to either be called from a functioning application or from startup when no firmware has been downloaded to the microcontroller. When the USB boot loader is called from an application, the application can customize some of the descriptors that are used for enumeration. This customization option is not available when the microcontroller is being programmed and there is no application present on the microcontroller.

When the USB boot loader is invoked from a running application, the boot loader reconfigures the USB controller to publish the required descriptor set for a Device Firmware Upgrade (DFU) class device and merge in any custom values that the application provides. Before calling the boot loader from an application, the main application is responsible for the following: enable the main PLL and configure it as the system clock, enable the USB PLL, enable the USB controller, and enable the USB D+ and D- pins on the microcontroller. If the main application is already acting as a USB device, then the application must remove the device from the bus by calling the DriverLib function ROM\_USBDevDisconnect () prior to entering the boot loader.

# 2.3.1 USB Device Firmware Upgrade Overview

The USB boot loader enumerates as a Device Firmware Upgrade (DFU) class device. This standard device class specifies a set of class-specific requests and a state machine that can be used to download and flash firmware images to a device and, op-

tionally, upload the existing firmware image to the USB host. The full specification for the device class can be downloaded from the USB Implementer's Forum web site at http://www.usb.org/developers/devclass\_docs#approved.

All communication with the DFU device takes place using the USB control endpoint, endpoint 0. The device publishes a standard device descriptor with vendor, product, device revisions and strings. It also publishes a single configuration descriptor and a single interface descriptor where the interface class of 0xFE indicates an application-specific class and the subclass of 0x01 indicates "Device Firmware Upgrade". Attached to the interface descriptor is a DFU Functional Descriptor which provides information to the host on DFU-specific device capabilities such as whether the device can perform upload operations and what the maximum transfer size for upload and download operations is.

DFU functions are initiated by means of a set of class-specific requests. Each request, which follows the standard USB request format, performs some operation and moves the DFU device between a series of well-defined states. Additional requests allow the host to query the current state of the device to determine whether, for example, it is ready to receive the next block of download data.

A DFU device may operation in either "Run Time" mode or "DFU" mode. In "Run Time" mode, the device publishes the DFU interface and functional descriptors along with any other descriptors that the device requires for normal operation. However, it is not required to respond to any DFU class-specific requests other than DFU\_DETACH which indicates that it should switch to "DFU" mode. The "Run Time" mode support is not part of the USB boot loader but can be added to a USB device application to provide simple switching to "DFU" mode. If a main application wishes to publish DFU descriptors and respond to the DFU\_DETACH request, it can cause a switch to "DFU" mode on receiving a DFU\_DETACH request by removing itself from the USB bus using a call to ROM\_USBDevDisconnect() before transferring control to the USB boot loader by making a call to ROM\_UpdateUSB(). Once in "DFU" mode in the boot loader, the device supports all DFU functionality and can perform upload and download operations as specified in its DFU functional descriptor.

# 2.3.2 DFU Requests

Requests supported by the USB boot loader are as follow:

DFU DNLOAD

This OUT request is used to send a block of binary data to the device. The DFU class specification does not define the content and format of the binary data but typically it is either binary data to be written to some position in the device's flash memory or a device-specific command. The request payload size is constrained by the maximum packet size specified in the DFU functional descriptor. In this implementation, that maximum is set to 1024 bytes.

After sending a DFU\_DNLOAD request, the host must poll the device status and wait until the state reverts to DNLOAD\_IDLE before sending another request. If the host wishes to indicate that it has finished sending download data, it sends a DFU\_DNLOAD request with a payload length of 0.

DFU\_UPLOAD

This IN request is used to request a block of binary data from the device. The data returned is device-specific but is typically the contents of a region of the device's flash memory or a device-specific response to a command previously sent via a DFU\_DNLOAD request. As with DFU\_DNLOAD, the maximum amount of data that can be requested is governed by the maximum packet size specified in the DFU functional descriptor, here 1024 bytes.

DFU\_GETSTATUS

This IN request allows the host to query the current status of the DFU device. It is typically used during download operations to determine when it is safe to send the next block of data. Depending upon the state of the DFU device, this request may also trigger a state change. During download, for example, the device enters <code>DNLOAD\_SYNC</code> state after receiving a block of data and remains there until the data has been processed and a <code>DFU\_GETSTATUS</code> request is received at which point the state changes to <code>DNLOAD\_IDLE</code>.

DFU\_CLRSTATUS

This request is used to reset any error condition reported by the DFU device. If an error is reported via the response to a DFU\_GETSTATUS request, that error condition is cleared when this request is received and the device returns to IDLE state.

DFU\_GETSTATE

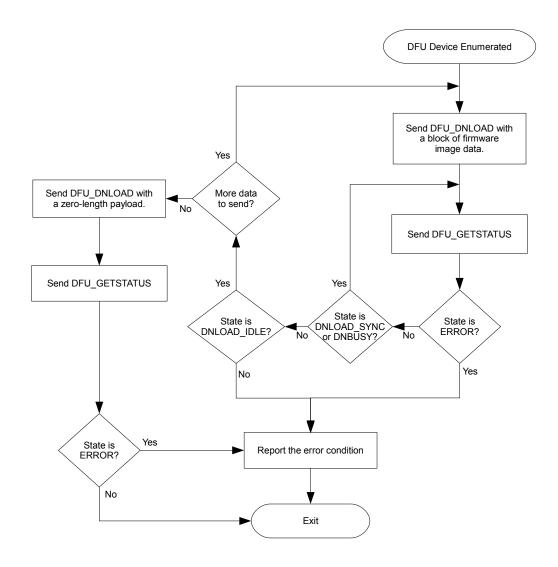
This IN request is used to query the current state of the device without triggering any state change. The single byte of data returned indicates the current state of the DFU device.

DFU\_ABORT

This request cancels any partially complete upload or download operation and returns the device to IDLE state in preparation for some other request.

# 2.3.3 Typical Firmware Download Sequence

The following flow chart illustrates a typical firmware image download sequence from the perspective of the host application.



# 2.3.4 Tiva-Specific USB Download Commands

The DFU class specification provides the framework necessary to download and upload firmware files to the USB device but does not specify the actual format of the binary data that is transferred. As a result, different device implementations have used different methods to perform operations that are not defined in the standard such as:

- Setting the address to flash a downloaded binary.
- Setting the address and size of the area of flash with contents to be uploaded.
- Erasing sections of the flash.
- Querying the size of flash and writeable area addresses.

The USB boot loader implementation employs a small set of commands which can be sent to the DFU device via a <code>DFU\_DNLOAD</code> request when the device is in IDLE state. Each command takes the form of an 8-byte structure that defines the operation to carry out and provides any required additional parameters.

To ensure that a host application that does not have explicit support for Tiva-specific commands can still be used to download binary firmware images to the device, the protocol is defined such that only a single 8-byte header structure must be placed at the start of the binary image being downloaded. This header and the DFU-defined suffix structure can both be added using the "dfuwrap" command-line application supplied with TivaWare, thus providing a single binary that can be sent to a device running the Tiva USB boot loader using a standard sequence of DFU\_DNLOAD requests with no other embedded commands or device-specific operations required. An application which does understand the Tiva-specific commands may make use of them to offer additional functionality that would not otherwise be available.

# **Querying Command Support**

Because the device-specific commands defined here are sent to the DFU device in <code>DFU\_DNLOAD</code> requests, the possibility exists that sending them to a device which does not understand the protocol could result in corruption of that device's firmware. To guard against this possibility, the USB boot loader supports an additional USB request which is used to query the device capabilities and allow a host to determine whether or not the device supports the Tiva commands. A device which does not support the commands either stalls the request or returns unexpected data.

To determine whether a target DFU device supports the Tiva-specific DFU commands, send the following IN request to the DFU interface:

bmRequest- Type	bRequest	wValue	wIndex	wLength	Data
10100001b	0x42	0x23	Interface	4	Protocol Info

where the protocol information returned is a 4-byte structure, the first two bytes of which are 0x4D, 0x4C and the second two bytes indicates the protocol version supported, currently 0x01 and 0x00 respectively.

## **Download Command Definitions**

The following commands may be sent to the USB boot loader as the first 8 bytes of the payload to a DFU DNLOAD request. The boot loader expects any DFU DNLOAD request received while in the

IDLE state to contain a command header but does not look for a command unless the state is IDLE. This protocol allows an application that is unaware of the command header to download a DFU-wrapped binary image using a standard sequence of multiple <code>DFU\_DNLOAD</code> and <code>DFU\_GETSTATUS</code> requests without the need to insert additional command headers during the download.

The commands defined here and their parameter block structures can be found in header file usbdfu.h provided with TivaWare. In all cases where multi-byte numbers are specified, the numbers are stored in little-endian format with the least significant byte in the lowest addressed location. The following definitions specify the command byte ordering unambiguously but care must be taken to ensure correct byte swapping if using the command structure types defined in usbdfu.h on bigendian systems.

DFU\_CMD\_PROG

This command is used to provide the USB boot loader with the address at which the next download should be written and the total length of the firmware image that follows. This structure forms the header that is written to the DFU-wrapped file generated by the dfuwrap tool.

The start address is provided in terms of 1024-byte flash blocks. To convert a byte address to a block address, merely divide by 1024. The start address must always be on a 1024-byte boundary.

This command may be followed by up to 1016 bytes of firmware image data, this number being the maximum transfer size minus the 8 bytes of the command structure.

The format of the command is as follows:

```
uint8_t pui8Data[8];
pui8Data[0] = DFU_CMD_PROG (0x01)
pui8Data[1] = Reserved - set to 0x00
pui8Data[2] = Start Block Number [7:0];
pui8Data[3] = Start Block Number [15:8];
pui8Data[4] = Image Size [7:0];
pui8Data[5] = Image Size [15:8];
pui8Data[6] = Image Size [23:16];
pui8Data[7] = Image Size [31:24];
```

DFU\_CMD\_READ

This command is used to set the address range of the content to be returned on subsequent DFU\_UPLOAD requests from the host.

The start address is provided in terms of 1024-byte flash blocks. To convert a byte address to a block address, divide by 1024. The start address must always be on a 1024-byte boundary.

To read back a the contents of a region of flash, the host should send a DFU\_DNLOAD request with command DFU\_CMD\_READ, start address set to the 1KB block start address and length set to the number of bytes to read. The host should then send one or more DFU\_UPLOAD requests to receive the current flash contents from the configured addresses. Data returned includes an 8-byte DFU\_CMD\_PROG prefix structure unless the prefix has been disabled by sending a DFU\_CMD\_BIN command with the bBinary parameter set to 1. The host should, therefore, be prepared to read 8 bytes more than the length specified in the READ command if the prefix is enabled.

By default, the 8-byte prefix is enabled for all upload operations. This prefix is required by the DFU class specification which states that uploaded images must be formatted to allow them to be directly downloaded back to the device at a later time.

The format of the command is as follows:

```
uint8_t pui8Data[8];

pui8Data[0] = DFU_CMD_READ (0x02)
pui8Data[1] = Reserved - set to 0x00
pui8Data[2] = Start Block Number [7:0];
pui8Data[3] = Start Block Number [15:8];
pui8Data[4] = Image Size [7:0];
pui8Data[5] = Image Size [15:8];
pui8Data[6] = Image Size [23:16];
pui8Data[7] = Image Size [31:24];
```

DFU\_CMD\_CHECK

This command is used to check a region of flash to ensure that it is completely erased.

The start address is provided in terms of 1024-byte flash blocks. To convert a byte address to a block address, divide by 1024. The start address must always be on a 1024-byte boundary. The length must also be a multiple of 4.

To check that a region of flash is erased, the DFU\_CMD\_CHECK command should be sent with the required start address and region length set then the host should issue a DFU\_GETSTATUS request. If the erase check was successful, the returned bStatus value is OK (0x00), otherwise it is errCheckErased (0x05).

The format of the command is as follows:

```
uint8_t pui8Data[8];
pui8Data[0] = DFU_CMD_CHECK (0x03)
pui8Data[1] = Reserved - set to 0x00
pui8Data[2] = Start Block Number [7:0];
pui8Data[3] = Start Block Number [15:8];
pui8Data[4] = Region Size [7:0];
pui8Data[5] = Region Size [15:8];
pui8Data[6] = Region Size [23:16];
pui8Data[7] = Region Size [31:24];
```

DFU CMD ERASE

This command is used to erase a region of flash.

The start address is provided in terms of 1024-byte flash blocks. To convert a byte address to a block address, divide by 1024. The start address must always be on a 1024-byte boundary. The length must also be a multiple of 4.

The size of the region to erase is expressed in terms of flash blocks. The block size can be determined using the <code>DFU\_CMD\_INFO</code> command.

The format of the command is as follows:

```
uint8_t pui8Data[8];
pui8Data[0] = DFU_CMD_ERASE (0x04)
pui8Data[1] = Reserved - set to 0x00
pui8Data[2] = Start Block Number [7:0];
pui8Data[3] = Start Block Number [15:8];
pui8Data[4] = Number of Blocks [7:0];
pui8Data[5] = Number of Blocks [15:8];
pui8Data[6] = Reserved - set to 0x00
pui8Data[7] = Reserved - set to 0x00
```

DFU\_CMD\_INFO

This command is used to query information relating to the target device and programmable region of flash. The device information structure, tDFUDeviceInfo, is returned on the next  $DFU\_UPLOAD$  request following this command.

The format of the command is as follows:

```
uint8_t pui8Data[8];
pui8Data[0] = DFU\_CMD\_INFO (0x05)
pui8Data[1] = Reserved - set to 0x00
pui8Data[2] = Reserved - set to 0x00
pui8Data[3] = Reserved - set to 0x00
pui8Data[4] = Reserved - set to 0x00
pui8Data[5] = Reserved - set to 0x00
pui8Data[6] = Reserved - set to 0x00
pui8Data[7] = Reserved - set to 0x00
//
// Payload returned in response to the DFU_CMD_INFO command.
// This is structure is returned in response to the first DFU_UPLOAD
// request following a DFU_CMD_INFO command. Note that byte ordering
// of multi-byte fields is little-endian.
//
//***************
typedef struct
    // The size of a flash block in bytes.
    uint16_t ui16FlashBlockSize;
    \ensuremath{//} The number of blocks of flash in the device. Total
    // flash size is usNumFlashBlocks * usFlashBlockSize.
    uint16_t ui16NumFlashBlocks;
    // Information on the part number, family, version and
    // package as read from SYSCTL register DID1.
    uint32_t ui32PartInfo;
    // Information on the part class and revision as read
    // from SYSCTL DIDO.
    uint32_t ui32ClassInfo;
    // Address 1 byte above the highest location the boot
    // loader can access.
    //
    uint32_t ui32FlashTop;
    \ensuremath{//} Lowest address the boot loader can write or erase.
    uint32_t ui32AppStartAddr;
PACKED tDFUDeviceInfo;
```

DFU\_CMD\_BIN

By default, data returned in response to a DFU\_UPLOAD request includes an 8-byte DFU\_CMD\_PROG prefix structure. This ensures that an uploaded image can be directly downloaded again without the need to further wrap it but, in cases where pure binary data is required, can be awkward. The DFU\_CMD\_BIN command allows the upload prefix to be disabled or enabled under host control.

The format of the command is as follows:

```
uint8_t pui8Data[8];
pui8Data[0] = DFU_CMD_BIN (0x06)
pui8Data[1] = 0x01 to disable upload prefix, 0x00 to enable
pui8Data[2] = Reserved - set to 0x00
pui8Data[3] = Reserved - set to 0x00
pui8Data[4] = Reserved - set to 0x00
pui8Data[5] = Reserved - set to 0x00
pui8Data[6] = Reserved - set to 0x00
pui8Data[7] = Reserved - set to 0x00
pui8Data[7] = Reserved - set to 0x00
```

DFU\_CMD\_RESET

This command may be sent to the USB boot loader to cause it to perform a soft reset of the board. This reboots the system and, assuming that the main application image is present, runs the main application. Note that a reboot also takes place if a firmware download operation completes and the host issues a USB reset to the DFU device.

The format of the command is as follows:

```
uint8_t pui8Data[8];
pui8Data[0] = DFU_CMD_RESET (0x07)
pui8Data[1] = Reserved - set to 0x00
pui8Data[2] = Reserved - set to 0x00
pui8Data[3] = Reserved - set to 0x00
pui8Data[4] = Reserved - set to 0x00
pui8Data[5] = Reserved - set to 0x00
pui8Data[6] = Reserved - set to 0x00
pui8Data[7] = Reserved - set to 0x00
```

# 2.3.5 Customizing the USB Device Firmware Upgrade

The USB boot loader provides a method to pass a set of custom values to the boot loader when called from a running application. When the USB boot loader is entered because the flash was empty, the boot ROM offers no customization and provides generic "Texas Instruments" and "Device Firmware Update" strings to the host as identifiers. The USB boot loader is called by an application via a call to ROM\_UpdateUSB(), which takes a single pointer as an argument that is a pointer to an array containing the values that the boot loader uses for customization. This pointer can also be 0 to indicate that the application wishes to use the defaults provided by the ROM boot loader. The application can place the customization structure anywhere in flash or SRAM.

The actual values that can be customized are the following:

- Vendor ID (default 0x1CBE)
- Product ID (default 0x00FF)
- Bus/Self Power (default Self Powered)
- Max Power (default 0)
- Device Version (default 0x110)
- All strings in multiple languages

The defaults for the strings are a Manufacturer set to "Texas Instruments", Product set to "Device Firmware Update", and serial number set to "1.0".

If the application is providing a structure to the boot loader with custom values, then the first 12 bytes must contain valid data. The values in the structure that is passed to the boot loader have the following meaning and are merged directly to the device and configuration descriptor for the boot loader:

Byte	Value
0	VID bits 7:0
1	VID bits 15:8
2	PID bits 7:9
3	PID bits 15:8
4	Device Version(BCD) bits 7:9
5	Device Version(BCD) bits 15:8
6	Power in 2mA Increments(250 maximum)
7	USB Configuration Descriptor bmAttributes (Self powered 0xC0,
	Bus powered 0x80).
8-11	Pointer to the string table

The values for the custom strings are contained in a pointer at the end of the structure passed to the boot loader. If the application wants to use the default strings, this pointer should be set to 0. The string table provided supports custom strings for Manufacturer, Product, and Serial Number in multiple languages. The string table is optimized to not require that a string be provided for every language in case there is not a unique string for every language. This is most likely the case for the Serial Number string but it could be any string that is provided.

The string table has a header that describes the number of languages provided and the language identifiers for each followed by a set of strings for each language. Each entry in the table has a size header that specifies the size of the string in bytes plus a byte for the size itself and a one byte tag of USB\_DTYPE\_STRING(0x03). This size and ID padding is included for ease of string handling in the boot loader and is required. It is very important for the application to provide the correct size values because the boot loader uses these to skip through the array and find the requested strings requested by the USB host. If these sizes are incorrect, the boot loader may fail to enumerate, so care should be taken when building the string table. The application must provide all three strings in the first language because these strings are treated as the default if a string is left blank in other languages. In other languages, a string can be left blank for strings that do not change per language. A blank entry in the table consists of a two byte entry with a byte size value of 2 followed by the USB DTYPE STRING value.

The string table has the following format:

Byte	Description
0	Size of the header(Number of Languages * 2) + 2
1	USB_DTYPE_STRING
2	Language ID 0 bits[7:0]
3	Language ID 0 bits[15:8]
	Language ID n bits[7:0]
	Language ID n bits[15:8]
	Language 0 Manufacturer string size in bytes + 2
	USB_DTYPE_STRING
	Language 0 Manufacturer Unicode String
	Language 0 Product string size in bytes + 2
	USB_DTYPE_STRING
	Language 0 Product Unicode String
	Language 0 Serial Number size in bytes + 2
	USB_DTYPE_STRING
	Language 0 Serial Number Unicode String
	:
	Language n Manufacturer string size in bytes + 2
	USB_DTYPE_STRING
	Language n Manufacturer Unicode String
	Language n Product string size in bytes + 2
	USB_DTYPE_STRING
	Language n Product Unicode String
	Language n Serial Number size in bytes + 2
	USB_DTYPE_STRING
	Language n Serial Number Unicode String

The next three examples show an example customization structure for a no string case, a single language case and a multiple language case.

Example: No strings but custom descriptor.

Example: Single US English string set.

```
uint8_t pui8Strings[] =
    (1 * 2) + 2, // One Language (1 * 2) + 2
   USB_DTYPE_STRING,
   0x09, 0x04, // Language code for US English.
    (17 * 2) + 2, // Size of Manufacturer String.
                  // "Texas Instruments"
   USB DTYPE STRING,
   'T', 0, 'e', 0, 'x', 0, 'a', 0, 's', 0, '', 0, 'I', 0, 'n', 0,
    's', 0, 't', 0, 'r', 0, 'u', 0, 'm', 0, 'e', 0, 'n', 0, 't', 0,
   's', 0,
    (23 * 2) + 2, // Size of Product String.
   USB_DTYPE_STRING,
                  // "Device Firmware Upgrade"
   'D', 0, 'e', 0, 'v', 0, 'i', 0, 'c', 0, 'e', 0, '', 0, 'F', 0,
    'i', 0, 'r', 0, 'm', 0, 'w', 0, 'a', 0, 'r', 0, 'e', 0, ' ', 0,
   'U', 0, 'p', 0, 'g', 0, 'r', 0, 'a', 0, 'd', 0, 'e', 0,
    (3 * 2) + 2,
                 // Size of Serial Number.
   USB_DTYPE_STRING,
                  // "1.0"
   '1', 0, '.', 0, '0', 0
};
uint8_t pui8USBBootROMInfo[] =
{
                  // TI VID
   0xbe, 0x1c,
                  // Tiva DFU PID
   0xff, 0x00,
                 // USB version 2.0
   0x00, 0x02,
                  // OmA of Bus power
    0x00,
   0xC0,
                  // Self powered using no bus power
   pui8Strings // Address of the string table
}
// Call to ROM USB boot loader.
//
ROM_UpdateUSB(pui8USBBootROMInfo);
```

Example: Two Languages with English(United States) and Spanish(Mexico) strings.

```
// "My Company"
   USB DTYPE STRING,
   'M', 0, 'y', 0, ' ', 0, 'C', 0, 'o', 0, 'm', 0, 'p', 0, 'a', 0,
   'n', 0, 'y', 0
    (23 * 2) + 2, // Size of Product String.
   USB DTYPE STRING,
                   // "Device Firmware Upgrade"
   'D', 0, 'e', 0, 'v', 0, 'i', 0, 'c', 0, 'e', 0, ' ', 0, 'F', 0,
    'i', 0, 'r', 0, 'm', 0, 'w', 0, 'a', 0, 'r', 0, 'e', 0, ' ', 0,
    'U', 0, 'p', 0, 'q', 0, 'r', 0, 'a', 0, 'd', 0, 'e', 0,
    (4 * 2) + 2, // Size of Serial Number.
   USB_DTYPE_STRING,
                  // "1.01"
   '1', 0, '.', 0, '0', 0, '1', 0
    (10 * 2) + 2, // Size of Manufacturer String.
   USB_DTYPE_STRING,
                  // "My Company"
   'M', 0, 'y', 0, ' ', 0, 'C', 0, 'o', 0, 'm', 0, 'p', 0, 'a', 0,
    'n', 0, 'y', 0
   's', 0,
    (25 * 2) + 2, // Size of Product String.
   USB_DTYPE_STRING,
                   // "Actualizacion de Firmware"
   'A', 0, 'c', 0, 't', 0, 'u', 0, 'a', 0, 'l', 0, 'i', 0, 'z', 0,
   'a', 0, 'c', 0, 'i', 0, 'o', 0, 'n', 0, ' ', 0, 'd', 0, 'e', 0,
    '', 0, 'F', 0, 'i', 0, 'r', 0, 'm', 0, 'w', 0, 'a', 0, 'r', 0,
   'e', 0,
    2,
                   // Size of Serial Number, this will use the last
                   // serial number found since this represents a null
                   // string.
   USB_DTYPE_STRING,
};
uint8 t pui8USBBootROMInfo[] =
                 // TI VID
   0xbe, 0x1c,
   0xff, 0x00,
                  // Tiva DFU PID
    250,
                  // 500mA of Bus power
   0x80,
                  // Bus Powered
   0x00, 0x02,
                  // USB version 2.0
   pui8Strings // Address of the string table
} ;
//
// Call to ROM USB boot loader.
//
ROM UpdateUSB(pui8USBBootROMInfo);
```

# 3 AES Data Tables

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# 3.1 Introduction

The Advanced Encryption Standard (AES) is a publicly defined encryption standard used by the U.S. Government. It is a strong encryption method with reasonable performance and size. AES is fast in both hardware and software, is fairly easy to implement, and requires little memory. AES is ideal for applications that can use pre-arranged keys, such as setup during manufacturing or configuration.

Four data tables used by the XySSL AES implementation are provided in the ROM. The first is the forward S-box substitution table, the second is the reverse S-box substitution table, the third is the forward polynomial table, and the final is the reverse polynomial table. The meanings of these tables and their use can be found in the AES code provided in TivaWare.

# 3.2 Data Structures

### **Data Structures**

■ ROM pvAESTable

## 3.2.1 Data Structure Documentation

### 3.2.1.1 ROM pvAESTable

This structure describes the AES tables that are available in the ROM.

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_SOFTWARETABLE is an array of pointers located at ROM_APITABLE[21].
ROM_pvAESTable is an array located at &ROM_SOFTWARETABLE[7].
```

#### **Definition:**

```
typedef struct
{
    unsigned char ucForwardSBox[256];
    unsigned long ulForwardTable[256];
    unsigned char ucReverseSBox[256];
    unsigned long ulReverseTable[256];
}
ROM_pvAESTable
```

### Members:

ucForwardSBox This table contains the forward S-Box, as defined by the AES standard.

- **ulForwardTable** This table contains the forward polynomial table, as used by the XySSL AES implementation.
- *ucReverseSBox* This table contains the reverse S-Box, as defined by the AES standard. This is simply the reverse of *ucForwardSBox*.
- *ulReverseTable* This table contains the reverse polynomial table, as used by the XySSL AES implementation.

# 4 Analog Comparator

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# 4.1 Introduction

The comparator API provides a set of functions for dealing with the analog comparators. A comparator can compare a test voltage against individual external reference voltage, a shared single external reference voltage, or a shared internal reference voltage. It can provide its output to a device pin, acting as a replacement for an analog comparator on the board, or it can be used to signal the application via interrupts or triggers to the ADC to cause it to start capturing a sample sequence. The interrupt generation and ADC triggering logic is separate, so that an interrupt can be generated on a rising edge and the ADC triggered on a falling edge (for example).

# 4.2 Functions

## **Functions**

- void ROM\_ComparatorConfigure (uint32\_t ui32Base, uint32\_t ui32Comp, uint32\_t ui32Config)
- void ROM ComparatorIntClear (uint32 t ui32Base, uint32 t ui32Comp)
- void ROM ComparatorIntDisable (uint32 t ui32Base, uint32 t ui32Comp)
- void ROM ComparatorIntEnable (uint32 t ui32Base, uint32 t ui32Comp)
- bool ROM ComparatorIntStatus (uint32 t ui32Base, uint32 t ui32Comp, bool bMasked)
- void ROM ComparatorRefSet (uint32 t ui32Base, uint32 t ui32Ref)
- bool ROM\_ComparatorValueGet (uint32\_t ui32Base, uint32\_t ui32Comp)

# 4.2.1 Function Documentation

### 4.2.1.1 ROM ComparatorConfigure

Configures a comparator.

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_COMPARATORTABLE is an array of pointers located at ROM_APITABLE[6].

ROM_ComparatorConfigure is a function pointer located at ROM_COMPARATORTABLE[1].
```

#### Parameters:

ui32Base is the base address of the comparator module.ui32Comp is the index of the comparator to configure.ui32Config is the configuration of the comparator.

#### **Description:**

This function configures a comparator. The *ui32Config* parameter is the result of a logical OR operation between the **COMP\_TRIG\_xxx**, **COMP\_INT\_xxx**, **COMP\_ASRCP\_xxx**, and **COMP\_OUTPUT\_xxx** values.

The **COMP\_TRIG\_xxx** term can take on the following values:

- COMP\_TRIG\_NONE to have no trigger to the ADC.
- COMP TRIG HIGH to trigger the ADC when the comparator output is high.
- **COMP\_TRIG\_LOW** to trigger the ADC when the comparator output is low.
- **COMP\_TRIG\_FALL** to trigger the ADC when the comparator output goes low.
- **COMP\_TRIG\_RISE** to trigger the ADC when the comparator output goes high.
- **COMP\_TRIG\_BOTH** to trigger the ADC when the comparator output goes low or high.

The **COMP INT xxx** term can take on the following values:

- **COMP\_INT\_HIGH** to generate an interrupt when the comparator output is high.
- COMP INT LOW to generate an interrupt when the comparator output is low.
- COMP\_INT\_FALL to generate an interrupt when the comparator output goes low.
- COMP INT RISE to generate an interrupt when the comparator output goes high.
- COMP INT BOTH to generate an interrupt when the comparator output goes low or high.

The COMP ASRCP xxx term can take on the following values:

- COMP ASRCP PIN to use the dedicated Comp+ pin as the reference voltage.
- COMP\_ASRCP\_PIN0 to use the Comp0+ pin as the reference voltage (this the same as COMP\_ASRCP\_PIN for the comparator 0).
- COMP ASRCP REF to use the internally generated voltage as the reference voltage.

The **COMP\_OUTPUT\_xxx** term can take on the following values:

- COMP\_OUTPUT\_NORMAL to enable a non-inverted output from the comparator to a device pin.
- COMP\_OUTPUT\_INVERT to enable an inverted output from the comparator to a device pin.

## Returns:

None.

### 4.2.1.2 ROM ComparatorIntClear

Clears a comparator interrupt.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_COMPARATORTABLE is an array of pointers located at ROM_APITABLE[6].

ROM_ComparatorIntClear is a function pointer located at ROM_COMPARATORTABLE[0].
```

#### Parameters:

ui32Base is the base address of the comparator module.ui32Comp is the index of the comparator.

#### **Description:**

The comparator interrupt is cleared, so that it no longer asserts. This function must be called in the interrupt handler to keep the handler from being called again immediately upon exit. Note that for a level-triggered interrupt, the interrupt cannot be cleared until it stops asserting.

#### Note:

Because there is a write buffer in the Cortex-M4 processor, it may take several clock cycles before the interrupt source is actually cleared. Therefore, it is recommended that the interrupt source be cleared early in the interrupt handler (as opposed to the very last action) to avoid returning from the interrupt handler before the interrupt source is actually cleared. Failure to do so may result in the interrupt handler being immediately reentered (because the interrupt controller still sees the interrupt source asserted).

#### Returns:

None.

# 4.2.1.3 ROM ComparatorIntDisable

Disables the comparator interrupt.

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_COMPARATORTABLE is an array of pointers located at ROM_APITABLE[6].

ROM_ComparatorIntDisable is a function pointer located at ROM_COMPARATORTABLE[5].
```

#### Parameters:

ui32Base is the base address of the comparator module.ui32Comp is the index of the comparator.

#### **Description:**

This function disables generation of an interrupt from the specified comparator. Only comparators whose interrupts are enabled can be reflected to the processor.

#### Returns:

None.

### 4.2.1.4 ROM ComparatorIntEnable

Enables the comparator interrupt.

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_COMPARATORTABLE is an array of pointers located at ROM_APITABLE[6].
ROM_ComparatorIntEnable is a function pointer located at ROM_COMPARATORTABLE[4].
```

#### Parameters:

ui32Base is the base address of the comparator module.ui32Comp is the index of the comparator.

#### **Description:**

This function enables generation of an interrupt from the specified comparator. Only comparators whose interrupts are enabled can be reflected to the processor.

#### Returns:

None.

# 4.2.1.5 ROM\_ComparatorIntStatus

Gets the current interrupt status.

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_COMPARATORTABLE is an array of pointers located at ROM_APITABLE[6].

ROM_ComparatorIntStatus is a function pointer located at ROM_COMPARATORTABLE[6].
```

#### Parameters:

ui32Base is the base address of the comparator module.

ui32Comp is the index of the comparator.

**bMasked** is **false** if the raw interrupt status is required and **true** if the masked interrupt status is required.

#### **Description:**

This returns the interrupt status for the comparator. Either the raw or the masked interrupt status can be returned.

#### Returns:

true if the interrupt is asserted and false if it is not asserted.

### 4.2.1.6 ROM ComparatorRefSet

Sets the internal reference voltage.

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_COMPARATORTABLE is an array of pointers located at ROM_APITABLE[6].

ROM_ComparatorRefSet is a function pointer located at ROM_COMPARATORTABLE[2].
```

#### Parameters:

ui32Base is the base address of the comparator module.ui32Ref is the desired reference voltage.

#### **Description:**

This function sets the internal reference voltage value. The voltage is specified as one of the following values:

- COMP REF OFF to turn off the reference voltage
- COMP REF 0V to set the reference voltage to 0 V
- COMP REF 0 1375V to set the reference voltage to 0.1375 V
- COMP\_REF\_0\_275V to set the reference voltage to 0.275 V
- COMP REF 0 4125V to set the reference voltage to 0.4125 V
- COMP\_REF\_0\_55V to set the reference voltage to 0.55 V
- COMP REF 0 6875V to set the reference voltage to 0.6875 V
- COMP REF 0 825V to set the reference voltage to 0.825 V
- COMP REF 0 928125V to set the reference voltage to 0.928125 V
- COMP REF 0 9625V to set the reference voltage to 0.9625 V
- COMP REF 1 03125V to set the reference voltage to 1.03125 V
- COMP\_REF\_1\_134375V to set the reference voltage to 1.134375 V
- COMP REF 1 1V to set the reference voltage to 1.1 V
- COMP\_REF\_1\_2375V to set the reference voltage to 1.2375 V
- COMP\_REF\_1\_340625V to set the reference voltage to 1.340625 V
- COMP\_REF\_1\_375V to set the reference voltage to 1.375 V
- COMP\_REF\_1\_44375V to set the reference voltage to 1.44375 V
- COMP\_REF\_1\_5125V to set the reference voltage to 1.5125 V
- COMP REF 1 546875V to set the reference voltage to 1.546875 V
- COMP\_REF\_1\_65V to set the reference voltage to 1.65 V
- COMP\_REF\_1\_753125V to set the reference voltage to 1.753125 V
- COMP REF 1 7875V to set the reference voltage to 1.7875 V
- COMP REF 1 85625V to set the reference voltage to 1.85625 V
- COMP REF 1 925V to set the reference voltage to 1.925 V
- COMP REF 1 959375V to set the reference voltage to 1.959375 V
- COMP REF 2 0625V to set the reference voltage to 2.0625 V
- COMP REF 2 165625V to set the reference voltage to 2.165625 V

- COMP REF 2 26875V to set the reference voltage to 2.26875 V
- COMP\_REF\_2\_371875V to set the reference voltage to 2.371875 V

#### Returns:

None.

### 4.2.1.7 ROM ComparatorValueGet

Gets the current comparator output value.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_COMPARATORTABLE is an array of pointers located at ROM_APITABLE[6].

ROM_ComparatorValueGet is a function pointer located at ROM_COMPARATORTABLE[3].
```

#### Parameters:

ui32Base is the base address of the comparator module.ui32Comp is the index of the comparator.

## **Description:**

This function retrieves the current value of the comparator output.

#### Returns:

Returns true if the comparator output is high and false if the comparator output is low.

# 5 Analog to Digital Converter (ADC)

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# 5.1 Introduction

The analog to digital converter (ADC) API provides a set of functions for dealing with the ADC. Functions are provided to configure the sample sequencers, read the captured data, register a sample sequence interrupt handler, and handle interrupt masking/clearing.

The ADC supports up to twenty-four input channels plus an internal temperature sensor. Four sampling sequences, each with configurable trigger events, can be captured. The first sequence will capture up to eight samples, the second and third sequences will capture up to four samples, and the fourth sequence will capture a single sample. Each sample can be the same channel, different channels, or any combination in any order.

The sample sequences have configurable priorities that determine the order in which they are captured when multiple triggers occur simultaneously. The highest priority sequence that is currently triggered will be sampled. Care must be taken with triggers that occur frequently (such as the "always" trigger); if their priority is too high it is possible to starve the lower priority sequences.

Hardware oversampling of the ADC data is available for improved accuracy. An oversampling factor of 2x, 4x, 8x, 16x, 32x, and 64x is supported, but reduces the throughput of the ADC by a corresponding factor. Hardware oversampling is applied uniformly across all sample sequences.

# 5.2 Functions

### **Functions**

- void ROM\_ADCComparatorConfigure (uint32\_t ui32Base, uint32\_t ui32Comp, uint32\_t ui32Config)
- void ROM ADCComparatorIntClear (uint32 t ui32Base, uint32 t ui32Status)
- void ROM ADCComparatorIntDisable (uint32 t ui32Base, uint32 t ui32SequenceNum)
- void ROM\_ADCComparatorIntEnable (uint32\_t ui32Base, uint32\_t ui32SequenceNum)
- uint32 t ROM ADCComparatorIntStatus (uint32 t ui32Base)
- void ROM\_ADCComparatorRegionSet (uint32\_t ui32Base, uint32\_t ui32Comp, uint32\_t ui32LowRef, uint32\_t ui32HighRef)
- void ROM\_ADCComparatorReset (uint32\_t ui32Base, uint32\_t ui32Comp, bool bTrigger, bool bInterrupt)
- void ROM ADCHardwareOversampleConfigure (uint32 t ui32Base, uint32 t ui32Factor)
- void ROM\_ADCIntClear (uint32\_t ui32Base, uint32\_t ui32SequenceNum)
- void ROM ADCIntDisable (uint32 t ui32Base, uint32 t ui32SequenceNum)
- void ROM\_ADCIntEnable (uint32\_t ui32Base, uint32\_t ui32SequenceNum)
- uint32 t ROM ADCIntStatus (uint32 t ui32Base, uint32 t ui32SequenceNum, bool bMasked)
- uint32\_t ROM\_ADCPhaseDelayGet (uint32\_t ui32Base)

- void ROM ADCPhaseDelaySet (uint32 t ui32Base, uint32 t ui32Phase)
- void ROM\_ADCProcessorTrigger (uint32\_t ui32Base, uint32\_t ui32SequenceNum)
- uint32 t ROM ADCReferenceGet (uint32 t ui32Base)
- void ROM ADCReferenceSet (uint32 t ui32Base, uint32 t ui32Ref)
- void ROM\_ADCSequenceConfigure (uint32\_t ui32Base, uint32\_t ui32SequenceNum, uint32\_t ui32Trigger, uint32\_t ui32Priority)
- int32\_t ROM\_ADCSequenceDataGet (uint32\_t ui32Base, uint32\_t ui32SequenceNum, uint32\_t \*pui32Buffer)
- void ROM ADCSequenceDisable (uint32 t ui32Base, uint32 t ui32SequenceNum)
- void ROM\_ADCSequenceEnable (uint32\_t ui32Base, uint32\_t ui32SequenceNum)
- int32 t ROM ADCSequenceOverflow (uint32 t ui32Base, uint32 t ui32SequenceNum)
- void ROM\_ADCSequenceOverflowClear (uint32\_t ui32Base, uint32\_t ui32SequenceNum)
- void ROM\_ADCSequenceStepConfigure (uint32\_t ui32Base, uint32\_t ui32SequenceNum, uint32\_t ui32Step, uint32\_t ui32Config)
- int32\_t ROM\_ADCSequenceUnderflow (uint32\_t ui32Base, uint32\_t ui32SequenceNum)
- void ROM\_ADCSequenceUnderflowClear (uint32\_t ui32Base, uint32\_t ui32SequenceNum)

### 5.2.1 Function Documentation

### 5.2.1.1 ROM ADCComparatorConfigure

Configures an ADC digital comparator.

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCComparatorConfigure is a function pointer located at ROM_ADCTABLE[15].
```

#### Parameters:

```
ui32Base is the base address of the ADC module.ui32Comp is the index of the comparator to configure.ui32Config is the configuration of the comparator.
```

#### Description:

This function will configure a comparator. The *ui32Config* parameter is the result of a logical OR operation between the **ADC\_COMP\_TRIG\_xxx**, and **ADC\_COMP\_INT\_xxx** values.

The **ADC COMP TRIG xxx** term can take on the following values:

- ADC COMP TRIG NONE to never trigger PWM fault condition.
- ADC\_COMP\_TRIG\_LOW\_ALWAYS to always trigger PWM fault condition when ADC output is in the low-band.
- ADC\_COMP\_TRIG\_LOW\_ONCE to trigger PWM fault condition once when ADC output transitions into the low-band.

- ADC\_COMP\_TRIG\_LOW\_HALWAYS to always trigger PWM fault condition when ADC output is in the low-band only if ADC output has been in the high-band since the last trigger output.
- ADC\_COMP\_TRIG\_LOW\_HONCE to trigger PWM fault condition once when ADC output transitions into low-band only if ADC output has been in the high-band since the last trigger output.
- ADC\_COMP\_TRIG\_MID\_ALWAYS to always trigger PWM fault condition when ADC output is in the mid-band.
- ADC\_COMP\_TRIG\_MID\_ONCE to trigger PWM fault condition once when ADC output transitions into the mid-band.
- ADC\_COMP\_TRIG\_HIGH\_ALWAYS to always trigger PWM fault condition when ADC output is in the high-band.
- ADC\_COMP\_TRIG\_HIGH\_ONCE to trigger PWM fault condition once when ADC output transitions into the high-band.
- ADC\_COMP\_TRIG\_HIGH\_HALWAYS to always trigger PWM fault condition when ADC output is in the high-band only if ADC output has been in the low-band since the last trigger output.
- ADC\_COMP\_TRIG\_HIGH\_HONCE to trigger PWM fault condition once when ADC output transitions into high-band only if ADC output has been in the low-band since the last trigger output.

The ADC COMP INT xxx term can take on the following values:

- ADC COMP INT NONE to never generate ADC interrupt.
- ADC\_COMP\_INT\_LOW\_ALWAYS to always generate ADC interrupt when ADC output is in the low-band.
- ADC\_COMP\_INT\_LOW\_ONCE to generate ADC interrupt once when ADC output transitions into the low-band.
- ADC\_COMP\_\_INT\_LOW\_HALWAYS to always generate ADC interrupt when ADC output is in the low-band only if ADC output has been in the high-band since the last trigger output.
- ADC\_COMP\_INT\_LOW\_HONCE to generate ADC interrupt once when ADC output transitions into low-band only if ADC output has been in the high-band since the last trigger output.
- ADC\_COMP\_INT\_MID\_ALWAYS to always generate ADC interrupt when ADC output is in the mid-band.
- ADC\_COMP\_INT\_MID\_ONCE to generate ADC interrupt once when ADC output transitions into the mid-band.
- ADC\_COMP\_INT\_HIGH\_ALWAYS to always generate ADC interrupt when ADC output is in the high-band.
- ADC\_COMP\_INT\_HIGH\_ONCE to generate ADC interrupt once when ADC output transitions into the high-band.
- ADC\_COMP\_INT\_HIGH\_HALWAYS to always generate ADC interrupt when ADC output is in the high-band only if ADC output has been in the low-band since the last trigger output.
- ADC\_COMP\_INT\_HIGH\_HONCE to generate ADC interrupt once when ADC output transitions into high-band only if ADC output has been in the low-band since the last trigger output.

#### Returns:

None.

# 5.2.1.2 ROM ADCComparatorIntClear

Clears sample sequence comparator interrupt source.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCComparatorIntClear is a function pointer located at ROM_ADCTABLE[21].
```

# Parameters:

ui32Base is the base address of the ADC module.ui32Status is the bit-mapped interrupts status to clear.

# **Description:**

The specified interrupt status is cleared.

### Returns:

None.

# 5.2.1.3 ROM\_ADCComparatorIntDisable

Disables a sample sequence comparator interrupt.

# Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCComparatorIntDisable is a function pointer located at ROM_ADCTABLE[18].
```

### Parameters:

```
ui32Base is the base address of the ADC module.ui32SequenceNum is the sample sequence number.
```

### **Description:**

This function disables the requested sample sequence comparator interrupt.

# Returns:

None.

# 5.2.1.4 ROM ADCComparatorIntEnable

Enables a sample sequence comparator interrupt.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCComparatorIntEnable is a function pointer located at ROM_ADCTABLE[19].
```

### Parameters:

ui32Base is the base address of the ADC module.ui32SequenceNum is the sample sequence number.

### **Description:**

This function enables the requested sample sequence comparator interrupt.

### Returns:

None.

# 5.2.1.5 ROM ADCComparatorIntStatus

Gets the current comparator interrupt status.

## Prototype:

```
uint32_t
ROM_ADCComparatorIntStatus(uint32_t ui32Base)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCComparatorIntStatus is a function pointer located at ROM_ADCTABLE[20].
```

#### Parameters:

ui32Base is the base address of the ADC module.

### **Description:**

This returns the digitial comparator interrupt status bits. This status is sequence agnostic.

## Returns:

The current comparator interrupt status.

# 5.2.1.6 ROM ADCComparatorRegionSet

Defines the ADC digital comparator regions.

# Prototype:

```
void
```

```
ROM_ADCComparatorRegionSet(uint32_t ui32Base, uint32_t ui32Comp, uint32_t ui32LowRef, uint32_t ui32HighRef)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCComparatorRegionSet is a function pointer located at ROM_ADCTABLE[16].
```

#### Parameters:

ui32Base is the base address of the ADC module.
ui32Comp is the index of the comparator to configure.
ui32LowRef is the reference point for the low/mid band threshold.
ui32HighRef is the reference point for the mid/high band threshold.

# **Description:**

The ADC digital comparator operation is based on three ADC value regions:

- low-band is defined as any ADC value less than or equal to the *ui32LowRef* value.
- **mid-band** is defined as any ADC value greater than the *ui32LowRef* value but less than or equal to the *ui32HighRef* value.
- high-band is defined as any ADC value greater than the *ui32HighRef* value.

#### Returns:

None.

# 5.2.1.7 ROM\_ADCComparatorReset

Resets the current ADC digital comparator conditions.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCComparatorReset is a function pointer located at ROM_ADCTABLE[17].
```

### Parameters:

ui32Base is the base address of the ADC module.

ui32Comp is the index of the comparator.

bTrigger is the flag to indicate reset of Trigger conditions.

**binterrupt** is the flag to indicate reset of Interrupt conditions.

# **Description:**

Because the digital comparator uses current and previous ADC values, this function is provide to allow the comparator to be reset to its initial value to prevent stale data from being used when a sequence is enabled.

#### Returns:

None.

# 5.2.1.8 ROM ADCHardwareOversampleConfigure

Configures the hardware oversampling factor of the ADC.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCHardwareOversampleConfigure is a function pointer located at ROM_ADCTABLE[14].
```

#### Parameters:

ui32Base is the base address of the ADC module.ui32Factor is the number of samples to be averaged.

## **Description:**

This function configures the hardware oversampling for the ADC, which can be used to provide better resolution on the sampled data. Oversampling is accomplished by averaging multiple samples from the same analog input. Six different oversampling rates are supported; 2x, 4x, 8x, 16x, 32x, and 64x. Specifying an oversampling factor of zero will disable hardware oversampling.

Hardware oversampling applies uniformly to all sample sequencers. It does not reduce the depth of the sample sequencers like the software oversampling APIs; each sample written into the sample sequence FIFO is a fully oversampled analog input reading.

Enabling hardware averaging increases the precision of the ADC at the cost of throughput. For example, enabling 4x oversampling reduces the throughput of a 250 Ksps ADC to 62.5 Ksps.

#### Returns:

None.

# 5.2.1.9 ROM\_ADCIntClear

Clears sample sequence interrupt source.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCIntClear is a function pointer located at ROM_ADCTABLE[4].
```

#### Parameters:

ui32Base is the base address of the ADC module.ui32SequenceNum is the sample sequence number.

### **Description:**

The specified sample sequence interrupt is cleared, so that it no longer asserts. This must be done in the interrupt handler to keep it from being called again immediately upon exit.

### Note:

Because there is a write buffer in the Cortex-M4 processor, it may take several clock cycles before the interrupt source is actually cleared. Therefore, it is recommended that the interrupt source be cleared early in the interrupt handler (as opposed to the very last action) to avoid returning from the interrupt handler before the interrupt source is actually cleared. Failure to do so may result in the interrupt handler being immediately reentered (because the interrupt controller still sees the interrupt source asserted).

#### Returns:

None.

# 5.2.1.10 ROM ADCIntDisable

Disables a sample sequence interrupt.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].
ROM_ADCIntDisable is a function pointer located at ROM_ADCTABLE[1].
```

#### Parameters:

```
ui32Base is the base address of the ADC module.ui32SequenceNum is the sample sequence number.
```

### **Description:**

This function disables the requested sample sequence interrupt.

### Returns:

None.

# 5.2.1.11 ROM ADCIntEnable

Enables a sample sequence interrupt.

# **Prototype:**

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCINtEnable is a function pointer located at ROM_ADCTABLE[2].
```

### Parameters:

ui32Base is the base address of the ADC module.ui32SequenceNum is the sample sequence number.

## **Description:**

This function enables the requested sample sequence interrupt. Any outstanding interrupts are cleared before enabling the sample sequence interrupt.

#### Returns:

None.

# 5.2.1.12 ROM\_ADCIntStatus

Gets the current interrupt status.

# Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].
ROM_ADCIntStatus is a function pointer located at ROM_ADCTABLE[3].
```

### Parameters:

ui32Base is the base address of the ADC module.

*ui32SequenceNum* is the sample sequence number.

**bMasked** is false if the raw interrupt status is required and true if the masked interrupt status is required.

# Description:

This returns the interrupt status for the specified sample sequence. Either the raw interrupt status or the status of interrupts that are allowed to reflect to the processor can be returned.

#### Returns:

The current raw or masked interrupt status.

# 5.2.1.13 ROM ADCPhaseDelayGet

Gets the phase delay between a trigger and the start of a sequence.

### Prototype:

```
uint32_t
ROM_ADCPhaseDelayGet(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCPhaseDelayGet is a function pointer located at ROM_ADCTABLE[25].
```

#### Parameters:

ui32Base is the base address of the ADC module.

### **Description:**

This function gets the current phase delay between the detection of an ADC trigger event and the start of the sample sequence.

### Returns:

```
Returns the phase delay, specified as one of ADC_PHASE_0, ADC_PHASE_22_5, ADC_PHASE_45, ADC_PHASE_67_5, ADC_PHASE_90, ADC_PHASE_112_5, ADC_PHASE_135, ADC_PHASE_157_5, ADC_PHASE_180, ADC_PHASE_202_5, ADC_PHASE_225, ADC_PHASE_247_5, ADC_PHASE_270, ADC_PHASE_292_5, ADC_PHASE_315, or ADC_PHASE_337_5.
```

# 5.2.1.14 ROM\_ADCPhaseDelaySet

Sets the phase delay between a trigger and the start of a sequence.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCPhaseDelaySet is a function pointer located at ROM_ADCTABLE[24].
```

#### Parameters:

ui32Base is the base address of the ADC module.

```
ui32Phase is the phase delay, specified as one of ADC_PHASE_0, ADC_PHASE_22_5, ADC_PHASE_45, ADC_PHASE_67_5, ADC_PHASE_90, ADC_PHASE_112_5, ADC_PHASE_135, ADC_PHASE_157_5, ADC_PHASE_180, ADC_PHASE_202_5, ADC_PHASE_225, ADC_PHASE_247_5, ADC_PHASE_270, ADC_PHASE_292_5, ADC_PHASE_315, or ADC_PHASE_337_5.
```

# Description:

This function sets the phase delay between the detection of an ADC trigger event and the start of the sample sequence. By selecting a different phase delay for a pair of ADC modules (such

as ADC\_PHASE\_0 and ADC\_PHASE\_180) and having each ADC module sample the same analog input, it is possible to increase the sampling rate of the analog input (with samples N, N+2, N+4, and so on, coming from the first ADC and samples N+1, N+3, N+5, and so on, coming from the second ADC). The ADC module has a single phase delay that is applied to all sample sequences within that module.

### Returns:

None.

# 5.2.1.15 ROM ADCProcessorTrigger

Causes a processor trigger for a sample sequence.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCProcessorTrigger is a function pointer located at ROM_ADCTABLE[13].
```

#### Parameters:

ui32Base is the base address of the ADC module.

ui32SequenceNum is the sample sequence number, with ADC\_TRIGGER\_WAIT or ADC\_TRIGGER\_SIGNAL optionally ORed into it.

## **Description:**

This function triggers a processor-initiated sample sequence if the sample sequence trigger is configured to **ADC\_TRIGGER\_PROCESSOR**. If **ADC\_TRIGGER\_WAIT** is ORed into the sequence number, the processor-initiated trigger is delayed until a later processor-initiated trigger to a different ADC module that specifies **ADC\_TRIGGER\_SIGNAL**, allowing multiple ADCs to start from a processor-initiated trigger in a synchronous manner.

#### Returns:

None.

## 5.2.1.16 ROM ADCReferenceGet

Returns the current setting of the ADC reference.

# Prototype:

```
uint32_t
ROM_ADCReferenceGet(uint32_t ui32Base)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCReferenceGet is a function pointer located at ROM_ADCTABLE[23].
```

#### Parameters:

ui32Base is the base address of the ADC module.

### **Description:**

Returns the value of the ADC reference setting. The returned value is one of **ADC\_REF\_INT** or **ADC\_REF\_EXT\_3V**.

#### Returns:

The current setting of the ADC reference.

# 5.2.1.17 ROM ADCReferenceSet

Selects the ADC reference.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCReferenceSet is a function pointer located at ROM_ADCTABLE[22].
```

#### Parameters:

ui32Base is the base address of the ADC module.
ui32Ref is the reference to use.

# **Description:**

The ADC reference is set as specified by *ui32Ref*. It must be one of **ADC\_REF\_INT** or **ADC\_REF\_EXT\_3V**, for internal or external reference. If **ADC\_REF\_INT** is chosen, then an internal 3V reference is used and no external reference is needed. If **ADC\_REF\_EXT\_3V** is chosen, then a 3V reference must be supplied to the AVREF pin.

#### Returns:

None.

# 5.2.1.18 ROM ADCSequenceConfigure

Configures the trigger source and priority of a sample sequence.

## Prototype:

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCSequenceConfigure is a function pointer located at ROM_ADCTABLE[7].
```

### Parameters:

ui32Base is the base address of the ADC module.

ui32SequenceNum is the sample sequence number.

ui32Trigger is the trigger source that initiates the sample sequence; must be one of the ADC TRIGGER \* values.

*ui32Priority* is the relative priority of the sample sequence with respect to the other sample sequences.

### **Description:**

This function configures the initiation criteria for a sample sequence. Valid sample sequences range from zero to three; sequence zero will capture up to eight samples, sequences one and two will capture up to four samples, and sequence three will capture a single sample. The trigger condition and priority (with respect to other sample sequence execution) is set.

The *ui32Trigger* parameter can take on the following values:

- ADC\_TRIGGER\_PROCESSOR A trigger generated by the processor, via the ROM\_ADCProcessorTrigger() function.
- ADC\_TRIGGER\_COMP0 A trigger generated by the first analog comparator; configured with ROM\_ComparatorConfigure().
- ADC\_TRIGGER\_COMP1 A trigger generated by the second analog comparator; configured with ROM\_ComparatorConfigure().
- ADC\_TRIGGER\_COMP2 A trigger generated by the third analog comparator; configured with ROM\_ComparatorConfigure().
- ADC TRIGGER EXTERNAL A trigger generated by an input from the Port B4 pin.
- ADC\_TRIGGER\_TIMER A trigger generated by a timer; configured with ROM\_TimerControlTrigger().
- ADC\_TRIGGER\_PWM0 A trigger generated by the first PWM generator; configured with ROM\_PWMGenIntTrigEnable().
- ADC\_TRIGGER\_PWM1 A trigger generated by the second PWM generator; configured with ROM\_PWMGenIntTrigEnable().
- **ADC\_TRIGGER\_PWM2** A trigger generated by the third PWM generator; configured with ROM\_PWMGenIntTrigEnable().
- ADC\_TRIGGER\_PWM3 A trigger generated by the fourth PWM generator; configured with ROM\_PWMGenIntTrigEnable().
- ADC\_TRIGGER\_ALWAYS A trigger that is always asserted, causing the sample sequence to capture repeatedly (so long as there is not a higher priority source active).

The *ui32Priority* parameter is a value between 0 and 3, where 0 represents the highest priority and 3 the lowest. Note that when programming the priority among a set of sample sequences, each must have unique priority; it is up to the caller to guarantee the uniqueness of the priorities.

### Returns:

None.

# 5.2.1.19 ROM ADCSequenceDataGet

Gets the captured data for a sample sequence.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCSequenceDataGet is a function pointer located at ROM_ADCTABLE[0].
```

#### Parameters:

```
ui32Base is the base address of the ADC module.ui32SequenceNum is the sample sequence number.pui32Buffer is the address where the data is stored.
```

### **Description:**

This function copies data from the specified sample sequence output FIFO to a memory resident buffer. The number of samples available in the hardware FIFO are copied into the buffer, which is assumed to be large enough to hold that many samples. This will only return the samples that are presently available, which may not be the entire sample sequence if it is in the process of being executed.

### Returns:

Returns the number of samples copied to the buffer.

# 5.2.1.20 ROM ADCSequenceDisable

Disables a sample sequence.

# Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCSequenceDisable is a function pointer located at ROM_ADCTABLE[6].
```

### Parameters:

ui32Base is the base address of the ADC module.ui32SequenceNum is the sample sequence number.

# **Description:**

Prevents the specified sample sequence from being captured when its trigger is detected. A sample sequence should be disabled before it is configured.

### Returns:

None.

# 5.2.1.21 ROM ADCSequenceEnable

Enables a sample sequence.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCSequenceEnable is a function pointer located at ROM_ADCTABLE[5].
```

### Parameters:

ui32Base is the base address of the ADC module.ui32SequenceNum is the sample sequence number.

### **Description:**

Allows the specified sample sequence to be captured when its trigger is detected. A sample sequence must be configured before it is enabled.

### Returns:

None.

# 5.2.1.22 ROM ADCSequenceOverflow

Determines if a sample sequence overflow occurred.

## Prototype:

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCSequenceOverflow is a function pointer located at ROM_ADCTABLE[9].
```

#### Parameters:

ui32Base is the base address of the ADC module.ui32SequenceNum is the sample sequence number.

### **Description:**

This determines if a sample sequence overflow has occurred. This will happen if the captured samples are not read from the FIFO before the next trigger occurs.

# Returns:

Returns zero if there was not an overflow, and non-zero if there was.

# 5.2.1.23 ROM ADCSequenceOverflowClear

Clears the overflow condition on a sample sequence.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCSequenceOverflowClear is a function pointer located at ROM_ADCTABLE[10].
```

### Parameters:

ui32Base is the base address of the ADC module.ui32SequenceNum is the sample sequence number.

### **Description:**

This will clear an overflow condition on one of the sample sequences. The overflow condition must be cleared in order to detect a subsequent overflow condition (it otherwise causes no harm).

#### Returns:

None.

# 5.2.1.24 ROM ADCSequenceStepConfigure

Configure a step of the sample sequencer.

### Prototype:

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCSequenceStepConfigure is a function pointer located at ROM_ADCTABLE[8].
```

### Parameters:

```
ui32Base is the base address of the ADC module.ui32SequenceNum is the sample sequence number.ui32Step is the step to be configured.
```

ui32Config is the configuration of this step; must be a logical OR of ADC\_CTL\_TS, ADC\_CTL\_IE, ADC\_CTL\_END, ADC\_CTL\_D, one of the input channel selects (ADC\_CTL\_CH0 through ADC\_CTL\_CH23), and one of the digital comparator selects (ADC\_CTL\_CMP0 through ADC\_CTL\_CMP7).

## **Description:**

This function will set the configuration of the ADC for one step of a sample sequence. The ADC can be configured for single-ended or differential operation (the ADC\_CTL\_D bit selects differential operation when set), the channel to be sampled can be chosen (the ADC\_CTL\_CH0 through ADC\_CTL\_CH23 values), and the internal temperature sensor can be selected (the ADC\_CTL\_TS bit). Additionally, this step can be defined as the last in the sequence (the ADC\_CTL\_END bit) and it can be configured to cause an interrupt when the step is complete (the ADC\_CTL\_IE bit). If the digital comparators are present on the device, this step may also be configured to send the ADC sample to the selected comparator using ADC\_CTL\_CMP0 through ADC\_CTL\_CMP7. The configuration is used by the ADC at the appropriate time when the trigger for this sequence occurs.

#### Note:

If the Digitial Comparator is present and enabled using the ADC\_CTL\_CMP0 through ADC\_CTL\_CMP7 selects, the ADC sample will NOT be written into the ADC sequence data FIFO.

The *ui32Step* parameter determines the order in which the samples are captured by the ADC when the trigger occurs. It can range from zero to seven for the first sample sequence, from zero to three for the second and third sample sequence, and can only be zero for the fourth sample sequence.

Differential mode only works with adjacent channel pairs (for example, 0 and 1). The channel select must be the number of the channel pair to sample (for example, **ADC\_CTL\_CH0** for 0 and 1, or **ADC\_CTL\_CH1** for 2 and 3) or undefined results are returned by the ADC. Additionally, if differential mode is selected when the temperature sensor is being sampled, undefined results are returned by the ADC.

It is the responsibility of the caller to ensure that a valid configuration is specified; this function does not check the validity of the specified configuration.

### Returns:

None.

# 5.2.1.25 ROM ADCSequenceUnderflow

Determines if a sample sequence underflow occurred.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCSequenceUnderflow is a function pointer located at ROM_ADCTABLE[11].
```

#### Parameters:

ui32Base is the base address of the ADC module.ui32SequenceNum is the sample sequence number.

### **Description:**

This determines if a sample sequence underflow has occurred. This will happen if too many samples are read from the FIFO.

### Returns:

Returns zero if there was not an underflow, and non-zero if there was.

# 5.2.1.26 ROM\_ADCSequenceUnderflowClear

Clears the underflow condition on a sample sequence.

# Prototype:

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_ADCTABLE is an array of pointers located at ROM_APITABLE[5].

ROM_ADCSequenceUnderflowClear is a function pointer located at ROM_ADCTABLE[12].
```

#### Parameters:

ui32Base is the base address of the ADC module.ui32SequenceNum is the sample sequence number.

# **Description:**

This will clear an underflow condition on one of the sample sequences. The underflow condition must be cleared in order to detect a subsequent underflow condition (it otherwise causes no harm).

### Returns:

None.

# 6 Controller Area Network (CAN)

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# 6.1 Introduction

The Controller Area Network (CAN) APIs provide a set of functions for accessing the CAN modules. Functions are provided to configure the CAN controllers, configure message objects, and manage CAN interrupts.

The CAN module provides hardware processing of the CAN data link layer. It can be configured with message filters and preloaded message data so that it can autonomously send and receive messages on the bus, and notify the application accordingly. It automatically handles generation and checking of CRCs, error processing, and retransmission of CAN messages.

The message objects are stored in the CAN controller and provide the main interface for the CAN module on the CAN bus. There are 32 message objects that can each be programmed to handle a separate message ID, or can be chained together for a sequence of frames with the same ID. The message identifier filters provide masking that can be programmed to match any or all of the message ID bits, and frame types.

The CAN module is disabled by default, so the the ROM\_CANInit() function must be called before any other CAN functions are called. This call initializes the message objects to a safe state prior to enabling the controller on the CAN bus. Also, the bit timing values must be programmed prior to enabling the CAN controller. The ROM\_CANBitTimingSet() function should be called with the appropriate bit timing values for the CAN bus. Once these two functions have been called, a CAN controller can be enabled using the ROM\_CANEnable(), and later disabled using ROM\_CANDisable() if needed. Calling ROM\_CANDisable() does not reinitialize a CAN controller, so it can be used to temporarily remove a CAN controller from the bus.

The CAN controller is highly configurable and contains 32 message objects that can be programmed to automatically transmit and receive CAN messages under certain conditions. Message objects allow the application to perform some actions automatically without interaction from the microcontroller. Some examples of these actions are the following:

- Send a data frame immediately
- Send a data frame when a matching remote frame is seen on the CAN bus
- Receive a specific data frame
- Receive data frames that match a certain identifier pattern

To configure message objects to perform any of these actions, the application must first set up one of the 32 message objects using ROM\_CANMessageSet(). This function must be used to configure a message object to send data, or to configure a message object to receive data. Each message object can be configured to generate interrupts on transmission or reception of CAN messages.

When data is received from the CAN bus, the application can use the ROM\_CANMessageGet() function to read the received message. This function can also be used to read a message object that is already configured in order to populate a message structure prior to making changes to the

configuration of a message object. Reading the message object using this function will also clear any pending interrupt on the message object.

Once a message object has been configured using ROM\_CANMessageSet(), it has allocated the message object and will continue to perform its programmed function unless it is released with a call to ROM\_CANMessageClear(). The application is not required to clear out a message object before setting it with a new configuration, because each time ROM\_CANMessageSet() is called, it will overwrite any previously programmed configuration.

The 32 message objects are identical except for priority. The lowest numbered message objects have the highest priority. Priority affects operation in two ways. First, if multiple actions are ready at the same time, the one with the highest priority message object will occur first. And second, when multiple message objects have interrupts pending, the highest priority will be presented first when reading the interrupt status. It is up to the application to manage the 32 message objects as a resource, and determine the best method for allocating and releasing them.

The CAN controller can generate interrupts on several conditions:

- When any message object transmits a message
- When any message object receives a message
- On warning conditions such as an error counter reaching a limit or occurrence of various bus errors
- On controller error conditions such as entering the bus-off state

Once CAN interrupts are enabled, the handler will be invoked whenever a CAN interrupt is triggered. The handler can determine which condition caused the interrupt by using the ROM\_CANIntStatus() function. Multiple conditions can be pending when an interrupt occurs, so the handler must be designed to process all pending interrupt conditions before exiting. Each interrupt condition must be cleared before exiting the handler. There are two ways to do this. The ROM\_CANIntClear() function will clear a specific interrupt condition without further action required by the handler. However, the handler can also clear the condition by performing certain actions. If the interrupt is a status interrupt, the interrupt can be cleared by reading the status register with ROM\_CANStatusGet(). If the interrupt is caused by one of the message objects, then it can be cleared by reading the message object using ROM\_CANMessageGet().

There are several status registers that can be used to help the application manage the controller. The status registers are read using the ROM\_CANStatusGet() function. There is a controller status register that provides general status information such as error or warning conditions. There are also several status registers that provide information about all of the message objects at once using a 32-bit bit map of the status, with one bit representing each message object. These status registers can be used to determine:

- Which message objects have unprocessed received data
- Which message objects have pending transmission requests
- Which message objects are allocated for use

# 6.2 Functions

# **Functions**

uint32\_t ROM\_CANBitRateSet (uint32\_t ui32Base, uint32\_t ui32SourceClock, uint32\_t ui32BitRate)

- void ROM CANBitTimingGet (uint32 t ui32Base, tCANBitClkParms \*psClkParms)
- void ROM\_CANBitTimingSet (uint32\_t ui32Base, tCANBitClkParms \*psClkParms)
- void ROM CANDisable (uint32 t ui32Base)
- void ROM\_CANEnable (uint32\_t ui32Base)
- bool ROM\_CANErrCntrGet (uint32\_t ui32Base, uint32\_t \*pui32RxCount, uint32\_t \*pui32TxCount)
- void ROM CANInit (uint32 t ui32Base)
- void ROM CANIntClear (uint32 t ui32Base, uint32 t ui32IntClr)
- void ROM CANIntDisable (uint32 t ui32Base, uint32 t ui32IntFlags)
- void ROM\_CANIntEnable (uint32\_t ui32Base, uint32\_t ui32IntFlags)
- uint32 t ROM CANIntStatus (uint32 t ui32Base, tCANIntStsReg eIntStsReg)
- void ROM\_CANMessageClear (uint32\_t ui32Base, uint32\_t ui32ObjID)
- void ROM\_CANMessageGet (uint32\_t ui32Base, uint32\_t ui32ObjID, tCANMsgObject \*pMsgObject, bool bClrPendingInt)
- void ROM\_CANMessageSet (uint32\_t ui32Base, uint32\_t ui32ObjID, tCANMsgObject \*pMsgObject, tMsgObjType eMsgType)
- bool ROM\_CANRetryGet (uint32\_t ui32Base)
- void ROM CANRetrySet (uint32 t ui32Base, bool bAutoRetry)
- uint32\_t ROM\_CANStatusGet (uint32\_t ui32Base, tCANStsReg eStatusReg)

# 6.2.1 Function Documentation

# 6.2.1.1 ROM CANBitRateSet

This function is used to set the CAN bit timing values to a nominal setting based on a desired bit rate.

# Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010. ROM_CANTABLE is an array of pointers located at ROM_APITABLE[18]. ROM_CANBitRateSet is a function pointer located at ROM_CANTABLE[16].
```

### Parameters:

ui32Base is the base address of the CAN controller.ui32SourceClock is the system clock for the device in Hz.ui32BitRate is the desired bit rate.

### **Description:**

This function will set the CAN bit timing for the bit rate passed in the *ui32BitRate* parameter based on the *ui32SourceClock* parameter. Since the CAN clock is based off of the system clock the calling function should pass in the source clock rate either by retrieving it from ROM\_SysCtlClockGet() or using a specific value in Hz. The CAN bit timing is calculated assuming a minimal amount of propagation delay, which will work for most cases where the

network length is short. If tighter timing requirements or longer network lengths are needed, then the ROM\_CANBitTimingSet() function is available for full customization of all of the CAN bit timing values. Since not all bit rates can be matched exactly, the bit rate is set to the value closest to the desired bit rate without being higher than the *ui32BitRate* value.

### Returns:

This function returns the bit rate that the CAN controller was configured to use or it returns 0 to indicate that the bit rate was not changed because the requested bit rate was not valid.

# 6.2.1.2 ROM\_CANBitTimingGet

Reads the current settings for the CAN controller bit timing.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_CANTABLE is an array of pointers located at ROM_APITABLE[18].

ROM_CANBitTimingGet is a function pointer located at ROM_CANTABLE[5].
```

#### Parameters:

ui32Base is the base address of the CAN controller.psClkParms is a pointer to a structure to hold the timing parameters.

### **Description:**

This function reads the current configuration of the CAN controller bit clock timing, and stores the resulting information in the structure supplied by the caller. Refer to ROM\_CANBitTimingSet() for the meaning of the values that are returned in the structure pointed to by *psClkParms*.

### Returns:

None.

# 6.2.1.3 ROM CANBitTimingSet

Configures the CAN controller bit timing.

# Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_CANTABLE is an array of pointers located at ROM_APITABLE[18].

ROM_CANBITIMINGSet is a function pointer located at ROM_CANTABLE[4].
```

#### Parameters:

ui32Base is the base address of the CAN controller.
psClkParms points to the structure with the clock parameters.

### **Description:**

Configures the various timing parameters for the CAN bus bit timing: Propagation segment, Phase Buffer 1 segment, Phase Buffer 2 segment, and the Synchronization Jump Width. The values for Propagation and Phase Buffer 1 segments are derived from the combination psClkParms->ui32SyncPropPhase1Seg parameter. Phase Buffer 2 is determined from the psClkParms->ui32Phase2Seg parameter. These two parameters, along with psClkParms->ui32SJW are based in units of bit time quanta. The actual quantum time is determined by the psClkParms->ui32QuantumPrescaler value, which specifies the divisor for the CAN module clock.

The total bit time, in quanta, is the sum of the two Seg parameters, as follows:

```
bit_time_q = ui32SyncPropPhase1Seg + ui32Phase2Seg + 1
```

Note that the Sync\_Seg is always one quantum in duration, and is added to derive the correct duration of Prop\_Seg and Phase1\_Seg.

The equation to determine the actual bit rate is as follows:

```
CAN Clock / ((ui32SyncPropPhase1Seg + ui32Phase2Seg + 1) * (ui32QuantumPrescaler))
```

This means that with ui32SyncPropPhase1Seg = 4, ui32Phase2Seg = 1, ui32QuantumPrescaler = 2 and an 8 MHz CAN clock, that the bit rate is (8 MHz) / ((5 + 2 + 1) \* 2) or 500 Kbit/sec.

### Returns:

None.

# 6.2.1.4 ROM CANDisable

Disables the CAN controller.

#### Prototype:

```
void
```

ROM\_CANDisable(uint32\_t ui32Base)

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_CANTABLE is an array of pointers located at ROM_APITABLE[18].

ROM_CANDisable is a function pointer located at ROM_CANTABLE[3].
```

### Parameters:

ui32Base is the base address of the CAN controller to disable.

### Description:

Disables the CAN controller for message processing. When disabled, the controller will no longer automatically process data on the CAN bus. The controller can be restarted by calling ROM\_CANEnable(). The state of the CAN controller and the message objects in the controller are left as they were before this call was made.

#### Returns:

None.

# 6.2.1.5 ROM CANEnable

Enables the CAN controller.

### Prototype:

```
void
ROM_CANEnable(uint32_t ui32Base)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_CANTABLE is an array of pointers located at ROM_APITABLE[18].

ROM_CANEnable is a function pointer located at ROM_CANTABLE[2].
```

#### Parameters:

ui32Base is the base address of the CAN controller to enable.

### **Description:**

Enables the CAN controller for message processing. Once enabled, the controller will automatically transmit any pending frames, and process any received frames. The controller can be stopped by calling ROM\_CANDisable(). Prior to calling ROM\_CANEnable(), ROM\_CANInit() should have been called to initialize the controller and the CAN bus clock should be configured by calling ROM\_CANBitTimingSet().

### Returns:

None.

# 6.2.1.6 ROM CANErrCntrGet

Reads the CAN controller error counter register.

### Prototype:

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_CANTABLE is an array of pointers located at ROM_APITABLE[18].

ROM_CANETRCHTGET is a function pointer located at ROM_CANTABLE[15].
```

#### Parameters:

```
ui32Base is the base address of the CAN controller.pui32RxCount is a pointer to storage for the receive error counter.pui32TxCount is a pointer to storage for the transmit error counter.
```

# Description:

Reads the error counter register and returns the transmit and receive error counts to the caller along with a flag indicating if the controller receive counter has reached the error passive limit. The values of the receive and transmit error counters are returned through the pointers provided as parameters.

After this call, \*pui32RxCount will hold the current receive error count and \*pui32TxCount will hold the current transmit error count.

### Returns:

Returns **true** if the receive error count has reached the error passive limit, and **false** if the error count is below the error passive limit.

# 6.2.1.7 ROM CANInit

Initializes the CAN controller after reset.

### Prototype:

```
void
ROM_CANInit(uint32_t ui32Base)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010. ROM_CANTABLE is an array of pointers located at ROM_APITABLE [18]. ROM_CANInit is a function pointer located at ROM_CANTABLE [1].
```

### Parameters:

ui32Base is the base address of the CAN controller.

## **Description:**

After reset, the CAN controller is left in the disabled state. However, the memory used for message objects contains undefined values and must be cleared prior to enabling the CAN controller the first time. This prevents unwanted transmission or reception of data before the message objects are configured. This function must be called before enabling the controller the first time.

#### Returns:

None.

# 6.2.1.8 ROM CANIntClear

Clears a CAN interrupt source.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_CANTABLE is an array of pointers located at ROM_APITABLE[18].

ROM_CANINtClear is a function pointer located at ROM_CANTABLE[0].
```

## Parameters:

ui32Base is the base address of the CAN controller.ui32IntCIr is a value indicating which interrupt source to clear.

# Description:

This function can be used to clear a specific interrupt source. The *ui32IntClr* parameter should be one of the following values:

- CAN INT INTID STATUS Clears a status interrupt.
- 1-32 Clears the specified message object interrupt

It is not necessary to use this function to clear an interrupt. This should only be used if the application wants to clear an interrupt source without taking the normal interrupt action.

Normally, the status interrupt is cleared by reading the controller status using ROM\_CANStatusGet(). A specific message object interrupt is normally cleared by reading the message object using ROM\_CANMessageGet().

#### Note:

Because there is a write buffer in the Cortex-M4 processor, it may take several clock cycles before the interrupt source is actually cleared. Therefore, it is recommended that the interrupt source be cleared early in the interrupt handler (as opposed to the very last action) to avoid returning from the interrupt handler before the interrupt source is actually cleared. Failure to do so may result in the interrupt handler being immediately reentered (because the interrupt controller still sees the interrupt source asserted).

#### Returns:

None.

# 6.2.1.9 ROM CANIntDisable

Disables individual CAN controller interrupt sources.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_CANTABLE is an array of pointers located at ROM_APITABLE[18].

ROM_CANIntDisable is a function pointer located at ROM_CANTABLE[11].
```

### Parameters:

ui32Base is the base address of the CAN controller.ui32IntFlags is the bit mask of the interrupt sources to be disabled.

### **Description:**

Disables the specified CAN controller interrupt sources. Only enabled interrupt sources can cause a processor interrupt.

The ui32IntFlags parameter has the same definition as in the ROM CANIntEnable() function.

### Returns:

None.

# 6.2.1.10 ROM CANIntEnable

Enables individual CAN controller interrupt sources.

# **Prototype:**

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_CANTABLE is an array of pointers located at ROM_APITABLE[18].

ROM_CANINtEnable is a function pointer located at ROM_CANTABLE[10].
```

#### Parameters:

ui32Base is the base address of the CAN controller.ui32IntFlags is the bit mask of the interrupt sources to be enabled.

# **Description:**

Enables specific interrupt sources of the CAN controller. Only enabled sources will cause a processor interrupt.

The *ui32IntFlags* parameter is the logical OR of any of the following:

- CAN INT ERROR a controller error condition has occurred
- CAN INT STATUS a message transfer has completed, or a bus error has been detected
- CAN INT MASTER allow CAN controller to generate interrupts

In order to generate any interrupts, **CAN\_INT\_MASTER** must be enabled. Further, for any particular transaction from a message object to generate an interrupt, that message object must have interrupts enabled (see ROM\_CANMessageSet()). **CAN\_INT\_ERROR** will generate an interrupt if the controller enters the "bus off" condition, or if the error counters reach a limit. **CAN\_INT\_STATUS** will generate an interrupt under quite a few status conditions and may provide more interrupts than the application needs to handle. When an interrupt occurs, use ROM\_CANIntStatus() to determine the cause.

### Returns:

None.

## 6.2.1.11 ROM CANIntStatus

Returns the current CAN controller interrupt status.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_CANTABLE is an array of pointers located at ROM_APITABLE[18].

ROM_CANIntStatus is a function pointer located at ROM_CANTABLE[12].
```

### Parameters:

ui32Base is the base address of the CAN controller.eIntStsReg indicates which interrupt status register to read

# **Description:**

Returns the value of one of two interrupt status registers. The interrupt status register read is determined by the *eIntStsReg* parameter, which can have one of the following values:

- CAN\_INT\_STS\_CAUSE indicates the cause of the interrupt
- CAN INT STS OBJECT indicates pending interrupts of all message objects

CAN\_INT\_STS\_CAUSE returns the value of the controller interrupt register and indicates the cause of the interrupt. It is a value of CAN\_INT\_INTID\_STATUS if the cause is a status interrupt. In this case, the status register should be read with the ROM\_CANStatusGet() function. Calling this function to read the status will also clear the status interrupt. If the value of the interrupt register is in the range 1-32, then this indicates the number of the highest priority message object that has an interrupt pending. The message object interrupt can be cleared by using the ROM\_CANIntClear() function, or by reading the message using ROM\_CANMessageGet() in the case of a received message. The interrupt handler can read the interrupt status again to make sure all pending interrupts are cleared before returning from the interrupt.

**CAN\_INT\_STS\_OBJECT** returns a bit mask indicating which message objects have pending interrupts. This can be used to discover all of the pending interrupts at once, as opposed to repeatedly reading the interrupt register by using **CAN\_INT\_STS\_CAUSE**.

#### Returns:

Returns the value of one of the interrupt status registers.

# 6.2.1.12 ROM\_CANMessageClear

Clears a message object so that it is no longer used.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_CANTABLE is an array of pointers located at ROM_APITABLE[18].

ROM_CANMessageClear is a function pointer located at ROM_CANTABLE[9].
```

### Parameters:

```
ui32Base is the base address of the CAN controller.ui32ObjID is the message object number to disable (1-32).
```

### **Description:**

This function frees the specified message object from use. Once a message object has been "cleared," it will no longer automatically send or receive messages, or generate interrupts.

### Returns:

None.

## 6.2.1.13 ROM CANMessageGet

Reads a CAN message from one of the message object buffers.

# **Prototype:**

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_CANTABLE is an array of pointers located at ROM_APITABLE[18].

ROM_CANMessageGet is a function pointer located at ROM_CANTABLE[7].
```

#### Parameters:

```
ui32Base is the base address of the CAN controller.
ui32ObjID is the object number to read (1-32).
pMsgObject points to a structure containing message object fields.
bCIrPendingInt indicates whether an associated interrupt should be cleared.
```

# **Description:**

This function is used to read the contents of one of the 32 message objects in the CAN controller, and return it to the caller. The data returned is stored in the fields of the caller-supplied structure pointed to by *pMsgObject*. The data consists of all of the parts of a CAN message, plus some control and status information.

Normally this is used to read a message object that has received and stored a CAN message with a certain identifier. However, this could also be used to read the contents of a message object in order to load the fields of the structure in case only part of the structure needs to be changed from a previous setting.

When using CANMessageGet, all of the same fields of the structure are populated in the same way as when the ROM\_CANMessageSet() function is used, with the following exceptions:

pMsgObject->ui32Flags:

- MSG OBJ NEW DATA indicates if this is new data since the last time it was read
- MSG\_OBJ\_DATA\_LOST indicates that at least one message was received on this message object, and not read by the host before being overwritten.

# Returns:

None.

# 6.2.1.14 ROM CANMessageSet

Configures a message object in the CAN controller.

### Prototype:

#### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_CANTABLE is an array of pointers located at ROM\_APITABLE[18].

ROM\_CANMessageSet is a function pointer located at ROM\_CANTABLE[6].

#### Parameters:

ui32Base is the base address of the CAN controller.
ui32ObjID is the object number to configure (1-32).
pMsgObject is a pointer to a structure containing message object settings.
eMsgType indicates the type of message for this object.

### **Description:**

This function is used to configure any one of the 32 message objects in the CAN controller. A message object can be configured as any type of CAN message object as well as several options for automatic transmission and reception. This call also allows the message object to be configured to generate interrupts on completion of message receipt or transmission. The message object can also be configured with a filter/mask so that actions are only taken when a message that meets certain parameters is seen on the CAN bus.

The *eMsgType* parameter must be one of the following values:

- MSG\_OBJ\_TYPE\_TX CAN transmit message object.
- MSG\_OBJ\_TYPE\_TX\_REMOTE CAN transmit remote request message object.
- MSG\_OBJ\_TYPE\_RX CAN receive message object.
- MSG\_OBJ\_TYPE\_RX\_REMOTE CAN receive remote request message object.
- MSG\_OBJ\_TYPE\_RXTX\_REMOTE CAN remote frame receive remote, then transmit message object.

The message object pointed to by *pMsgObject* must be populated by the caller, as follows:

- *ui32MsgID* contains the message ID, either 11 or 29 bits.
- *ui32MsgIDMask* mask of bits from *ui32MsgID* that must match if identifier filtering is enabled.
- ui32Flags
  - Set MSG OBJ TX INT ENABLE flag to enable interrupt on transmission.
  - Set MSG\_OBJ\_RX\_INT\_ENABLE flag to enable interrupt on receipt.
  - Set MSG\_OBJ\_USE\_ID\_FILTER flag to enable filtering based on the identifier mask specified by ui32MsgIDMask.
- *ui32MsgLen* the number of bytes in the message data. This should be non-zero even for a remote frame; it should match the expected bytes of the data responding data frame.
- pucMsqData points to a buffer containing up to 8 bytes of data for a data frame.

**Example:** To send a data frame or remote frame(in response to a remote request), take the following steps:

- 1. Set *eMsgType* to **MSG\_OBJ\_TYPE\_TX**.
- 2. Set *pMsgObject->ui32MsgID* to the message ID.
- 3. Set *pMsgObject->ui32Flags*. Make sure to set **MSG\_OBJ\_TX\_INT\_ENABLE** to allow an interrupt to be generated when the message is sent.
- 4. Set *pMsgObject->ui32MsgLen* to the number of bytes in the data frame.
- 5. Set *pMsgObject->pucMsgData* to point to an array containing the bytes to send in the message.

6. Call this function with *ui32ObjID* set to one of the 32 object buffers.

**Example:** To receive a specific data frame, take the following steps:

- 1. Set eMsgObjType to MSG OBJ TYPE RX.
- 2. Set *pMsgObject->ui32MsgID* to the full message ID, or a partial mask to use partial ID matching.
- Set pMsgObject->ui32MsgIDMask bits that should be used for masking during comparison.
- 4. Set *pMsgObject->ui32Flags* as follows:
  - Set MSG\_OBJ\_RX\_INT\_ENABLE flag to be interrupted when the data frame is received.
  - Set MSG OBJ USE ID FILTER flag to enable identifier based filtering.
- 5. Set *pMsgObject->ui32MsgLen* to the number of bytes in the expected data frame.
- 6. The buffer pointed to by *pMsgObject->pucMsgData* is not used by this call as no data is present at the time of the call.
- 7. Call this function with *ui32ObjID* set to one of the 32 object buffers.

If you specify a message object buffer that already contains a message definition, it is overwritten.

#### Returns:

None.

# 6.2.1.15 ROM\_CANRetryGet

Returns the current setting for automatic retransmission.

### Prototype:

```
bool
ROM_CANRetryGet(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_CANTABLE is an array of pointers located at ROM_APITABLE[18].

ROM_CANRETRYGET is a function pointer located at ROM_CANTABLE[13].
```

# Parameters:

ui32Base is the base address of the CAN controller.

## **Description:**

Reads the current setting for the automatic retransmission in the CAN controller and returns it to the caller.

### Returns:

Returns **true** if automatic retransmission is enabled, **false** otherwise.

# 6.2.1.16 ROM CANRetrySet

Sets the CAN controller automatic retransmission behavior.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_CANTABLE is an array of pointers located at ROM_APITABLE[18].

ROM_CANRETRYSET is a function pointer located at ROM_CANTABLE[14].
```

#### Parameters:

ui32Base is the base address of the CAN controller.bAutoRetry enables automatic retransmission.

### **Description:**

Enables or disables automatic retransmission of messages with detected errors. If *bAutoRetry* is **true**, then automatic retransmission is enabled, otherwise it is disabled.

#### Returns:

None.

# 6.2.1.17 ROM CANStatusGet

Reads one of the controller status registers.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_CANTABLE is an array of pointers located at ROM_APITABLE[18].

ROM_CANStatusGet is a function pointer located at ROM_CANTABLE[8].
```

#### Parameters:

ui32Base is the base address of the CAN controller.eStatusReg is the status register to read.

### **Description:**

Reads a status register of the CAN controller and returns it to the caller. The different status registers are:

- CAN\_STS\_CONTROL the main controller status
- CAN\_STS\_TXREQUEST bit mask of objects pending transmission
- CAN\_STS\_NEWDAT bit mask of objects with new data
- CAN\_STS\_MSGVAL bit mask of objects with valid configuration

When reading the main controller status register, a pending status interrupt is cleared. This should be used in the interrupt handler for the CAN controller if the cause is a status interrupt. The controller status register fields are as follows:

■ CAN\_STATUS\_BUS\_OFF - controller is in bus-off condition

- CAN STATUS EWARN an error counter has reached a limit of at least 96
- CAN\_STATUS\_EPASS CAN controller is in the error passive state
- CAN\_STATUS\_RXOK a message was received successfully (independent of any message filtering).
- CAN STATUS TXOK a message was successfully transmitted
- CAN STATUS LEC MSK mask of last error code bits (3 bits)
- CAN STATUS LEC NONE no error
- CAN STATUS LEC STUFF stuffing error detected
- CAN STATUS LEC FORM a format error occurred in the fixed format part of a message
- CAN\_STATUS\_LEC\_ACK a transmitted message was not acknowledged
- CAN\_STATUS\_LEC\_BIT1 dominant level detected when trying to send in recessive mode
- CAN\_STATUS\_LEC\_BIT0 recessive level detected when trying to send in dominant mode
- CAN STATUS LEC CRC CRC error in received message

The remaining status registers are 32-bit bit maps to the message objects. They can be used to quickly obtain information about the status of all the message objects without needing to query each one. They contain the following information:

- CAN\_STS\_TXREQUEST if a message object's TxRequest bit is set, that means that a transmission is pending on that object. The application can use this to determine which objects are still waiting to send a message.
- CAN\_STS\_NEWDAT if a message object's NewDat bit is set, that means that a new message has been received in that object, and has not yet been picked up by the host application
- CAN\_STS\_MSGVAL if a message object's MsgVal bit is set, that means it has a valid configuration programmed. The host application can use this to determine which message objects are empty/unused.

### Returns:

Returns the value of the status register.

# 7 CRC

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# 7.1 Introduction

CRC (Cyclic Redundancy Check) is a technique to validate a span of data has the same contents as when previously checked. This technique can be used to validate correct receipt of messages (nothing lost or modified in transit), to validate data after decompression, to validate that Flash memory contents have not been changed, and for other cases where the data must be validated. A CRC is preferred over a simple checksum (for example, XOR all bits) because it catches changes more readily.

The CRC API provides functions to compute the CRC-8-CCITT and CRC-16 of a buffer of data. Support is provided for computing a running CRC, where a partial CRC is computed on one portion of the data, and then continued at a later time on another portion of the data. This is useful when computing the CRC on a stream of data that is coming in via a serial link (for example).

The CRC-16 APIs implement the standard CRC-16 polynomial (also known as CRC-16-IBM):

$$x^{16} + x^{15} + x^2 + 1$$

The CRC-8-CCITT API implements the standard CRC-8-CCITT polynomial:

$$x^8 + x^2 + x + 1$$

The ROM\_Crc16Array3() function fperforms three separate CRC-16 calculations; one across all bytes in the input data array, one across the even bytes, and one across the odd bytes. The ability of a CRC to detect errors decreases as the size of the data array increases. The triple CRC-16 function tries to slow this decrease in error detection rate as it is more difficult for a data error (or errors) to result in all three CRC-16 calculations being correct.

# 7.2 Functions

# **Functions**

- uint16 t ROM Crc16 (uint16 t ui16Crc, const uint8 t \*pui8Data, uint32 t ui32Count)
- uint16\_t ROM\_Crc16Array (uint32\_t ui32WordLen, uint32\_t \*pui32Data)
- void ROM Crc16Array3 (uint32 t ui32WordLen, uint32 t \*pui32Data, uint16 t \*pui16Crc3)
- uint8\_t ROM\_Crc8CCITT (uint8\_t ui8Crc, const uint8\_t \*pui8Data, uint32\_t ui32Count)

# 7.2.1 Function Documentation

# 7.2.1.1 ROM\_Crc16

Calculates the CRC-16 of an array of bytes.

### Prototype:

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_SOFTWARETABLE is an array of pointers located at ROM_APITABLE [21].
ROM_Crc16 is a function pointer located at ROM_SOFTWARETABLE [3].
```

#### Parameters:

```
ui16Crc is the starting CRC-16 value.pui8Data is a pointer to the data buffer.ui32Count is the number of bytes in the data buffer.
```

# **Description:**

This function is used to calculate the CRC-16 of the input buffer. The CRC-16 is computed in a running fashion, meaning that the entire data block that is to have its CRC-16 computed does not need to be supplied all at once. If the input buffer contains the entire block of data, then **ui16Crc** should be set to 0. If, however, the entire block of data is not available, then **ui16Crc** should be set to 0 for the first portion of the data, and then the returned value should be passed back in as **ui16Crc** for the next portion of the data.

For example, to compute the CRC-16 of a block that has been split into three pieces, use the following:

```
uil6Crc = ROM_Crc16(0, pui8Data1, ui32Len1);
uil6Crc = ROM_Crc16(uil6Crc, pui8Data2, ui32Len2);
uil6Crc = ROM_Crc16(uil6Crc, pui8Data3, ui32Len3);
```

Computing a CRC-16 in a running fashion is useful in cases where the data is arriving via a serial link (for example) and is therefore not all available at one time.

### Returns:

The CRC-16 of the input data.

# 7.2.1.2 ROM Crc16Array

Calculates the CRC-16 of an array of words.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_SOFTWARETABLE is an array of pointers located at ROM_APITABLE [21].
ROM_Crc16Array is a function pointer located at ROM_SOFTWARETABLE [1].
```

#### Parameters:

ui32WordLen is the length of the array in words.pui32Data is a pointer to the array of words.

### **Description:**

This function is used to calculate a standard CRC-16 cyclical redundancy check on the data passed to it. The length of the data only matters in terms of the "strength" of the CRC (likelihood of catching errors). The longer the data, the more likely it will not catch some errors.

### Returns:

Returns the calculated CRC-16.

# 7.2.1.3 ROM Crc16Array3

Calculates three CRC-16s of an array of words.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SOFTWARETABLE is an array of pointers located at ROM_APITABLE[21].

ROM_Crc16Array3 is a function pointer located at ROM_SOFTWARETABLE[2].
```

# Parameters:

ui32WordLen is the length of the array in words.
 pui32Data is a pointer to the array of words.
 pui16Crc3 is a pointer to an array into which the three CRC values are to be placed.

### **Description:**

This function is used to calculate three CRC-16s from the same array. This computes the CRC-16 on all of the bytes (same as ROM\_Crc16Array()), on the even bytes, and on the odd bytes. This calculation of three CRC-16s increases the chance of detecting errors because it is much harder for a set of errors to end up being correct for all three CRC-16s.

### Returns:

None

# 7.2.1.4 ROM Crc8CCITT

Calculates the CRC-8-CCITT of an array of bytes.

# Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SOFTWARETABLE is an array of pointers located at ROM_APITABLE[21].

ROM_Crc8CCITT is a function pointer located at ROM_SOFTWARETABLE[4].
```

### Parameters:

ui8Crc is the starting CRC-8-CCITT value.pui8Data is a pointer to the data buffer.ui32Count is the number of bytes in the data buffer.

### **Description:**

This function is used to calculate the CRC-8-CCITT of the input buffer. The CRC-8-CCITT is computed in a running fashion, meaning that the entire data block that is to have its CRC-8-CCITT computed does not need to be supplied all at once. If the input buffer contains the entire block of data, then **ui8Crc** should be set to 0. If, however, the entire block of data is not available, then **ui8Crc** should be set to 0 for the first portion of the data, and then the returned value should be passed back in as **ui8Crc** for the next portion of the data.

For example, to compute the CRC-8-CCITT of a block that has been split into three pieces, use the following:

```
ui8Crc = ROM_Crc8CCITT(0, pui8Data1, ui32Len1);
ui8Crc = ROM_Crc8CCITT(ui8Crc, pui8Data2, ui32Len2);
ui8Crc = ROM_Crc8CCITT(ui8Crc, pui8Data3, ui32Len3);
```

Computing a CRC-8-CCITT in a running fashion is useful in cases where the data is arriving via a serial link (for example) and is therefore not all available at one time.

### Returns:

The CRC-8-CCITT of the input data.

# 8 Flash

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# 8.1 Introduction

The flash API provides a set of functions for dealing with the on-chip flash. Functions are provided to program and erase the flash, configure the flash protection, and handle the flash interrupt.

The flash is organized as a set of 1 kB blocks that can be individually erased. Erasing a block causes the entire contents of the block to be reset to all ones. These blocks are paired into a set of 2 kB blocks that can be individually protected. The blocks can be marked as read-only or execute-only, providing differing levels of code protection. Read-only blocks cannot be erased or programmed, protecting the contents of those blocks from being modified. Execute-only blocks cannot be erased or programmed, and can only be read by the processor instruction fetch mechanism, protecting the contents of those blocks from being read by either the processor or by debuggers.

The flash can be programmed on a word-by-word basis. Programming causes 1 bits to become 0 bits (where appropriate); because of this, a word can be repeatedly programmed so long as each programming operation only requires changing 1 bits to 0 bits.

The timing for the flash is automatically handled by the flash controller. In order to do this, the flash controller must know the clock rate of the system in order to be able to time the number of micro-seconds certain signals are asserted. The number of clock cycles per micro-second must be provided to the flash controller for it to accomplish this timing.

The flash controller has the ability to generate an interrupt when an invalid access is attempted (such as reading from execute-only flash). This can be used to validate the operation of a program; the interrupt will keep invalid accesses from being silently ignored, hiding potential bugs. The flash protection can be applied without being permanently enabled; this, along with the interrupt, allows the program to be debugged before the flash protection is permanently applied to the device (which is a non-reversible operation). An interrupt can also be generated when an erase or programming operation has completed.

# 8.2 Functions

# **Functions**

- int32 t ROM FlashErase (uint32 t ui32Address)
- void ROM\_FlashIntClear (uint32\_t ui32IntFlags)
- void ROM FlashIntDisable (uint32 t ui32IntFlags)
- void ROM FlashIntEnable (uint32 t ui32IntFlags)
- uint32 t ROM FlashIntStatus (bool bMasked)
- int32\_t ROM\_FlashProgram (uint32\_t \*pui32Data, uint32\_t ui32Address, uint32\_t ui32Count)
- tFlashProtection ROM\_FlashProtectGet (uint32\_t ui32Address)
- int32 t ROM FlashProtectSave (void)
- int32\_t ROM\_FlashProtectSet (uint32\_t ui32Address, tFlashProtection eProtect)

- int32 t ROM FlashUserGet (uint32 t \*pui32User0, uint32 t \*pui32User1)
- int32 t ROM FlashUserSave (void)
- int32 t ROM FlashUserSet (uint32 t ui32User0, uint32 t ui32User1)

# 8.2.1 Function Documentation

# 8.2.1.1 ROM FlashErase

Erases a block of flash.

### Prototype:

```
int32_t
ROM_FlashErase(uint32_t ui32Address)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_FLASHTABLE is an array of pointers located at ROM_APITABLE[7].

ROM_FlashErase is a function pointer located at ROM_FLASHTABLE[3].
```

#### Parameters:

ui32Address is the start address of the flash block to be erased.

#### **Description:**

This function will erase a 1 kB block of the on-chip flash. After erasing, the block is filled with 0xFF bytes. Read-only and execute-only blocks cannot be erased.

This function will not return until the block has been erased.

### Returns:

Returns 0 on success, or -1 if an invalid block address was specified or the block is write-protected.

# 8.2.1.2 ROM FlashIntClear

Clears flash controller interrupt sources.

#### Prototype:

```
void
ROM_FlashIntClear(uint32_t ui32IntFlags)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_FLASHTABLE is an array of pointers located at ROM_APITABLE[7].

ROM_FlashIntClear is a function pointer located at ROM_FLASHTABLE[13].
```

#### Parameters:

ui32IntFlags is the bit mask of the interrupt sources to be cleared. Can be any of the FLASH INT PROGRAM or FLASH INT AMISC values.

### **Description:**

The specified flash controller interrupt sources are cleared, so that they no longer assert. This must be done in the interrupt handler to keep it from being called again immediately upon exit.

#### Note:

Because there is a write buffer in the Cortex-M4 processor, it may take several clock cycles before the interrupt source is actually cleared. Therefore, it is recommended that the interrupt source be cleared early in the interrupt handler (as opposed to the very last action) to avoid returning from the interrupt handler before the interrupt source is actually cleared. Failure to do so may result in the interrupt handler being immediately reentered (because the interrupt controller still sees the interrupt source asserted).

#### Returns:

None.

# 8.2.1.3 ROM FlashIntDisable

Disables individual flash controller interrupt sources.

### Prototype:

```
void
ROM_FlashIntDisable(uint32_t ui32IntFlags)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_FLASHTABLE is an array of pointers located at ROM_APITABLE[7].

ROM_FlashIntDisable is a function pointer located at ROM_FLASHTABLE[11].
```

#### Parameters:

ui32IntFlags is a bit mask of the interrupt sources to be disabled. Can be any of the FLASH\_INT\_PROGRAM or FLASH\_INT\_ACCESS values.

### **Description:**

Disables the indicated flash controller interrupt sources. Only the sources that are enabled can be reflected to the processor interrupt; disabled sources have no effect on the processor.

### Returns:

None.

# 8.2.1.4 ROM FlashIntEnable

Enables individual flash controller interrupt sources.

#### Prototype:

```
void
ROM FlashIntEnable(uint32 t ui32IntFlags)
```

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_FLASHTABLE is an array of pointers located at ROM_APITABLE[7].

ROM_FlashIntEnable is a function pointer located at ROM_FLASHTABLE[10].
```

#### Parameters:

ui32IntFlags is a bit mask of the interrupt sources to be enabled. Can be any of the FLASH\_INT\_PROGRAM or FLASH\_INT\_ACCESS values.

Enables the indicated flash controller interrupt sources. Only the sources that are enabled can be reflected to the processor interrupt; disabled sources have no effect on the processor.

#### Returns:

None.

# 8.2.1.5 ROM FlashIntStatus

Gets the current interrupt status.

### Prototype:

```
uint32_t
ROM FlashIntStatus(bool bMasked)
```

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_FLASHTABLE is an array of pointers located at ROM_APITABLE[7].

ROM_FlashIntStatus is a function pointer located at ROM_FLASHTABLE[12].
```

#### Parameters:

**bMasked** is false if the raw interrupt status is required and true if the masked interrupt status is required.

### **Description:**

This returns the interrupt status for the flash controller. Either the raw interrupt status or the status of interrupts that are allowed to reflect to the processor can be returned.

### Returns:

The current interrupt status, enumerated as a bit field of FLASH\_INT\_PROGRAM and FLASH\_INT\_ACCESS.

# 8.2.1.6 ROM FlashProgram

Programs flash.

## Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_FLASHTABLE is an array of pointers located at ROM_APITABLE[7].

ROM_FlashProgram is a function pointer located at ROM_FLASHTABLE[0].
```

### Parameters:

*pui32Data* is a pointer to the data to be programmed.

*ui32Address* is the starting address in flash to be programmed. Must be a multiple of four. *ui32Count* is the number of bytes to be programmed. Must be a multiple of four.

This function will program a sequence of words into the on-chip flash. Each word in a page of flash can only be programmed one time between an erase of that page; programming a word multiple times will result in an unpredictable value in that word of flash.

Since the flash is programmed one word at a time, the starting address and byte count must both be multiples of four. It is up to the caller to verify the programmed contents, if such verification is required.

This function will not return until the data has been programmed.

#### Returns:

Returns 0 on success, or -1 if a programming error is encountered.

# 8.2.1.7 ROM FlashProtectGet

Gets the protection setting for a block of flash.

### Prototype:

```
tFlashProtection
ROM_FlashProtectGet(uint32_t ui32Address)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_FLASHTABLE is an array of pointers located at ROM_APITABLE[7].
ROM_FlashProtectGet is a function pointer located at ROM_FLASHTABLE[4].
```

#### Parameters:

ui32Address is the start address of the flash block to be queried.

#### **Description:**

This function will get the current protection for the specified 2 kB block of flash. Each block can be read/write, read-only, or execute-only. Read/write blocks can be read, executed, erased, and programmed. Read-only blocks can be read and executed. Execute-only blocks can only be executed; processor and debugger data reads are not allowed.

### Returns:

Returns the protection setting for this block. See ROM\_FlashProtectSet() for possible values.

# 8.2.1.8 ROM FlashProtectSave

Saves the flash protection settings.

#### Prototype:

```
int32_t
ROM_FlashProtectSave(void)
```

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_FLASHTABLE is an array of pointers located at ROM_APITABLE[7].

ROM_FlashProtectSave is a function pointer located at ROM_FLASHTABLE[6].
```

This function will make the currently programmed flash protection settings permanent. This is a non-reversible operation; a chip reset or power cycle will not change the flash protection.

This function will not return until the protection has been saved.

#### Returns:

Returns 0 on success, or -1 if a hardware error is encountered.

# 8.2.1.9 ROM FlashProtectSet

Sets the protection setting for a block of flash.

### Prototype:

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_FLASHTABLE is an array of pointers located at ROM_APITABLE[7].

ROM_FlashProtectSet is a function pointer located at ROM_FLASHTABLE[5].
```

#### Parameters:

ui32Address is the start address of the flash block to be protected.

**eProtect** is the protection to be applied to the block. Can be one of **FlashReadWrite**, **FlashReadOnly**, or **FlashExecuteOnly**.

### **Description:**

This function will set the protection for the specified 2 kB block of flash. Blocks which are read/write can be made read-only or execute-only. Blocks which are read-only can be made execute-only. Blocks which are execute-only cannot have their protection modified. Attempts to make the block protection less stringent (that is, read-only to read/write) will result in a failure (and be prevented by the hardware).

Changes to the flash protection are maintained only until the next reset. This allows the application to be executed in the desired flash protection environment to check for inappropriate flash access (via the flash interrupt). To make the flash protection permanent, use the ROM\_FlashProtectSave() function.

# Returns:

Returns 0 on success, or -1 if an invalid address or an invalid protection was specified.

## 8.2.1.10 ROM FlashUserGet

Gets the user registers.

#### **Prototype:**

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_FLASHTABLE is an array of pointers located at ROM_APITABLE[7].
ROM_FlashUserGet is a function pointer located at ROM_FLASHTABLE[7].
```

## Parameters:

pui32User0 is a pointer to the location to store USER Register 0.pui32User1 is a pointer to the location to store USER Register 1.

### **Description:**

This function will read the contents of user registers (0 and 1), and store them in the specified locations.

#### Returns:

Returns 0 on success, or -1 if a hardware error is encountered.

# 8.2.1.11 ROM\_FlashUserSave

Saves the user registers.

## Prototype:

```
int32_t
ROM FlashUserSave(void)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_FLASHTABLE is an array of pointers located at ROM_APITABLE[7].
ROM_FlashUserSave is a function pointer located at ROM_FLASHTABLE[9].
```

# **Description:**

This function will make the currently programmed user register settings permanent. This is a non-reversible operation; a chip reset or power cycle will not change this setting.

This function will not return until the protection has been saved.

#### Returns:

Returns 0 on success, or -1 if a hardware error is encountered.

# 8.2.1.12 ROM FlashUserSet

Sets the user registers.

# Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_FLASHTABLE is an array of pointers located at ROM_APITABLE[7].

ROM_FlashUserSet is a function pointer located at ROM_FLASHTABLE[8].
```

# Parameters:

ui32User0 is the value to store in USER Register 0.ui32User1 is the value to store in USER Register 1.

# **Description:**

This function will set the contents of the user registers (0 and 1) to the specified values.

# Returns:

Returns 0 on success, or -1 if a hardware error is encountered.

# 9 Floating-Point Unit (FPU)

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# 9.1 Introduction

The floating-point unit (FPU) driver provides methods for manipulating the behavior of the floating-point unit in the Cortex-M processor. By default, the floating-point is disabled and must be enabled prior to the execution of any floating-point instructions. If a floating-point instruction is executed when the floating-point unit is disabled, a NOCP usage fault is generated. This feature can be used by an RTOS, for example, to keep track of which tasks actually use the floating-point unit, and therefore only perform floating-point context save/restore on task switches that involve those tasks.

There are three methods of handling the floating-point context when the processor executes an interrupt handler: it can do nothing with the floating-point context, it can always save the floating-point context, or it can perform a lazy save/restore of the floating-point context. If nothing is done with the floating-point context, the interrupt stack frame is identical to a Cortex-M processor that does not have a floating-point unit, containing only the volatile registers of the integer unit. This method is useful for applications where the floating-point unit is used by the main thread of execution, but not in any of the interrupt handlers. By not saving the floating-point context, stack usage is reduced and interrupt latency is kept to a minimum.

Alternatively, the floating-point context can always be saved onto the stack. This method allows floating-point operations to be performed inside interrupt handlers without any special precautions, at the expense of increased stack usage (for the floating-point context) and increased interrupt latency (due to the additional writes to the stack). The advantage to this method is that the stack frame always contains the floating-point context when inside an interrupt handler.

The default handling of the floating-point context is to perform a lazy save/restore. When an interrupt is taken, space is reserved on the stack for the floating-point context but the context is not written. This method keeps the interrupt latency to a minimum because only the integer state is written to the stack. Then, if a floating-point instruction is executed from within the interrupt handler, the floating-point context is written to the stack prior to the execution of the floating-point instruction. Finally, upon return from the interrupt, the floating-point context is restored from the stack only if it was written. Using lazy save/restore provides a blend between fast interrupt response and the ability to use floating-point instructions in the interrupt handler.

The floating-point unit can generate an interrupt when one of several exceptions occur. The exceptions are underflow, overflow, divide by zero, invalid operation, input denormal, and inexact exception. The application can optionally choose to enable one or more of these interrupts and use the interrupt handler to decide upon a course of action to be taken in each case.

The behavior of the floating-point unit can also be adjusted, specifying the format of half-precision floating-point values, the handle of NaN values, the flush-to-zero mode (which sacrifices full IEEE compliance for execution speed), and the rounding mode for results.

# 9.2 Functions

# **Functions**

- void ROM\_FPUDisable (void)
- void ROM\_FPUEnable (void)
- void ROM FPUFlushToZeroModeSet (uint32 t ui32Mode)
- void ROM FPUHalfPrecisionModeSet (uint32 t ui32Mode)
- void ROM FPULazyStackingEnable (void)
- void ROM\_FPUNaNModeSet (uint32\_t ui32Mode)
- void ROM FPURoundingModeSet (uint32 t ui32Mode)
- void ROM\_FPUStackingDisable (void)
- void ROM FPUStackingEnable (void)

# 9.2.1 Function Documentation

# 9.2.1.1 ROM FPUDisable

Disables the floating-point unit.

### Prototype:

```
void
ROM_FPUDisable(void)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_FPUTABLE is an array of pointers located at ROM_APITABLE [26].

ROM FPUDisable is a function pointer located at ROM FPUTABLE [1].
```

#### **Description:**

This function disables the floating-point unit, preventing floating-point instructions from executing (generating a NOCP usage fault instead).

### Returns:

None.

# 9.2.1.2 ROM FPUEnable

Enables the floating-point unit.

### Prototype:

```
void
ROM FPUEnable(void)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_FPUTABLE is an array of pointers located at ROM_APITABLE[26].

ROM_FPUEnable is a function pointer located at ROM_FPUTABLE[0].
```

This function enables the floating-point unit, allowing the floating-point instructions to be executed. This function must be called prior to performing any hardware floating-point operations; failure to do so results in a NOCP usage fault.

#### Returns:

None.

# 9.2.1.3 ROM FPUFlushToZeroModeSet

Selects the flush-to-zero mode.

### Prototype:

void

ROM FPUFlushToZeroModeSet(uint32 t ui32Mode)

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_FPUTABLE is an array of pointers located at ROM_APITABLE[26].

ROM_FPUFlushToZeroModeSet is a function pointer located at ROM_FPUTABLE[2].
```

#### Parameters:

ui32Mode is the flush-to-zero mode; which is either FPU\_FLUSH\_TO\_ZERO\_DIS or FPU\_FLUSH\_TO\_ZERO\_EN.

## **Description:**

This function enables or disables the flush-to-zero mode of the floating-point unit. When disabled (the default), the floating-point unit is fully IEEE compliant. When enabled, values close to zero are treated as zero, greatly improving the execution speed at the expense of some accuracy (as well as IEEE compliance).

#### Note:

Unless this function is called prior to executing any floating-point instructions, the default mode is used.

# Returns:

None.

# 9.2.1.4 ROM FPUHalfPrecisionModeSet

Selects the format of half-precision floating-point values.

### Prototype:

void

ROM\_FPUHalfPrecisionModeSet(uint32\_t ui32Mode)

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_FPUTABLE is an array of pointers located at ROM_APITABLE[26].

ROM_FPUHalfPrecisionModeSet is a function pointer located at ROM_FPUTABLE[3].
```

#### Parameters:

ui32Mode is the format for half-precision floating-point values; which is either FPU HALF IEEE or FPU HALF ALTERNATE.

# **Description:**

This function selects between the IEEE half-precision floating-point representation and the Cortex-M processor alternative representation. The alternative representation has a larger range but does not have a way to encode infinity (positive or negative) or NaN (quiet or signaling). The default setting is the IEEE format.

#### Note:

Unless this function is called prior to executing any floating-point instructions, the default mode is used.

#### Returns:

None.

# 9.2.1.5 ROM\_FPULazyStackingEnable

Enables the lazy stacking of floating-point registers.

### Prototype:

void

ROM\_FPULazyStackingEnable(void)

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_FPUTABLE is an array of pointers located at ROM_APITABLE[26].

ROM_FPULazyStackingEnable is a function pointer located at ROM_FPUTABLE[4].
```

# **Description:**

This function enables the lazy stacking of floating-point registers s0-s15 when an interrupt is handled. When lazy stacking is enabled, space is reserved on the stack for the floating-point context, but the floating-point state is not saved. If a floating-point instruction is executed from within the interrupt context, the floating-point context is first saved into the space reserved on the stack. On completion of the interrupt handler, the floating-point context is only restored if it was saved (as the result of executing a floating-point instruction).

This provides a compromise between fast interrupt response (because the floating-point state is not saved on interrupt entry) and the ability to use floating-point in interrupt handlers (because the floating-point state is saved if floating-point instructions are used).

#### Returns:

None.

## 9.2.1.6 ROM FPUNaNModeSet

Selects the NaN mode.

## Prototype:

void

ROM\_FPUNaNModeSet(uint32\_t ui32Mode)

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_FPUTABLE is an array of pointers located at ROM_APITABLE[26].

ROM_FPUNaNModeSet is a function pointer located at ROM_FPUTABLE[5].
```

#### Parameters:

ui32Mode is the mode for NaN results; which is either FPU\_NAN\_PROPAGATE or FPU\_NAN\_DEFAULT.

### **Description:**

This function selects the handling of NaN results during floating-point computations. NaNs can either propagate (the default), or they can return the default NaN.

#### Note:

Unless this function is called prior to executing any floating-point instructions, the default mode is used.

#### Returns:

None.

# 9.2.1.7 ROM FPURoundingModeSet

Selects the rounding mode for floating-point results.

# Prototype:

void

ROM FPURoundingModeSet(uint32 t ui32Mode)

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_FPUTABLE is an array of pointers located at ROM_APITABLE[26].

ROM_FPURoundingModeSet is a function pointer located at ROM_FPUTABLE[6].
```

### Parameters:

ui32Mode is the rounding mode.

# Description:

This function selects the rounding mode for floating-point results. After a floating-point operation, the result is rounded toward the specified value. The default mode is **FPU ROUND NEAREST**.

The following rounding modes are available (as specified by *ui32Mode*):

- FPU ROUND NEAREST round toward the nearest value
- FPU\_ROUND\_POS\_INF round toward positive infinity
- FPU\_ROUND\_NEG\_INF round toward negative infinity
- FPU\_ROUND\_ZERO round toward zero

### Note:

Unless this function is called prior to executing any floating-point instructions, the default mode is used.

#### Returns:

None.

# 9.2.1.8 ROM FPUStackingDisable

Disables the stacking of floating-point registers.

### Prototype:

```
void
ROM FPUStackingDisable(void)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_FPUTABLE is an array of pointers located at ROM_APITABLE[26].

ROM_FPUStackingDisable is a function pointer located at ROM_FPUTABLE[7].
```

### **Description:**

This function disables the stacking of floating-point registers s0-s15 when an interrupt is handled. When floating-point context stacking is disabled, floating-point operations performed in an interrupt handler destroy the floating-point context of the main thread of execution.

#### Returns:

None.

# 9.2.1.9 ROM\_FPUStackingEnable

Enables the stacking of floating-point registers.

#### Prototype:

```
void
ROM_FPUStackingEnable(void)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_FPUTABLE is an array of pointers located at ROM_APITABLE[26].

ROM_FPUSTackingEnable is a function pointer located at ROM_FPUTABLE[8].
```

# Description:

This function enables the stacking of floating-point registers s0-s15 when an interrupt is handled. When enabled, space is reserved on the stack for the floating-point context and the floating-point state is saved into this stack space. Upon return from the interrupt, the floating-point context is restored.

If the floating-point registers are not stacked, floating-point instructions cannot be safely executed in an interrupt handler because the values of s0-s15 are not likely to be preserved for the interrupted code. On the other hand, stacking the floating-point registers increases the stacking operation from 8 words to 26 words, also increasing the interrupt response latency.

### Returns:

None.

# 10 GPIO

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# 10.1 Introduction

The GPIO module provides control for up to eight independent GPIO pins (the actual number present depend upon the GPIO port and part number). Each pin has the following capabilities:

- Can be configured as an input or an output. On reset, they default to being an input.
- In input mode, can generate interrupts on high level, low level, rising edge, falling edge, or both edges.
- In output mode, can be configured for 2 mA, 4 mA, or 8 mA drive strength. The 8 mA drive strength configuration has optional slew rate control to limit the rise and fall times of the signal. On reset, they default to 2 mA drive strength.
- Optional weak pull-up or pull-down resistors. On reset, they default to no pull-up or pull-down resistors.
- Optional open-drain operation. On reset, they default to standard push/pull operation.
- Can be configured to be a GPIO or a peripheral pin. On reset, they default to being GPIOs. Note that not all pins on all parts have peripheral functions, in which case the pin is only useful as a GPIO (that is, when configured for peripheral function the pin will not do anything useful).

Most of the GPIO functions can operate on more than one GPIO pin (within a single module) at a time. The *ui8Pins* parameter to these functions is used to specify the pins that are affected; the GPIO pins whose corresponding bits in this parameter that are set will be affected (where pin 0 is in bit 0, pin 1 in bit 1, and so on). For example, if *ui8Pins* is 0x09, then pins 0 and 3 will be affected by the function.

This is most useful for the ROM\_GPIOPinRead() and ROM\_GPIOPinWrite() functions; a read will return only the value of the requested pins (with the other pin values masked out) and a write will affect the requested pins simultaneously (that is, the state of multiple GPIO pins can be changed at the same time). This data masking for the GPIO pin state occurs in the hardware; a single read or write is issued to the hardware, which interprets some of the address bits as an indication of the GPIO pins to operate upon (and therefore the ones to not affect). See the part data sheet for details of the GPIO data register address-based bit masking.

For functions that have a *ui8Pin* (singular) parameter, only a single pin is affected by the function. In this case, this value specifies the pin number (that is, 0 through 7).

# 10.2 Functions

# **Functions**

- void ROM GPIOADCTriggerDisable (uint32 t ui32Port, uint8 t ui8Pins)
- void ROM\_GPIOADCTriggerEnable (uint32\_t ui32Port, uint8\_t ui8Pins)

- uint32 t ROM GPIODirModeGet (uint32 t ui32Port, uint8 t ui8Pin)
- void ROM\_GPIODirModeSet (uint32\_t ui32Port, uint8\_t ui8Pins, uint32\_t ui32PinIO)
- void ROM\_GPIODMATriggerDisable (uint32\_t ui32Port, uint8\_t ui8Pins)
- void ROM\_GPIODMATriggerEnable (uint32\_t ui32Port, uint8\_t ui8Pins)
- uint32\_t ROM\_GPIOIntTypeGet (uint32\_t ui32Port, uint8\_t ui8Pin)
- void ROM\_GPIOIntTypeSet (uint32\_t ui32Port, uint8\_t ui8Pins, uint32\_t ui32IntType)
- void ROM\_GPIOPadConfigGet (uint32\_t ui32Port, uint8\_t ui8Pin, uint32\_t \*pui32Strength, uint32\_t \*pui32PinType)
- void ROM\_GPIOPadConfigSet (uint32\_t ui32Port, uint8\_t ui8Pins, uint32\_t ui32Strength, uint32\_t ui32PinType)
- void ROM\_GPIOPinConfigure (uint32\_t ui32PinConfig)
- int32 t ROM GPIOPinRead (uint32 t ui32Port, uint8 t ui8Pins)
- void ROM\_GPIOPinTypeADC (uint32\_t ui32Port, uint8\_t ui8Pins)
- void ROM\_GPIOPinTypeCAN (uint32\_t ui32Port, uint8\_t ui8Pins)
- void ROM\_GPIOPinTypeComparator (uint32\_t ui32Port, uint8\_t ui8Pins)
- void ROM\_GPIOPinTypeGPIOInput (uint32\_t ui32Port, uint8\_t ui8Pins)
- void ROM GPIOPinTypeGPIOOutput (uint32 t ui32Port, uint8 t ui8Pins)
- void ROM\_GPIOPinTypeGPIOOutputOD (uint32\_t ui32Port, uint8\_t ui8Pins)
- void ROM\_GPIOPinTypeI2C (uint32\_t ui32Port, uint8\_t ui8Pins)
- void ROM GPIOPinTypeI2CSCL (uint32 t ui32Port, uint8 t ui8Pins)
- void ROM GPIOPinTypePWM (uint32 t ui32Port, uint8 t ui8Pins)
- void ROM\_GPIOPinTypeQEI (uint32\_t ui32Port, uint8\_t ui8Pins)
- void ROM\_GPIOPinTypeSSI (uint32\_t ui32Port, uint8\_t ui8Pins)
- void ROM GPIOPinTypeTimer (uint32 t ui32Port, uint8 t ui8Pins)
- void ROM GPIOPinTypeUART (uint32 t ui32Port, uint8 t ui8Pins)
- void ROM\_GPIOPinTypeUSBAnalog (uint32\_t ui32Port, uint8\_t ui8Pins)
- void ROM GPIOPinTypeUSBDigital (uint32 t ui32Port, uint8 t ui8Pins)
- void ROM GPIOPinWrite (uint32 t ui32Port, uint8 t ui8Pins, uint8 t ui8Val)

# 10.2.1 Function Documentation

# 10.2.1.1 ROM GPIOADCTriggerDisable

Disable a GPIO pin as a trigger to start an ADC capture.

#### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIOADCTriggerDisable is a function pointer located at ROM_GPIOTABLE[34].
```

### Parameters:

*ui32Port* is the base address of the GPIO port.

ui8Pins is the bit-packed representation of the pin(s).

# Description:

This function disables a GPIO pin to be used as a trigger to start an ADC sequence. This function can be used to disable this feature if it was enabled via a call to ROM\_GPIOADCTriggerEnable().

#### Returns:

None.

# 10.2.1.2 ROM\_GPIOADCTriggerEnable

Enables a GPIO pin as a trigger to start an ADC capture.

## Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIOADCTriggerEnable is a function pointer located at ROM_GPIOTABLE[33].
```

#### Parameters:

```
ui32Port is the base address of the GPIO port.ui8Pins is the bit-packed representation of the pin(s).
```

#### **Description:**

This function enables a GPIO pin to be used as a trigger to start an ADC sequence. Any GPIO pin can be configured to be an external trigger for an ADC sequence. The GPIO pin will still generate interrupts if the interrupt is enabled for the selected pin.

#### Returns:

None.

# 10.2.1.3 ROM GPIODirModeGet

Gets the direction and mode of a pin.

#### Prototype:

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIODirModeGet is a function pointer located at ROM_GPIOTABLE[2].
```

#### Parameters:

ui32Port is the base address of the GPIO port.ui8Pin is the pin number.

### **Description:**

This function gets the direction and control mode for a specified pin on the selected GPIO port. The pin can be configured as either an input or output under software control, or it can be under hardware control. The type of control and direction are returned as an enumerated data type.

#### Returns:

Returns one of the enumerated data types described for ROM\_GPIODirModeSet().

# 10.2.1.4 ROM GPIODirModeSet

Sets the direction and mode of the specified pin(s).

# Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIODirModeSet is a function pointer located at ROM_GPIOTABLE[1].
```

### Parameters:

```
ui32Port is the base address of the GPIO portui8Pins is the bit-packed representation of the pin(s).ui32PinIO is the pin direction and/or mode.
```

### **Description:**

This function will set the specified pin(s) on the selected GPIO port as either an input or output under software control, or it will set the pin to be under hardware control.

The parameter *ui32PinIO* is an enumerated data type that can be one of the following values:

```
■ GPIO_DIR_MODE_IN
■ GPIO_DIR_MODE_OUT
■ GPIO DIR MODE HW
```

where **GPIO\_DIR\_MODE\_IN** specifies that the pin is programmed as a software controlled input, **GPIO\_DIR\_MODE\_OUT** specifies that the pin is programmed as a software controlled output, and **GPIO\_DIR\_MODE\_HW** specifies that the pin is placed under hardware control.

The pin(s) are specified using a bit-packed byte, where each bit that is set identifies the pin to be accessed, and where bit 0 of the byte represents GPIO port pin 0, bit 1 represents GPIO port pin 1, and so on.

#### Note:

ROM\_GPIOPadConfigSet() must also be used to configure the corresponding pad(s) in order for them to propagate the signal to/from the GPIO.

#### Returns:

None.

# 10.2.1.5 ROM GPIODMATriggerDisable

Disables a GPIO pin as a trigger to start a DMA transaction.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIODMATriggerDisable is a function pointer located at ROM_GPIOTABLE[32].
```

#### Parameters:

ui32Port is the base address of the GPIO port.ui8Pins is the bit-packed representation of the pin(s).

#### **Description:**

This function disables a GPIO pin to be used as a trigger to start a uDMA transaction. This function can be used to disable this feature if it was enabled via a call to GPIODMATriggerEnable().

### Returns:

None.

# 10.2.1.6 ROM\_GPIODMATriggerEnable

Enables a GPIO pin as a trigger to start a DMA transaction.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIODMATriggerEnable is a function pointer located at ROM_GPIOTABLE[31].
```

### Parameters:

```
ui32Port is the base address of the GPIO port.ui8Pins is the bit-packed representation of the pin(s).
```

### **Description:**

This function enables a GPIO pin to be used as a trigger to start a uDMA transaction. Any GPIO pin can be configured to be an external trigger for the uDMA. The GPIO pin will still generate interrupts if the interrupt is enabled for the selected pin.

#### Returns:

None.

# 10.2.1.7 ROM\_GPIOIntTypeGet

Gets the interrupt type for a pin.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].
ROM_GPIOIntTypeGet is a function pointer located at ROM_GPIOTABLE[4].
```

### Parameters:

ui32Port is the base address of the GPIO port.
ui8Pin is the pin number.

# **Description:**

This function gets the interrupt type for a specified pin on the selected GPIO port. The pin can be configured as a falling edge, rising edge, or both edge detected interrupt, or it can be configured as a low level or high level detected interrupt. The type of interrupt detection mechanism is returned as an enumerated data type.

### Returns:

Returns one of the enumerated data types described for ROM\_GPIOIntTypeSet().

# 10.2.1.8 ROM GPIOIntTypeSet

Sets the interrupt type for the specified pin(s).

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIOIntTypeSet is a function pointer located at ROM_GPIOTABLE[3].
```

#### Parameters:

```
ui32Port is the base address of the GPIO port.ui8Pins is the bit-packed representation of the pin(s).ui32IntType specifies the type of interrupt trigger mechanism.
```

This function sets up the various interrupt trigger mechanisms for the specified pin(s) on the selected GPIO port.

The parameter *ui32IntType* is an enumerated data type that can be one of the following values:

- **GPIO FALLING EDGE**
- **GPIO RISING EDGE**
- GPIO BOTH EDGES
- GPIO LOW LEVEL
- GPIO\_HIGH\_LEVEL

where the different values describe the interrupt detection mechanism (edge or level) and the particular triggering event (falling, rising, or both edges for edge detect, low or high for level detect).

The pin(s) are specified using a bit-packed byte, where each bit that is set identifies the pin to be accessed, and where bit 0 of the byte represents GPIO port pin 0, bit 1 represents GPIO port pin 1, and so on.

#### Note:

In order to avoid any spurious interrupts, the user must ensure that the GPIO inputs remain stable for the duration of this function.

#### Returns:

None.

# 10.2.1.9 ROM GPIOPadConfigGet

Gets the pad configuration for a pin.

# Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].
ROM_GPIOPadConfigGet is a function pointer located at ROM_GPIOTABLE[6].
```

### Parameters:

```
ui32Port is the base address of the GPIO port.ui8Pin is the pin number.pui32Strength is a pointer to storage for the output drive strength.pui32PinType is a pointer to storage for the output drive type.
```

### **Description:**

This function gets the pad configuration for a specified pin on the selected GPIO port. The values returned in *pui32Strength* and *pui32PinType* correspond to the values used in ROM\_GPIOPadConfigSet(). This function also works for pin(s) configured as input pin(s);

however, the only meaningful data returned is whether the pin is terminated with a pull-up or down resistor.

#### Returns:

None

# 10.2.1.10 ROM\_GPIOPadConfigSet

Sets the pad configuration for the specified pin(s).

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIOPadConfigSet is a function pointer located at ROM_GPIOTABLE[5].
```

#### Parameters:

```
ui32Port is the base address of the GPIO port.
ui8Pins is the bit-packed representation of the pin(s).
ui32Strength specifies the output drive strength.
ui32PinType specifies the pin type.
```

#### **Description:**

This function sets the drive strength and type for the specified pin(s) on the selected GPIO port. For pin(s) configured as input ports, the pad is configured as requested, but the only real effect on the input is the configuration of the pull-up or pull-down termination.

The parameter *ui32Strength* can be one of the following values:

```
■ GPIO STRENGTH 2MA
```

- GPIO\_STRENGTH\_4MA
- GPIO STRENGTH 8MA
- GPIO\_STRENGTH\_8MA\_SC

where **GPIO\_STRENGTH\_xMA** specifies either 2, 4, or 8 mA output drive strength, and **GPIO\_OUT\_STRENGTH\_8MA\_SC** specifies 8 mA output drive with slew control.

The parameter *ui32PinType* can be one of the following values:

```
■ GPIO_PIN_TYPE_STD
```

- GPIO PIN TYPE STD WPU
- GPIO\_PIN\_TYPE\_STD\_WPD
- GPIO PIN TYPE OD
- GPIO PIN TYPE OD WPU
- GPIO\_PIN\_TYPE\_OD\_WPD
- GPIO\_PIN\_TYPE\_ANALOG

where **GPIO\_PIN\_TYPE\_STD**\* specifies a push-pull pin, **GPIO\_PIN\_TYPE\_OD**\* specifies an open-drain pin, \*\_**WPU** specifies a weak pull-up, \*\_**WPD** specifies a weak pull-down, and **GPIO\_PIN\_TYPE\_ANALOG** specifies an analog input.

The pin(s) are specified using a bit-packed byte, where each bit that is set identifies the pin to be accessed, and where bit 0 of the byte represents GPIO port pin 0, bit 1 represents GPIO port pin 1, and so on.

#### Returns:

None.

# 10.2.1.11 ROM GPIOPinConfigure

Configures the alternate function of a GPIO pin.

### Prototype:

```
void
ROM_GPIOPinConfigure(uint32_t ui32PinConfig)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIOPinConfigure is a function pointer located at ROM_GPIOTABLE[26].
```

#### Parameters:

ui32PinConfig is the pin configuration value, specified as only one of the GPIO\_P??\_??? values.

# Description:

This function configures the pin mux that selects the peripheral function associated with a particular GPIO pin. Only one peripheral function at a time can be associated with a GPIO pin, and each peripheral function should only be associated with a single GPIO pin at a time (despite the fact that many of them can be associated with more than one GPIO pin).

#### Returns:

None.

# 10.2.1.12 ROM GPIOPinRead

Reads the values present of the specified pin(s).

# Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIOPinRead is a function pointer located at ROM_GPIOTABLE[11].
```

#### Parameters:

ui32Port is the base address of the GPIO port.ui8Pins is the bit-packed representation of the pin(s).

#### **Description:**

The values at the specified pin(s) are read, as specified by *ui8Pins*. Values are returned for both input and output pin(s), and the value for pin(s) that are not specified by *ui8Pins* are set to 0.

The pin(s) are specified using a bit-packed byte, where each bit that is set identifies the pin to be accessed, and where bit 0 of the byte represents GPIO port pin 0, bit 1 represents GPIO port pin 1, and so on.

#### Returns:

Returns a bit-packed byte providing the state of the specified pin, where bit 0 of the byte represents GPIO port pin 0, bit 1 represents GPIO port pin 1, and so on. Any bit that is not specified by *ui8Pins* is returned as a 0. Bits 31:8 should be ignored.

# 10.2.1.13 ROM GPIOPinTypeADC

Configures pin(s) for use as analog-to-digital converter inputs.

# Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIOPinTypeADC is a function pointer located at ROM_GPIOTABLE[23].
```

#### Parameters:

```
ui32Port is the base address of the GPIO port. ui8Pins is the bit-packed representation of the pin(s).
```

# **Description:**

The analog-to-digital converter input pins must be properly configured to function correctly. This function provides the proper configuration for those pin(s).

The pin(s) are specified using a bit-packed byte, where each bit that is set identifies the pin to be accessed, and where bit 0 of the byte represents GPIO port pin 0, bit 1 represents GPIO port pin 1, and so on.

#### Note:

This cannot be used to turn any pin into an ADC input; it only configures an ADC input pin for proper operation.

#### Returns:

None.

# 10.2.1.14 ROM GPIOPinTypeCAN

Configures pin(s) for use as a CAN device.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIOPinTypeCAN is a function pointer located at ROM_GPIOTABLE[12].
```

#### Parameters:

ui32Port is the base address of the GPIO port.ui8Pins is the bit-packed representation of the pin(s).

#### **Description:**

The CAN pins must be properly configured for the CAN peripherals to function correctly. This function provides a typical configuration for those pin(s); other configurations may work as well depending upon the board setup (for example, using the on-chip pull-ups).

The pin(s) are specified using a bit-packed byte, where each bit that is set identifies the pin to be accessed, and where bit 0 of the byte represents GPIO port pin 0, bit 1 represents GPIO port pin 1, and so on.

# Note:

This cannot be used to turn any pin into a CAN pin; it only configures a CAN pin for proper operation.

### Returns:

None.

# 10.2.1.15 ROM\_GPIOPinTypeComparator

Configures pin(s) for use as an analog comparator input.

### Prototype:

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIOPinTypeComparator is a function pointer located at ROM_GPIOTABLE[13].
```

#### Parameters:

```
ui32Port is the base address of the GPIO port.ui8Pins is the bit-packed representation of the pin(s).
```

The analog comparator input pins must be properly configured for the analog comparator to function correctly. This function provides the proper configuration for those pin(s).

The pin(s) are specified using a bit-packed byte, where each bit that is set identifies the pin to be accessed, and where bit 0 of the byte represents GPIO port pin 0, bit 1 represents GPIO port pin 1, and so on.

#### Note:

This cannot be used to turn any pin into an analog comparator input; it only configures an analog comparator pin for proper operation.

#### Returns:

None.

# 10.2.1.16 ROM GPIOPinTypeGPIOInput

Configures pin(s) for use as GPIO inputs.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIOPinTypeGPIOInput is a function pointer located at ROM_GPIOTABLE[14].
```

#### Parameters:

```
ui32Port is the base address of the GPIO port.ui8Pins is the bit-packed representation of the pin(s).
```

## **Description:**

The GPIO pins must be properly configured in order to function correctly as GPIO inputs. This function provides the proper configuration for those pin(s).

The pin(s) are specified using a bit-packed byte, where each bit that is set identifies the pin to be accessed, and where bit 0 of the byte represents GPIO port pin 0, bit 1 represents GPIO port pin 1, and so on.

## Returns:

None.

# 10.2.1.17 ROM GPIOPinTypeGPIOOutput

Configures pin(s) for use as GPIO outputs.

# Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIOPinTypeGPIOOutput is a function pointer located at ROM_GPIOTABLE[15].
```

#### Parameters:

ui32Port is the base address of the GPIO port.ui8Pins is the bit-packed representation of the pin(s).

## **Description:**

The GPIO pins must be properly configured in order to function correctly as GPIO outputs. This function provides the proper configuration for those pin(s).

The pin(s) are specified using a bit-packed byte, where each bit that is set identifies the pin to be accessed, and where bit 0 of the byte represents GPIO port pin 0, bit 1 represents GPIO port pin 1, and so on.

#### Returns:

None.

# 10.2.1.18 ROM\_GPIOPinTypeGPIOOutputOD

Configures pin(s) for use as GPIO open drain outputs.

# Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIOPinTypeGPIOOutputOD is a function pointer located at ROM_GPIOTABLE[22].
```

#### Parameters:

```
ui32Port is the base address of the GPIO port.ui8Pins is the bit-packed representation of the pin(s).
```

### **Description:**

The GPIO pins must be properly configured in order to function correctly as GPIO outputs. This function provides the proper configuration for those pin(s).

The pin(s) are specified using a bit-packed byte, where each bit that is set identifies the pin to be accessed, and where bit 0 of the byte represents GPIO port pin 0, bit 1 represents GPIO port pin 1, and so on.

### Returns:

None.

# 10.2.1.19 ROM GPIOPinTypeI2C

Configures pin(s) for use by the I2C peripheral.

# Prototype:

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIOPinTypeI2C is a function pointer located at ROM_GPIOTABLE[16].
```

#### Parameters:

ui32Port is the base address of the GPIO port.ui8Pins is the bit-packed representation of the pin(s).

#### **Description:**

The I2C pins must be properly configured for the I2C peripheral to function correctly. This function provides the proper configuration for those pin(s).

The pin(s) are specified using a bit-packed byte, where each bit that is set identifies the pin to be accessed, and where bit 0 of the byte represents GPIO port pin 0, bit 1 represents GPIO port pin 1, and so on.

#### Note:

This cannot be used to turn any pin into an I2C pin; it only configures an I2C pin for proper operation.

#### Returns:

None.

# 10.2.1.20 ROM\_GPIOPinTypeI2CSCL

Configures pin(s) for use as SCL by the I2C peripheral.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIOPinTypeI2CSCL is a function pointer located at ROM_GPIOTABLE[39].
```

#### Parameters:

ui32Port is the base address of the GPIO port.ui8Pins is the bit-packed representation of the pin(s).

#### **Description:**

The I2C pins must be properly configured for the I2C peripheral to function correctly. This function provides the proper configuration for the SCL pin(s).

The pin(s) are specified using a bit-packed byte, where each bit that is set identifies the pin to be accessed, and where bit 0 of the byte represents GPIO port pin 0, bit 1 represents GPIO port pin 1, and so on.

#### Note:

This cannot be used to turn any pin into an I2C SCL pin; it only configures an I2C SCL pin for proper operation.

#### Returns:

None.

# 10.2.1.21 ROM\_GPIOPinTypePWM

Configures pin(s) for use by the PWM peripheral.

# Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIOPinTypePWM is a function pointer located at ROM_GPIOTABLE[17].
```

#### Parameters:

```
ui32Port is the base address of the GPIO port.ui8Pins is the bit-packed representation of the pin(s).
```

#### **Description:**

The PWM pins must be properly configured for the PWM peripheral to function correctly. This function provides a typical configuration for those pin(s); other configurations may work as well depending upon the board setup (for example, using the on-chip pull-ups).

The pin(s) are specified using a bit-packed byte, where each bit that is set identifies the pin to be accessed, and where bit 0 of the byte represents GPIO port pin 0, bit 1 represents GPIO port pin 1, and so on.

#### Note:

This cannot be used to turn any pin into a PWM pin; it only configures a PWM pin for proper operation.

#### Returns:

None.

# 10.2.1.22 ROM GPIOPinTypeQEI

Configures pin(s) for use by the QEI peripheral.

# Prototype:

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIOPinTypeQEI is a function pointer located at ROM_GPIOTABLE[18].
```

#### Parameters:

ui32Port is the base address of the GPIO port.ui8Pins is the bit-packed representation of the pin(s).

### **Description:**

The QEI pins must be properly configured for the QEI peripheral to function correctly. This function provides a typical configuration for those pin(s); other configurations may work as well depending upon the board setup (for example, not using the on-chip pull-ups).

The pin(s) are specified using a bit-packed byte, where each bit that is set identifies the pin to be accessed, and where bit 0 of the byte represents GPIO port pin 0, bit 1 represents GPIO port pin 1, and so on.

#### Note:

This cannot be used to turn any pin into a QEI pin; it only configures a QEI pin for proper operation.

### Returns:

None.

# 10.2.1.23 ROM GPIOPinTypeSSI

Configures pin(s) for use by the SSI peripheral.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIOPinTypeSSI is a function pointer located at ROM_GPIOTABLE[19].
```

#### Parameters:

```
ui32Port is the base address of the GPIO port.ui8Pins is the bit-packed representation of the pin(s).
```

#### **Description:**

The SSI pins must be properly configured for the SSI peripheral to function correctly. This function provides a typical configuration for those pin(s); other configurations may work as well depending upon the board setup (for example, using the on-chip pull-ups).

The pin(s) are specified using a bit-packed byte, where each bit that is set identifies the pin to be accessed, and where bit 0 of the byte represents GPIO port pin 0, bit 1 represents GPIO port pin 1, and so on.

#### Note:

This cannot be used to turn any pin into a SSI pin; it only configures a SSI pin for proper operation.

#### Returns:

None.

# 10.2.1.24 ROM\_GPIOPinTypeTimer

Configures pin(s) for use by the Timer peripheral.

# Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIOPINTypeTimer is a function pointer located at ROM_GPIOTABLE[20].
```

#### Parameters:

```
ui32Port is the base address of the GPIO port.ui8Pins is the bit-packed representation of the pin(s).
```

#### **Description:**

The CCP pins must be properly configured for the timer peripheral to function correctly. This function provides a typical configuration for those pin(s); other configurations may work as well depending upon the board setup (for example, using the on-chip pull-ups).

The pin(s) are specified using a bit-packed byte, where each bit that is set identifies the pin to be accessed, and where bit 0 of the byte represents GPIO port pin 0, bit 1 represents GPIO port pin 1, and so on.

#### Note:

This cannot be used to turn any pin into a timer pin; it only configures a timer pin for proper operation.

#### Returns:

None.

# 10.2.1.25 ROM\_GPIOPinTypeUART

Configures pin(s) for use by the UART peripheral.

# **Prototype:**

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].
ROM_GPIOPinTypeUART is a function pointer located at ROM_GPIOTABLE[21].
```

#### Parameters:

ui32Port is the base address of the GPIO port.ui8Pins is the bit-packed representation of the pin(s).

### **Description:**

The UART pins must be properly configured for the UART peripheral to function correctly. This function provides a typical configuration for those pin(s); other configurations may work as well depending upon the board setup (for example, using the on-chip pull-ups).

The pin(s) are specified using a bit-packed byte, where each bit that is set identifies the pin to be accessed, and where bit 0 of the byte represents GPIO port pin 0, bit 1 represents GPIO port pin 1, and so on.

#### Note:

This cannot be used to turn any pin into a UART pin; it only configures a UART pin for proper operation.

#### Returns:

None.

# 10.2.1.26 ROM GPIOPinTypeUSBAnalog

Configures pin(s) for use by the USB peripheral.

#### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIOPinTypeUSBAnalog is a function pointer located at ROM_GPIOTABLE[28].
```

#### Parameters:

```
ui32Port is the base address of the GPIO port.ui8Pins is the bit-packed representation of the pin(s).
```

#### **Description:**

Some USB analog pins must be properly configured for the USB peripheral to function correctly. This function provides the proper configuration for any USB pin(s). This can also be used to configure the EPEN and PFAULT pins so that they are no longer used by the USB controller.

The pin(s) are specified using a bit-packed byte, where each bit that is set identifies the pin to be accessed, and where bit 0 of the byte represents GPIO port pin 0, bit 1 represents GPIO port pin 1, and so on.

#### Note:

This cannot be used to turn any pin into a USB pin; it only configures a USB pin for proper operation.

### Returns:

None.

# 10.2.1.27 ROM\_GPIOPinTypeUSBDigital

Configures pin(s) for use by the USB peripheral.

# Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_GPIOTABLE is an array of pointers located at ROM_APITABLE[4].

ROM_GPIOPinTypeUSBDigital is a function pointer located at ROM_GPIOTABLE[24].
```

#### Parameters:

```
ui32Port is the base address of the GPIO port.ui8Pins is the bit-packed representation of the pin(s).
```

#### **Description:**

Some USB digital pins must be properly configured for the USB peripheral to function correctly. This function provides a typical configuration for the digital USB pin(s); other configurations may work as well depending upon the board setup (for example, using the on-chip pull-ups).

This function should only be used with EPEN and PFAULT pins as all other USB pins are analog in nature or are not used in devices without OTG functionality.

The pin(s) are specified using a bit-packed byte, where each bit that is set identifies the pin to be accessed, and where bit 0 of the byte represents GPIO port pin 0, bit 1 represents GPIO port pin 1, and so on.

#### Note:

This cannot be used to turn any pin into a USB pin; it only configures a USB pin for proper operation.

#### Returns:

None.

# 10.2.1.28 ROM GPIOPinWrite

Writes a value to the specified pin(s).

#### Prototype:

# **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_GPIOTABLE is an array of pointers located at ROM\_APITABLE[4].

ROM\_GPIOPinWrite is a function pointer located at ROM\_GPIOTABLE[0].

#### Parameters:

ui32Port is the base address of the GPIO port.ui8Pins is the bit-packed representation of the pin(s).ui8Val is the value to write to the pin(s).

# **Description:**

Writes the corresponding bit values to the output pin(s) specified by *ui8Pins*. Writing to a pin configured as an input pin has no effect.

The pin(s) are specified using a bit-packed byte, where each bit that is set identifies the pin to be accessed, and where bit 0 of the byte represents GPIO port pin 0, bit 1 represents GPIO port pin 1, and so on.

#### Returns:

None.

# 11 Hibernation Module

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# 11.1 Introduction

The Hibernate API provides a set of functions for using the Hibernation module, which allows the software application to cause power to be removed from the microcontroller, and then be powered on later based on specific time or a signal on the external **WAKE** pin. The API provides functions to configure wake conditions, manage interrupts, read status, save and restore program state information, and request hibernation mode.

Some of the features of the Hibernation module are:

- 32-bit real time clock
- Trim register for fine tuning the RTC rate
- Two RTC match registers for generating RTC events
- External **WAKE** pin to initiate a wake-up
- Low-battery detection
- 64 32-bit words of non-volatile memory
- Programmable interrupts for hibernation events

The Hibernation module must be enabled before it can be used. Use the ROM\_HibernateEnableExpClk() function to enable it. If a crystal is used for the clock source, then the initializing code must allow time for the crystal to stabilize after calling the ROM\_HibernateEnableExpClk() function. Refer to the device data sheet for information about crystal stabilization time. If an oscillator is used, then no delay is necessary.

In order to use the RTC feature of the Hibernation module, the RTC must be enabled by calling ROM\_HibernateRTCEnable(). It can be later disabled by calling ROM\_HibernateRTCDisable(). These functions can be called at any time to start and stop the RTC. The RTC value can be read or set by using the ROM\_HibernateRTCGet() and ROM\_HibernateRTCSet() functions. The real-time clock rate can be adjusted by using the trim register. Use the ROM\_HibernateRTCTrimGet() and ROM\_HibernateRTCTrimSet() functions for this purpose.

Application state information can be stored in the non-volatile memory of the Hibernation module when the processor is powered off. Use the ROM\_HibernateDataSet() and ROM\_HibernateDataGet() functions to access the non-volatile memory area.

The module can be configured to wake when the external **WAKE** pin is asserted, or when an RTC match occurs, or both. Use the ROM\_HibernateWakeSet() function to configure the wake conditions. The present configuration can be read by calling ROM\_HibernateWakeGet().

The Hibernation module can detect a low battery and signal the processor. It can also be configured to abort a hibernation request if the battery voltage is too low. Use the ROM\_HibernateLowBatSet() and ROM\_HibernateLowBatGet() functions to configure this feature.

Several functions are provided for managing interrupts. Use the ROM\_HibernateIntEnable() and ROM\_HibernateIntDisable() functions to enable and disable specific interrupt sources. The present

interrupt status can be found by calling ROM\_HibernateIntStatus(). In the interrupt handler, all pending interrupts must be cleared. Use the ROM\_HibernateIntClear() function to clear pending interrupts.

Finally, once the module is appropriately configured, the state saved, and the software application is ready to hibernate, call the ROM\_HibernateRequest() function. This will initiate the sequence to remove power from the processor. At a power-on reset, the software application can use the ROM\_HibernateIsActive() function to determine if the Hibernation module is already active and therefore does not need to be enabled. This can provide a hint to the software that the processor is waking from hibernation instead of a cold start. The software can then use the ROM\_HibernateIntStatus() and ROM\_HibernateDataGet() functions to discover the cause of the wake and to get the saved system state.

# 11.2 Functions

# **Functions**

- uint32 t ROM HibernateBatCheckDone (void)
- void ROM\_HibernateBatCheckStart (void)
- void ROM\_HibernateClockConfig (uint32\_t ui32Config)
- void ROM\_HibernateDataGet (uint32\_t \*pui32Data, uint32\_t ui32Count)
- void ROM HibernateDataSet (uint32 t \*pui32Data, uint32 t ui32Count)
- void ROM\_HibernateDisable (void)
- void ROM HibernateEnableExpClk (uint32 t ui32HibClk)
- void ROM\_HibernateIntClear (uint32\_t ui32IntFlags)
- void ROM HibernateIntDisable (uint32 t ui32IntFlags)
- void ROM\_HibernateIntEnable (uint32\_t ui32IntFlags)
- uint32 t ROM HibernateIntStatus (bool bMasked)
- uint32 t ROM HibernateIsActive (void)
- uint32 t ROM HibernateLowBatGet (void)
- void ROM HibernateLowBatSet (uint32 t ui32LowBatFlags)
- void ROM\_HibernateRequest (void)
- void ROM\_HibernateRTCDisable (void)
- void ROM\_HibernateRTCEnable (void)
- uint32 t ROM HibernateRTCGet (void)
- void ROM HibernateRTCSet (uint32 t ui32RTCValue)
- uint32\_t ROM\_HibernateRTCSSGet (void)
- uint32 t ROM HibernateRTCTrimGet (void)
- void ROM HibernateRTCTrimSet (uint32 t ui32Trim)
- uint32\_t ROM\_HibernateWakeGet (void)
- void ROM HibernateWakeSet (uint32 t ui32WakeFlags)

# 11.2.1 Function Documentation

## 11.2.1.1 ROM HibernateBatCheckDone

Returns if a forced battery check has completed.

# **Prototype:**

```
uint32_t
ROM_HibernateBatCheckDone(void)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].

ROM_HibernateBatCheckDone is a function pointer located at ROM HIBERNATETABLE[30].
```

# **Description:**

This function returns if the forced battery check initiated by a call to the HibernateBatCheck-Start() function has completed. This function will return a non-zero value until the battery level check has completed. Once this function returns a value of zero, the hibernation module has completed the battery check and the HibernateIntStatus() function can be used to check if the battery was low by checking if the value returned has the **HIBERNATE\_INT\_LOW\_BAT** set.

#### Returns:

The value is zero when the battery level check has completed or non-zero if the check is still in process.

# 11.2.1.2 ROM HibernateBatCheckStart

Forces the Hibernation module to initiate a check of the battery voltage.

### Prototype:

```
void
ROM_HibernateBatCheckStart(void)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.

ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].

ROM_HibernateBatCheckStart is a function pointer located at ROM HIBERNATETABLE[29].
```

#### **Description:**

This function forces the Hibernation module to initiate a check of the battery voltage immediately rather than waiting for the next check interval to pass. After calling this function, the application should call the () function and wait for the function to return a zero value before calling the HibernateIntStatus() to check if the return code has the HIBERNATE\_INT\_LOW\_BAT set. If HIBERNATE\_INT\_LOW\_BAT is set this indicates that battery level is low. The application can also enable the HIBERNATE\_INT\_LOW\_BAT interrupt and wait for an interrupt to indicate that the battery level is low.

#### Note:

A hibernation request is held off if a battery check is in progress.

### Returns:

None.

# 11.2.1.3 ROM HibernateClockConfig

Configures the clock input for the Hibernation module.

### Prototype:

void

ROM\_HibernateClockConfig(uint32\_t ui32Config)

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].

ROM_HibernateClockConfig is a function pointer located at ROM_HIBERNATETABLE[28].
```

#### Parameters:

ui32Config is one of the possible configuration options for the clock input listed below.

# **Description:**

This function is used to configure the clock input for the Hibernation module. The *ui32Config* parameter can be one of the following values:

- HIBERNATE\_OSC\_DISABLE specifies that the internal oscillator is powered off and either an externally supplied clock source or no clock source is being used.
- HIBERNATE\_OSC\_HIGHDRIVE specifies a higher drive strength when a 24pF filter capacitor is used with a crystal.
- HIBERNATE\_OSC\_LOWDRIVE specifies a lower drive strength when a 12pF filter capacitor is used with a crystal.

The **HIBERNATE\_OSC\_DISABLE** option is used to disable and power down the internal oscillator if an external clock source or no clock source is used instead of a 32.768 kHz crystal. In the case where an external crystal is used, either the **HIBERNATE\_OSC\_HIGHDRIVE** or **HIBERNATE\_OSC\_LOWDRIVE** is used. This optimizes the oscillator drive strength to match the size of the filter capacitor that is used with the external crystal circuit.

#### Returns:

None.

# 11.2.1.4 ROM HibernateDataGet

Reads a set of data from the non-volatile memory of the Hibernation module.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].

ROM_HibernateDataGet is a function pointer located at ROM_HIBERNATETABLE[19].
```

#### Parameters:

pui32Data points to a location where the data that is read from the Hibernation module will be stored.

ui32Count is the count of 32-bit words to read.

### **Description:**

Retrieves a set of data from the Hibernation module non-volatile memory that was previously stored with the ROM\_HibernateDataSet() function. The caller must ensure that *pui32Data* points to a large enough memory block to hold all the data that is read from the non-volatile memory.

#### Returns:

None.

# 11.2.1.5 ROM HibernateDataSet

Stores data in the non-volatile memory of the Hibernation module.

# Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].

ROM_HibernateDataSet is a function pointer located at ROM_HIBERNATETABLE[18].
```

#### **Parameters:**

**pui32Data** points to the data that the caller wants to store in the memory of the Hibernation module.

ui32Count is the count of 32-bit words to store.

### **Description:**

Stores a set of data in the Hibernation module non-volatile memory. This memory is preserved when the power to the processor is turned off, and can be used to store application state information which will be available when the processor wakes. Up to 64 32-bit words can be stored in the non-volatile memory. The data can be restored by calling the ROM\_HibernateDataGet() function.

#### Returns:

None.

# 11.2.1.6 ROM HibernateDisable

Disables the Hibernation module for operation.

### Prototype:

```
void
ROM_HibernateDisable(void)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].

ROM_HibernateDisable is a function pointer located at ROM_HIBERNATETABLE[2].
```

# **Description:**

Disables the Hibernation module for operation. After this function is called, none of the Hibernation module features are available.

#### Returns:

None.

# 11.2.1.7 ROM HibernateEnableExpClk

Enables the Hibernation module for operation.

# Prototype:

void

ROM\_HibernateEnableExpClk(uint32\_t ui32HibClk)

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].

ROM_HIBERNATETABLE[1].
```

#### Parameters:

*ui32HibClk* is the rate of the clock supplied to the Hibernation module.

# **Description:**

Enables the Hibernation module for operation. This function should be called before any of the Hibernation module features are used.

The peripheral clock is the same as the processor clock. This is the value returned by ROM\_SysCtlClockGet(), or it can be explicitly hard-coded if it is constant and known (to save the code/execution overhead of a call to ROM\_SysCtlClockGet()).

### Returns:

None.

# 11.2.1.8 ROM HibernateIntClear

Clears pending interrupts from the Hibernation module.

#### Prototype:

```
void
```

ROM\_HibernateIntClear(uint32\_t ui32IntFlags)

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.

ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].

ROM_HibernateIntClear is a function pointer located at ROM_HIBERNATETABLE[0].
```

#### Parameters:

ui32IntFlags is the bit mask of the interrupts to be cleared.

# **Description:**

Clears the specified interrupt sources. This must be done from within the interrupt handler or else the handler is called again upon exit.

The *ui32IntFlags* parameter has the same definition as the *ui32IntFlags* parameter to the ROM HibernateIntEnable() function.

#### Note:

Because there is a write buffer in the Cortex-M4 processor, it may take several clock cycles before the interrupt source is actually cleared. Therefore, it is recommended that the interrupt source be cleared early in the interrupt handler (as opposed to the very last action) to avoid returning from the interrupt handler before the interrupt source is actually cleared. Failure to do so may result in the interrupt handler being immediately reentered (because the interrupt controller still sees the interrupt source asserted).

#### Returns:

None.

# 11.2.1.9 ROM HibernateIntDisable

Disables interrupts for the Hibernation module.

# Prototype:

void

ROM\_HibernateIntDisable(uint32\_t ui32IntFlags)

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].

ROM_HibernateIntDisable is a function pointer located at ROM_HIBERNATETABLE[22].
```

### Parameters:

ui32IntFlags is the bit mask of the interrupts to be disabled.

#### Description:

Disables the specified interrupt sources from the Hibernation module.

The *ui32IntFlags* parameter has the same definition as the *ui32IntFlags* parameter to the ROM HibernateIntEnable() function.

#### Returns:

None.

# 11.2.1.10 ROM HibernateIntEnable

Enables interrupts for the Hibernation module.

# Prototype:

```
void
```

ROM\_HibernateIntEnable(uint32\_t ui32IntFlags)

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].

ROM_HibernateIntEnable is a function pointer located at ROM_HIBERNATETABLE[21].
```

#### Parameters:

ui32IntFlags is the bit mask of the interrupts to be enabled.

# **Description:**

Enables the specified interrupt sources from the Hibernation module.

The ui32IntFlags parameter must be the logical OR of any combination of the following:

- HIBERNATE\_INT\_PIN\_WAKE wake from pin interrupt
- HIBERNATE\_INT\_LOW\_BAT low battery interrupt
- HIBERNATE INT RTC MATCH 0 RTC match 0 interrupt
- HIBERNATE INT RTC MATCH 1 RTC match 1 interrupt

#### Returns:

None.

# 11.2.1.11 ROM HibernateIntStatus

Gets the current interrupt status of the Hibernation module.

#### Prototype:

```
uint32_t
ROM_HibernateIntStatus(bool bMasked)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].

ROM_HibernateIntStatus is a function pointer located at ROM_HIBERNATETABLE[23].
```

### Parameters:

**bMasked** is false to retrieve the raw interrupt status, and true to retrieve the masked interrupt status.

#### **Description:**

Returns the interrupt status of the Hibernation module. The caller can use this to determine the cause of a hibernation interrupt. Either the masked or raw interrupt status can be returned.

#### Returns:

Returns the interrupt status as a bit field with the values as described in the ROM\_HibernateIntEnable() function.

# 11.2.1.12 ROM\_HibernateIsActive

Checks to see if the Hibernation module is already powered up.

# Prototype:

```
uint32_t
ROM HibernateIsActive(void)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].
ROM_HibernateIsActive is a function pointer located at ROM_HIBERNATETABLE[24].
```

### **Description:**

This function queries the control register to determine if the module is already active. This function can be called at a power-on reset to help determine if the reset is due to a wake from hibernation or a cold start. If the Hibernation module is already active, then it does not need to be re-enabled and its status can be queried immediately.

The software application should also use the ROM\_HibernateIntStatus() function to read the raw interrupt status to determine the cause of the wake. The ROM\_HibernateDataGet() function can be used to restore state. These combinations of functions can be used by the software to determine if the processor is waking from hibernation and the appropriate action to take as a result.

#### Returns:

Returns **true** if the module is already active, and **false** if not.

# 11.2.1.13 ROM HibernateLowBatGet

Gets the currently configured low battery detection behavior.

### Prototype:

```
uint32_t
ROM_HibernateLowBatGet(void)
```

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].

ROM_HibernateLowBatGet is a function pointer located at ROM_HIBERNATETABLE[9].
```

# **Description:**

Returns a value representing the currently configured low battery detection behavior. The return value is one of the following:

- HIBERNATE\_LOW\_BAT\_DETECT detect a low battery condition.
- HIBERNATE\_LOW\_BAT\_ABORT detect a low battery condition, and abort hibernation if low battery is detected.

### Returns:

Returns a value indicating the configured low battery detection.

# 11.2.1.14 ROM HibernateLowBatSet

Configures the low battery detection.

# Prototype:

void

ROM\_HibernateLowBatSet(uint32\_t ui32LowBatFlags)

#### **ROM Location:**

ROM\_APITABLE is an array of pointers located at  $0 \times 0100.0010$ . ROM\_HIBERNATETABLE is an array of pointers located at ROM\_APITABLE[19]. ROM\_HibernateLowBatSet is a function pointer located at ROM\_HIBERNATETABLE[8].

#### Parameters:

ui32LowBatFlags specifies behavior of low battery detection.

#### Description:

Enables the low battery detection and whether hibernation is allowed if a low battery is detected. If low battery detection is enabled, then a low battery condition is indicated in the raw interrupt status register, and can also trigger an interrupt. Optionally, hibernation can be aborted if a low battery is detected.

The ui32LowBatFlags parameter is one of the following values:

- HIBERNATE\_LOW\_BAT\_DETECT detect a low battery condition.
- HIBERNATE\_LOW\_BAT\_ABORT detect a low battery condition, and abort hibernation if low battery is detected.

#### Returns:

None.

# 11.2.1.15 ROM HibernateRequest

Requests hibernation mode.

### Prototype:

void

ROM\_HibernateRequest(void)

#### **ROM Location:**

ROM\_APITABLE is an array of pointers located at  $0 \times 0100.0010$ . ROM\_HIBERNATETABLE is an array of pointers located at ROM\_APITABLE [19].

ROM\_HibernateRequest is a function pointer located at ROM\_HIBERNATETABLE [20].

### **Description:**

This function requests the Hibernation module to disable the external regulator, thus removing power from the processor and all peripherals. The Hibernation module will remain powered from the battery or auxiliary power supply.

The Hibernation module will re-enable the external regulator when one of the configured wake conditions occurs (such as RTC match or external **WAKE** pin). When the power is restored the processor will go through a normal power-on reset. The processor can retrieve saved state information with the ROM\_HibernateDataGet() function. Prior to calling the function to request hibernation mode, the conditions for waking must have already been set by using the ROM\_HibernateWakeSet() function.

Note that this function may return because some time may elapse before the power is actually removed, or it may not be removed at all. For this reason, the processor will continue

to execute instructions for some time and the caller should be prepared for this function to return. There are various reasons why the power may not be removed. For example, if the ROM\_HibernateLowBatSet() function was used to configure an abort if low battery is detected, then the power will not be removed if the battery voltage is too low. There may be other reasons, related to the external circuit design, that a request for hibernation may not actually occur.

For all these reasons, the caller must be prepared for this function to return. The simplest way to handle it is to just enter an infinite loop and wait for the power to be removed.

#### Returns:

None.

# 11.2.1.16 ROM HibernateRTCDisable

Disables the RTC feature of the Hibernation module.

### Prototype:

void

ROM HibernateRTCDisable (void)

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].

ROM_HibernateRTCDisable is a function pointer located at ROM_HIBERNATETABLE[5].
```

### **Description:**

Disables the RTC in the Hibernation module. After calling this function the RTC features of the Hibernation module will not be available.

#### Returns:

None.

# 11.2.1.17 ROM HibernateRTCEnable

Enables the RTC feature of the Hibernation module.

### Prototype:

```
void
```

ROM\_HibernateRTCEnable(void)

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].

ROM HibernateRTCEnable is a function pointer located at ROM HIBERNATETABLE[4].
```

### **Description:**

Enables the RTC in the Hibernation module. The RTC can be used to wake the processor from hibernation at a certain time, or to generate interrupts at certain times. This function must be called before using any of the RTC features of the Hibernation module.

#### Returns:

None.

# 11.2.1.18 ROM HibernateRTCGet

Gets the value of the real time clock (RTC) counter.

### Prototype:

```
uint32_t
ROM_HibernateRTCGet(void)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].

ROM_HibernateRTCGet is a function pointer located at ROM_HIBERNATETABLE[11].
```

### **Description:**

Gets the value of the RTC and returns it to the caller.

#### Returns:

Returns the value of the RTC.

# 11.2.1.19 ROM HibernateRTCSet

Sets the value of the real time clock (RTC) counter.

# Prototype:

```
void
ROM_HibernateRTCSet(uint32_t ui32RTCValue)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].

ROM_HibernateRTCSet is a function pointer located at ROM_HIBERNATETABLE[10].
```

#### Parameters:

ui32RTCValue is the new value for the RTC.

# **Description:**

Sets the value of the RTC. The RTC will count seconds if the hardware is configured correctly. The RTC must be enabled by calling ROM\_HibernateRTCEnable() before calling this function.

### Returns:

None.

# 11.2.1.20 ROM HibernateRTCSSGet

Returns the current value of the RTC sub second count.

### Prototype:

```
uint32_t
ROM_HibernateRTCSSGet(void)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].

ROM_HibernateRTCSSGet is a function pointer located at ROM_HIBERNATETABLE[27].
```

### **Description:**

This function will return the current value of the sub second count for the for the RTC in 1/32768 of a second increments.

#### Returns:

The current RTC sub second count in 1/32768 seconds.

# 11.2.1.21 ROM HibernateRTCTrimGet

Gets the value of the RTC predivider trim register.

# Prototype:

```
uint32_t
ROM_HibernateRTCTrimGet(void)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].

ROM HibernateRTCTrimGet is a function pointer located at ROM HIBERNATETABLE[17].
```

#### **Description:**

Gets the value of the pre-divider trim register. This function can be used to get the current value of the trim register prior to making an adjustment by using the ROM\_HibernateRTCTrimSet() function.

### Returns:

None.

# 11.2.1.22 ROM HibernateRTCTrimSet

Sets the value of the RTC predivider trim register.

### Prototype:

```
void
ROM HibernateRTCTrimSet(uint32 t ui32Trim)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].

ROM_HibernateRTCTrimSet is a function pointer located at ROM_HIBERNATETABLE[16].
```

# Parameters:

ui32Trim is the new value for the pre-divider trim register.

# **Description:**

Sets the value of the pre-divider trim register. The input time source is divided by the predivider to achieve a one-second clock rate. Once every 64 seconds, the value of the pre-divider

trim register is applied to the predivider to allow fine-tuning of the RTC rate, in order to make corrections to the rate. The software application can make adjustments to the predivider trim register to account for variations in the accuracy of the input time source. The nominal value is 0x7FFF, and it can be adjusted up or down in order to fine-tune the RTC rate.

### Returns:

None.

# 11.2.1.23 ROM\_HibernateWakeGet

Gets the currently configured wake conditions for the Hibernation module.

### Prototype:

```
uint32_t
ROM_HibernateWakeGet(void)
```

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].

ROM_HIBERNATETABLE[19].
```

#### **Description:**

Returns the flags representing the wake configuration for the Hibernation module. The return value is a combination of the following flags:

- HIBERNATE WAKE PIN wake when the external wake pin is asserted.
- HIBERNATE\_WAKE\_RTC wake when one of the RTC matches occurs.

### Returns:

Returns flags indicating the configured wake conditions.

# 11.2.1.24 ROM HibernateWakeSet

Configures the wake conditions for the Hibernation module.

### Prototype:

```
void
ROM_HibernateWakeSet(uint32_t ui32WakeFlags)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_HIBERNATETABLE is an array of pointers located at ROM_APITABLE[19].

ROM_HibernateWakeSet is a function pointer located at ROM_HIBERNATETABLE[6].
```

#### Parameters:

ui32WakeFlags specifies which conditions should be used for waking.

# **Description:**

Enables the conditions under which the Hibernation module will wake. The *ui32WakeFlags* parameter is the logical OR of any combination of the following:

- HIBERNATE\_WAKE\_PIN wake when the external wake pin is asserted.
- HIBERNATE\_WAKE\_RTC wake when one of the RTC matches occurs.

# Returns:

None.

# 12 Inter-Integrated Circuit (I2C)

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# 12.1 Introduction

The Inter-Integrated Circuit (I2C) API provides a set of functions for using the I2C master and slave modules. Functions are provided to initialize the I2C modules, to send and receive data, obtain status, and to manage interrupts for the I2C modules.

The I2C master and slave modules provide the ability to communicate to other IC devices over an I2C bus. The I2C bus is specified to support devices that can both transmit and receive (write and read) data. Also, devices on the I2C bus can be designated as either a master or a slave. The I2C modules support both sending and receiving data as either a master or a slave, and also support the simultaneous operation as both a master and a slave. Finally, the I2C modules can operate at two speeds: Standard (100 kb/s) and Fast (400 kb/s).

Both the master and slave I2C modules can generate interrupts. The I2C master module will generate interrupts when a transmit or receive operation is completed (or aborted due to an error). The I2C slave module will generate interrupts when data has been sent or requested by a master.

# 12.1.1 Master Operations

When using this API to drive the I2C master module, the user must first initialize the I2C master module with a call to ROM\_I2CMasterInitExpClk(). That function will set the bus speed and enable the master module.

The user may transmit or receive data after the successful initialization of the I2C master module. Data is transferred by first setting the slave address using ROM\_I2CMasterSlaveAddrSet(). That function is also used to define whether the transfer is a send (a write to the slave from the master) or a receive (a read from the slave by the master). Then, if connected to an I2C bus that has multiple masters, the I2C master must first call ROM\_I2CMasterBusBusy() before attempting to initiate the desired transaction. After determining that the bus is not busy, if trying to send data, the user must call the ROM\_I2CMasterDataPut() function. The transaction can then be initiated on the bus by calling the ROM\_I2CMasterControl() function with any of the following commands:

- I2C\_MASTER\_CMD\_SINGLE\_SEND
- I2C\_MASTER\_CMD\_SINGLE\_RECEIVE
- I2C MASTER CMD BURST SEND START
- I2C MASTER CMD BURST RECEIVE START

Any of those commands will result in the master arbitrating for the bus, driving the start sequence onto the bus, and sending the slave address and direction bit across the bus. The remainder of the transaction can then be driven using either a polling or interrupt-driven method.

For the single send and receive cases, the polling method will involve looping on the return from ROM\_I2CMasterBusy(). Once that function indicates that the I2C master is no longer busy, the bus transaction has been completed and can be checked for errors

using ROM\_I2CMasterErr(). If there are no errors, then the data has been sent or is ready to be read using ROM\_I2CMasterDataGet(). For the burst send and receive cases, the polling method also involves calling the ROM\_I2CMasterControl() function for each byte transmitted or received (using either the I2C\_MASTER\_CMD\_BURST\_SEND\_CONT or I2C\_MASTER\_CMD\_BURST\_RECEIVE\_CONT commands), and for the last byte sent or received (using either the I2C\_MASTER\_CMD\_BURST\_SEND\_FINISH or I2C\_MASTER\_CMD\_BURST\_RECEIVE\_FINISH commands). If any error is detected during the burst transfer, the ROM\_I2CMasterControl() function should be called using the appropriate stop command (I2C\_MASTER\_CMD\_BURST\_SEND\_ERROR\_STOP).

For the interrupt-driven transaction, the user must register an interrupt handler for the I2C devices and enable the I2C master interrupt; the interrupt will occur when the master is no longer busy.

# 12.2 Functions

# **Functions**

- bool ROM I2CMasterBusBusy (uint32 t ui32Base)
- bool ROM\_I2CMasterBusy (uint32\_t ui32Base)
- void ROM\_I2CMasterControl (uint32\_t ui32Base, uint32\_t ui32Cmd)
- uint32 t ROM I2CMasterDataGet (uint32 t ui32Base)
- void ROM I2CMasterDataPut (uint32 t ui32Base, uint8 t ui8Data)
- void ROM\_I2CMasterDisable (uint32\_t ui32Base)
- void ROM I2CMasterEnable (uint32 t ui32Base)
- uint32\_t ROM\_I2CMasterErr (uint32\_t ui32Base)
- void ROM\_I2CMasterInitExpClk (uint32\_t ui32Base, uint32\_t ui32I2CClk, bool bFast)
- void ROM\_I2CMasterIntClear (uint32\_t ui32Base)
- void ROM I2CMasterIntClearEx (uint32 t ui32Base, uint32 t ui32IntFlags)
- void ROM\_I2CMasterIntDisable (uint32\_t ui32Base)
- void ROM\_I2CMasterIntDisableEx (uint32\_t ui32Base, uint32\_t ui32IntFlags)
- void ROM\_I2CMasterIntEnable (uint32\_t ui32Base)
- void ROM I2CMasterIntEnableEx (uint32 t ui32Base, uint32 t ui32IntFlags)
- bool ROM\_I2CMasterIntStatus (uint32\_t ui32Base, bool bMasked)
- uint32 t ROM I2CMasterIntStatusEx (uint32 t ui32Base, bool bMasked)
- uint32 t ROM I2CMasterLineStateGet (uint32 t ui32Base)
- void ROM\_I2CMasterSlaveAddrSet (uint32\_t ui32Base, uint8\_t ui8SlaveAddr, bool bReceive)
- void ROM I2CMasterTimeoutSet (uint32 t ui32Base, uint32 t ui32Value)
- void ROM Updatel2C (void)

# 12.2.1 Function Documentation

# 12.2.1.1 ROM I2CMasterBusBusy

Indicates whether or not the I2C bus is busy.

# Prototype:

```
bool
```

ROM\_I2CMasterBusBusy(uint32\_t ui32Base)

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_I2CTABLE is an array of pointers located at ROM_APITABLE[3].

ROM_I2CMasterBusBusy is a function pointer located at ROM_I2CTABLE[17].
```

### Parameters:

ui32Base is the base address of the I2C Master module.

### Description:

This function returns an indication of whether or not the I2C bus is busy. This function can be used in a multi-master environment to determine if another master is currently using the bus.

# Returns:

Returns true if the I2C bus is busy; otherwise, returns false.

# 12.2.1.2 ROM I2CMasterBusy

Indicates whether or not the I2C Master is busy.

# Prototype:

```
bool
ROM I2CMasterBusy(uint32 t ui32Base)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_I2CTABLE is an array of pointers located at ROM_APITABLE[3].

ROM_I2CMasterBusy is a function pointer located at ROM_I2CTABLE[16].
```

### Parameters:

ui32Base is the base address of the I2C Master module.

# **Description:**

This function returns an indication of whether or not the I2C Master is busy transmitting or receiving data.

#### Returns:

Returns true if the I2C Master is busy; otherwise, returns false.

# 12.2.1.3 ROM I2CMasterControl

Controls the state of the I2C Master module.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_I2CTABLE is an array of pointers located at ROM_APITABLE[3].

ROM_I2CMasterControl is a function pointer located at ROM_I2CTABLE[18].
```

#### Parameters:

ui32Base is the base address of the I2C Master module.
ui32Cmd command to be issued to the I2C Master module

### **Description:**

This function is used to control the state of the Master module send and receive operations. The *ui8Cmd* parameter can be one of the following values:

- I2C\_MASTER\_CMD\_SINGLE\_SEND
- I2C\_MASTER\_CMD\_SINGLE\_RECEIVE
- I2C MASTER CMD BURST SEND START
- I2C\_MASTER\_CMD\_BURST\_SEND\_CONT
- I2C MASTER CMD BURST SEND FINISH
- I2C MASTER CMD BURST SEND ERROR STOP
- I2C MASTER CMD BURST RECEIVE START
- I2C MASTER CMD BURST RECEIVE CONT
- I2C MASTER CMD BURST RECEIVE FINISH
- I2C\_MASTER\_CMD\_BURST\_RECEIVE\_ERROR\_STOP

#### Returns:

None.

# 12.2.1.4 ROM I2CMasterDataGet

Receives a byte that has been sent to the I2C Master.

### Prototype:

```
uint32_t
ROM_I2CMasterDataGet(uint32_t ui32Base)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_I2CTABLE is an array of pointers located at ROM_APITABLE[3].
ROM_I2CMasterDataGet is a function pointer located at ROM_I2CTABLE[20].
```

# Parameters:

ui32Base is the base address of the I2C Master module.

#### Description:

This function reads a byte of data from the I2C Master Data Register.

# Returns:

Returns the byte received from by the I2C Master, cast as an uint32 t.

# 12.2.1.5 ROM I2CMasterDataPut

Transmits a byte from the I2C Master.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_I2CTABLE is an array of pointers located at ROM_APITABLE[3].

ROM_I2CMasterDataPut is a function pointer located at ROM_I2CTABLE[0].
```

### Parameters:

ui32Base is the base address of the I2C Master module.
ui8Data data to be transmitted from the I2C Master

### **Description:**

This function will place the supplied data into I2C Master Data Register.

#### Returns:

None.

# 12.2.1.6 ROM I2CMasterDisable

Disables the I2C master block.

## Prototype:

```
void
ROM_I2CMasterDisable(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_I2CTABLE is an array of pointers located at ROM_APITABLE[3].

ROM_I2CMasterDisable is a function pointer located at ROM_I2CTABLE[5].
```

### Parameters:

ui32Base is the base address of the I2C Master module.

# **Description:**

This will disable operation of the I2C master block.

### Returns:

None.

# 12.2.1.7 ROM I2CMasterEnable

Enables the I2C Master block.

# Prototype:

void

ROM\_I2CMasterEnable(uint32\_t ui32Base)

### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_I2CTABLE is an array of pointers located at ROM\_APITABLE[3].

ROM\_I2CMasterEnable is a function pointer located at ROM\_I2CTABLE[3].

#### Parameters:

ui32Base is the base address of the I2C Master module.

#### **Description:**

This will enable operation of the I2C Master block.

### Returns:

None.

# 12.2.1.8 ROM\_I2CMasterErr

Gets the error status of the I2C Master module.

### Prototype:

```
uint32_t
ROM_I2CMasterErr(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_I2CTABLE is an array of pointers located at ROM_APITABLE[3].

ROM_I2CMasterErr is a function pointer located at ROM_I2CTABLE[19].
```

### Parameters:

ui32Base is the base address of the I2C Master module.

#### **Description:**

This function is used to obtain the error status of the Master module send and receive operations.

#### Returns:

```
Returns the error status, as one of I2C_MASTER_ERR_NONE, I2C_MASTER_ERR_ADDR_ACK, I2C_MASTER_ERR_DATA_ACK, or I2C_MASTER_ERR_ARB_LOST.
```

# 12.2.1.9 ROM\_I2CMasterInitExpClk

Initializes the I2C Master block.

#### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_I2CTABLE is an array of pointers located at ROM_APITABLE[3].

ROM_I2CMasterInitExpClk is a function pointer located at ROM_I2CTABLE[1].
```

#### Parameters:

ui32Base is the base address of the I2C Master module.ui32I2CCIk is the rate of the clock supplied to the I2C module.bFast set up for fast data transfers

# **Description:**

This function initializes operation of the I2C Master block. Upon successful initialization of the I2C block, this function will have set the bus speed for the master, and will have enabled the I2C Master block.

If the parameter *bFast* is **true**, then the master block is set up to transfer data at 400 kbps; otherwise, it is set up to transfer data at 100 kbps.

The peripheral clock is the same as the processor clock. This is the value returned by ROM\_SysCtlClockGet(), or it can be explicitly hard-coded if it is constant and known (to save the code/execution overhead of a call to ROM\_SysCtlClockGet()).

#### Returns:

None.

# 12.2.1.10 ROM I2CMasterIntClear

Clears I2C Master interrupt sources.

### Prototype:

```
void
ROM_I2CMasterIntClear(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_I2CTABLE is an array of pointers located at ROM_APITABLE[3].

ROM_I2CMasterIntClear is a function pointer located at ROM_I2CTABLE[13].
```

#### Parameters:

ui32Base is the base address of the I2C Master module.

#### **Description:**

The I2C Master interrupt source is cleared, so that it no longer asserts. This must be done in the interrupt handler to keep it from being called again immediately upon exit.

### Note:

Because there is a write buffer in the Cortex-M4 processor, it may take several clock cycles before the interrupt source is actually cleared. Therefore, it is recommended that the interrupt source be cleared early in the interrupt handler (as opposed to the very last action) to avoid returning from the interrupt handler before the interrupt source is actually cleared. Failure to do so may result in the interrupt handler being immediately reentered (because the interrupt controller still sees the interrupt source asserted).

#### Returns:

None.

# 12.2.1.11 ROM I2CMasterIntClearEx

Clears I2C Master interrupt sources.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_I2CTABLE is an array of pointers located at ROM_APITABLE[3].

ROM_I2CMasterIntClearEx is a function pointer located at ROM_I2CTABLE[32].
```

#### Parameters:

ui32Base is the base address of the I2C Master module.ui32IntFlags is a bit mask of the interrupt sources to be cleared.

### **Description:**

The specified I2C Master interrupt sources are cleared, so that they no longer assert. This must be done in the interrupt handler to keep it from being called again immediately upon exit.

The *ui32IntFlags* parameter has the same definition as the *ui32IntFlags* parameter to I2CMasterIntEnableEx().

### Note:

Because there is a write buffer in the Cortex-M4 processor, it may take several clock cycles before the interrupt source is actually cleared. Therefore, it is recommended that the interrupt source be cleared early in the interrupt handler (as opposed to the very last action) to avoid returning from the interrupt handler before the interrupt source is actually cleared. Failure to do so may result in the interrupt handler being immediately reentered (because the interrupt controller still sees the interrupt source asserted).

#### Returns:

None.

# 12.2.1.12 ROM I2CMasterIntDisable

Disables the I2C Master interrupt.

# Prototype:

```
void
ROM I2CMasterIntDisable(uint32 t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_I2CTABLE is an array of pointers located at ROM_APITABLE[3].

ROM_I2CMasterIntDisable is a function pointer located at ROM_I2CTABLE[9].
```

## Parameters:

ui32Base is the base address of the I2C Master module.

### **Description:**

Disables the I2C Master interrupt source.

### Returns:

None.

# 12.2.1.13 ROM I2CMasterIntDisableEx

Disables individual I2C Master interrupt sources.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_I2CTABLE is an array of pointers located at ROM_APITABLE[3].

ROM_I2CMasterIntDisableEx is a function pointer located at ROM_I2CTABLE[30].
```

#### Parameters:

ui32Base is the base address of the I2C Master module.
ui32IntFlags is the bit mask of the interrupt sources to be disabled.

#### **Description:**

Disables the indicated I2C Master interrupt sources. Only the sources that are enabled can be reflected to the processor interrupt; disabled sources have no effect on the processor.

The *ui32IntFlags* parameter has the same definition as the *ui32IntFlags* parameter to I2CMasterIntEnableEx().

#### Returns:

None.

# 12.2.1.14 ROM I2CMasterIntEnable

Enables the I2C Master interrupt.

### Prototype:

```
void
ROM_I2CMasterIntEnable(uint32_t ui32Base)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_I2CTABLE is an array of pointers located at ROM_APITABLE[3].

ROM_I2CMasterIntEnable is a function pointer located at ROM_I2CTABLE[7].
```

### Parameters:

ui32Base is the base address of the I2C Master module.

#### **Description:**

Enables the I2C Master interrupt source.

### Returns:

None.

# 12.2.1.15 ROM I2CMasterIntEnableEx

Enables individual I2C Master interrupt sources.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_I2CTABLE is an array of pointers located at ROM_APITABLE[3].

ROM_I2CMasterIntEnableEx is a function pointer located at ROM_I2CTABLE[29].
```

#### Parameters:

ui32Base is the base address of the I2C Master module.
ui32IntFlags is the bit mask of the interrupt sources to be enabled.

### **Description:**

Enables the indicated I2C Master interrupt sources. Only the sources that are enabled can be reflected to the processor interrupt; disabled sources have no effect on the processor.

The *ui32IntFlags* parameter is the logical OR of any of the following:

- I2C\_MASTER\_INT\_TIMEOUT Clock Timeout interrupt
- I2C\_MASTER\_INT\_DATA Data interrupt

#### Returns:

None.

# 12.2.1.16 ROM\_I2CMasterIntStatus

Gets the current I2C Master interrupt status.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_I2CTABLE is an array of pointers located at ROM_APITABLE[3].

ROM_I2CMasterIntStatus is a function pointer located at ROM_I2CTABLE[11].
```

#### Parameters:

ui32Base is the base address of the I2C Master module.

**bMasked** is false if the raw interrupt status is requested and true if the masked interrupt status is requested.

### **Description:**

This returns the interrupt status for the I2C Master module. Either the raw interrupt status or the status of interrupts that are allowed to reflect to the processor can be returned.

#### Returns:

The current interrupt status, returned as **true** if active or **false** if not active.

# 12.2.1.17 ROM I2CMasterIntStatusEx

Gets the current I2C Master interrupt status.

# Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_I2CTABLE is an array of pointers located at ROM_APITABLE[3].

ROM_I2CMasterIntStatusEx is a function pointer located at ROM_I2CTABLE[31].
```

#### Parameters:

ui32Base is the base address of the I2C Master module.

**bMasked** is false if the raw interrupt status is requested and true if the masked interrupt status is requested.

# **Description:**

This returns the interrupt status for the I2C Master module. Either the raw interrupt status or the status of interrupts that are allowed to reflect to the processor can be returned.

# Returns:

Returns the current interrupt status, enumerated as a bit field of values described in I2CMasterIntEnableEx().

# 12.2.1.18 ROM I2CMasterLineStateGet

Reads the state of the SDA and SCL pins.

### Prototype:

```
uint32_t
ROM_I2CMasterLineStateGet(uint32_t ui32Base)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_I2CTABLE is an array of pointers located at ROM_APITABLE[3].

ROM_I2CMasterLineStateGet is a function pointer located at ROM_I2CTABLE[38].
```

# Parameters:

ui32Base is the base address of the I2C Master module.

#### **Description:**

This function returns the state of the I2C bus by providing the real time values of the SDA and SCL pins.

#### Returns:

Returns the state of the bus with SDA in bit position 1 and SCL in bit position 0.

# 12.2.1.19 ROM I2CMasterSlaveAddrSet

Sets the address that the I2C Master will place on the bus.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_I2CTABLE is an array of pointers located at ROM_APITABLE[3].

ROM_I2CMasterSlaveAddrSet is a function pointer located at ROM_I2CTABLE[15].
```

#### Parameters:

ui32Base is the base address of the I2C Master module.

ui8SlaveAddr 7-bit slave address

**bReceive** flag indicating the type of communication with the slave

### **Description:**

This function will set the address that the I2C Master will place on the bus when initiating a transaction. When the *bReceive* parameter is set to **true**, the address will indicate that the I2C Master is initiating a read from the slave; otherwise the address will indicate that the I2C Master is initiating a write to the slave.

#### Returns:

None.

# 12.2.1.20 ROM I2CMasterTimeoutSet

Sets the Master clock timeout value.

# Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_I2CTABLE is an array of pointers located at ROM_APITABLE[3].

ROM_I2CMasterTimeoutSet is a function pointer located at ROM_I2CTABLE[33].
```

#### Parameters:

ui32Base is the base address of the I2C Master module.ui32Value is the number of I2C clocks before the timeout is asserted.

# Description:

This function enables and configures the clock low timeout feature in the I2C peripheral. This feature is implemented as a 12-bit counter, with the upper 8-bits being programmable. For example, to program a timeout of 20ms with a 100kHz SCL frequency, *ui32Value* would be 0x7d.

# Returns:

None.

# 12.2.1.21 ROM\_UpdateI2C

Starts an update over the I2C0 interface.

# Prototype:

void
ROM\_UpdateI2C(void)

# **ROM Location:**

ROM\_APITABLE is an array of pointers located at  $0 \times 0100.0010$ . ROM\_I2CTABLE is an array of pointers located at ROM\_APITABLE[3]. ROM\_UpdateI2C is a function pointer located at ROM\_I2CTABLE[24].

# **Description:**

Calling this function commences an update of the firmware via the I2C0 interface. This function assumes that the I2C0 interface has already been configured and is currently operational. The I2C0 slave is used for data transfer, and the I2C0 master is used to monitor bus busy conditions (therefore, both must be enabled).

#### Returns:

Never returns.

# 13 Interrupt Controller (NVIC)

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# 13.1 Introduction

The interrupt controller API provides a set of functions for dealing with the Nested Vectored Interrupt Controller (NVIC). Functions are provided to enable and disable interrupts, register interrupt handlers, and set the priority of interrupts.

The NVIC provides global interrupt masking, prioritization, and handler dispatching. Thirty-two interrupt sources and eight priority levels are supported. Individual interrupt sources can be masked, and the processor interrupt can be globally masked as well (without affecting the individual source masks).

The NVIC is tightly coupled with the Cortex-M4 microprocessor. When the processor responds to an interrupt, NVIC will supply the address of the function to handle the interrupt directly to the processor. This eliminates the need for a global interrupt handler that queries the interrupt controller to determine the cause of the interrupt and branch to the appropriate handler, reducing interrupt response time.

The interrupt prioritization in the NVIC allows higher priority interrupts to be handled before lower priority interrupts, as well as allowing preemption of lower priority interrupt handlers by higher priority interrupts. Again, this helps reduce interrupt response time (for example, a 1 ms system control interrupt is not held off by the execution of a lower priority 1 second housekeeping interrupt handler).

Sub-prioritization is also possible; instead of having N bits of preemptable prioritization, NVIC can be configured (via software) for N - M bits of preemptable prioritization and M bits of subpriority. In this scheme, two interrupts with the same preemptable prioritization but different subpriorities will not cause a preemption; tail chaining will instead be used to process the two interrupts back-to-back.

If two interrupts with the same priority (and subpriority if so configured) are asserted at the same time, the one with the lower interrupt number will be processed first. NVIC keeps track of the nesting of interrupt handlers, allowing the processor to return from interrupt context only once all nested and pending interrupts have been handled.

# 13.2 Functions

# **Functions**

- void ROM IntDisable (uint32 t ui32Interrupt)
- void ROM IntEnable (uint32 t ui32Interrupt)
- uint32 t ROM IntlsEnabled (uint32 t ui32Interrupt)
- bool ROM\_IntMasterDisable (void)
- bool ROM IntMasterEnable (void)
- void ROM IntPendClear (uint32 t ui32Interrupt)

- void ROM IntPendSet (uint32 t ui32Interrupt)
- int32\_t ROM\_IntPriorityGet (uint32\_t ui32Interrupt)
- uint32 t ROM IntPriorityGroupingGet (void)
- void ROM\_IntPriorityGroupingSet (uint32\_t ui32Bits)
- uint32 t ROM IntPriorityMaskGet (void)
- void ROM IntPriorityMaskSet (uint32 t ui32PriorityMask)
- void ROM\_IntPrioritySet (uint32\_t ui32Interrupt, uint8\_t ui8Priority)

# 13.2.1 Function Documentation

# 13.2.1.1 ROM\_IntDisable

Disables an interrupt.

# Prototype:

```
void
ROM_IntDisable(uint32_t ui32Interrupt)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_INTERRUPTTABLE is an array of pointers located at ROM_APITABLE[14].

ROM_IntDisable is a function pointer located at ROM_INTERRUPTTABLE[3].
```

#### Parameters:

ui32Interrupt specifies the interrupt to be disabled.

### **Description:**

The specified interrupt is disabled in the interrupt controller. Other enables for the interrupt (such as at the peripheral level) are unaffected by this function.

#### Returns:

None.

# 13.2.1.2 ROM IntEnable

Enables an interrupt.

### Prototype:

```
void
ROM_IntEnable(uint32_t ui32Interrupt)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_INTERRUPTTABLE is an array of pointers located at ROM_APITABLE[14].

ROM_INTERABLE is a function pointer located at ROM_INTERRUPTTABLE[0].
```

### Parameters:

ui32Interrupt specifies the interrupt to be enabled.

# **Description:**

The specified interrupt is enabled in the interrupt controller. Other enables for the interrupt (such as at the peripheral level) are unaffected by this function.

#### Returns:

None.

# 13.2.1.3 ROM\_IntlsEnabled

Returns if a peripheral interrupt is enabled.

# Prototype:

```
uint32_t
ROM_IntIsEnabled(uint32_t ui32Interrupt)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_INTERRUPTTABLE is an array of pointers located at ROM_APITABLE[14].

ROM_IntIsEnabled is a function pointer located at ROM_INTERRUPTTABLE[12].
```

#### Parameters:

ui32Interrupt specifies the interrupt to check.

# **Description:**

This function checks if the specified interrupt is enabled in the interrupt controller.

# Returns:

A non-zero value if the interrupt is enabled.

# 13.2.1.4 ROM IntMasterDisable

Disables the processor interrupt.

### Prototype:

```
bool
ROM_IntMasterDisable(void)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_INTERRUPTTABLE is an array of pointers located at ROM_APITABLE[14].
ROM_IntMasterDisable is a function pointer located at ROM_INTERRUPTTABLE[2].
```

### **Description:**

Prevents the processor from receiving interrupts. This does not affect the set of interrupts enabled in the interrupt controller; it just gates the single interrupt from the controller to the processor.

#### Returns:

Returns **true** if interrupts were already disabled when the function was called or **false** if they were initially enabled.

# 13.2.1.5 ROM IntMasterEnable

Enables the processor interrupt.

# Prototype:

```
bool
ROM_IntMasterEnable(void)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_INTERRUPTTABLE is an array of pointers located at ROM_APITABLE[14].

ROM_IntMasterEnable is a function pointer located at ROM_INTERRUPTTABLE[1].
```

# **Description:**

Allows the processor to respond to interrupts. This does not affect the set of interrupts enabled in the interrupt controller; it just gates the single interrupt from the controller to the processor.

#### Returns:

Returns **true** if interrupts were disabled when the function was called or **false** if they were initially enabled.

# 13.2.1.6 ROM IntPendClear

Unpends an interrupt.

## Prototype:

```
void
ROM_IntPendClear(uint32_t ui32Interrupt)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_INTERRUPTTABLE is an array of pointers located at ROM_APITABLE[14].

ROM_IntPendClear is a function pointer located at ROM_INTERRUPTTABLE[9].
```

#### Parameters:

ui32Interrupt specifies the interrupt to be unpended.

#### **Description:**

The specified interrupt is unpended in the interrupt controller. This will cause any previously generated interrupts that have not been handled yet (due to higher priority interrupts or the interrupt no having been enabled yet) to be discarded.

# Returns:

None.

# 13.2.1.7 ROM IntPendSet

Pends an interrupt.

# Prototype:

```
void
ROM_IntPendSet(uint32_t ui32Interrupt)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_INTERRUPTTABLE is an array of pointers located at ROM_APITABLE[14].

ROM_IntPendSet is a function pointer located at ROM_INTERRUPTTABLE[8].
```

#### Parameters:

ui32Interrupt specifies the interrupt to be pended.

### **Description:**

The specified interrupt is pended in the interrupt controller. This will cause the interrupt controller to execute the corresponding interrupt handler at the next available time, based on the current interrupt state priorities. For example, if called by a higher priority interrupt handler, the specified interrupt handler will not be called until after the current interrupt handler has completed execution. The interrupt must have been enabled for it to be called.

#### Returns:

None.

# 13.2.1.8 ROM IntPriorityGet

Gets the priority of an interrupt.

### Prototype:

```
int32_t
ROM_IntPriorityGet(uint32_t ui32Interrupt)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_INTERRUPTTABLE is an array of pointers located at ROM_APITABLE[14].

ROM_IntPriorityGet is a function pointer located at ROM_INTERRUPTTABLE[7].
```

### Parameters:

ui32Interrupt specifies the interrupt in question.

### **Description:**

This function gets the priority of an interrupt. See ROM\_IntPrioritySet() for a definition of the priority value.

#### Returns:

Returns the interrupt priority, or -1 if an invalid interrupt was specified.

# 13.2.1.9 ROM\_IntPriorityGroupingGet

Gets the priority grouping of the interrupt controller.

### Prototype:

```
uint32_t
ROM_IntPriorityGroupingGet(void)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_INTERRUPTTABLE is an array of pointers located at ROM_APITABLE[14].

ROM_IntPriorityGroupingGet is a function pointer located at ROM_INTERRUPTTABLE[5].
```

#### **Description:**

This function returns the split between preemptable priority levels and subpriority levels in the interrupt priority specification.

#### Returns:

The number of bits of preemptable priority.

# 13.2.1.10 ROM IntPriorityGroupingSet

Sets the priority grouping of the interrupt controller.

# Prototype:

```
void
ROM_IntPriorityGroupingSet(uint32_t ui32Bits)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.

ROM_INTERRUPTTABLE is an array of pointers located at ROM_APITABLE[14].

ROM_IntPriorityGroupingSet is a function pointer located at ROM_INTERRUPTTABLE[4].
```

### Parameters:

ui32Bits specifies the number of bits of preemptable priority.

### **Description:**

This function specifies the split between preemptable priority levels and subpriority levels in the interrupt priority specification. The range of the grouping values are dependent upon the hardware implementation; three bits are available for hardware interrupt prioritization and therefore priority grouping values of three through seven have the same effect.

#### Returns:

None.

# 13.2.1.11 ROM IntPriorityMaskGet

Gets the priority masking level

# Prototype:

```
uint32_t
ROM_IntPriorityMaskGet(void)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_INTERRUPTTABLE is an array of pointers located at ROM_APITABLE[14].

ROM_IntPriorityMaskGet is a function pointer located at ROM_INTERRUPTTABLE[11].
```

# **Description:**

This function gets the current setting of the interrupt priority masking level. The value returned is the priority level such that all interrupts of that and lesser priority are masked. A value of 0 means that priority masking is disabled.

Smaller numbers correspond to higher interrupt priorities. So for example a priority level mask of 4 will allow interrupts of priority level 0-3, and interrupts with a numerical priority of 4 and greater is blocked.

The hardware priority mechanism will only look at the upper 3 bits of the priority level, so any prioritization must be performed in those bits.

#### Returns:

Returns the value of the interrupt priority level mask.

# 13.2.1.12 ROM IntPriorityMaskSet

Sets the priority masking level

### Prototype:

```
void
ROM_IntPriorityMaskSet(uint32_t ui32PriorityMask)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_INTERRUPTTABLE is an array of pointers located at ROM_APITABLE[14].

ROM_INTERRUPTTABLE[10].
```

#### Parameters:

ui32PriorityMask is the priority level that is masked.

### **Description:**

This function sets the interrupt priority masking level so that all interrupts at the specified or lesser priority level is masked. This can be used to globally disable a set of interrupts with priority below a predetermined threshold. A value of 0 disables priority masking.

Smaller numbers correspond to higher interrupt priorities. So for example a priority level mask of 4 will allow interrupts of priority level 0-3, and interrupts with a numerical priority of 4 and greater is blocked.

The hardware priority mechanism will only look at the upper 3 bits of the priority level, so any prioritization must be performed in those bits.

#### Returns:

None.

# 13.2.1.13 ROM IntPrioritySet

Sets the priority of an interrupt.

#### Prototype:

# **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010. ROM\_INTERRUPTTABLE is an array of pointers located at ROM\_APITABLE[14]. ROM\_IntPrioritySet is a function pointer located at ROM\_INTERRUPTTABLE[6].

#### Parameters:

ui32Interrupt specifies the interrupt in question.ui8Priority specifies the priority of the interrupt.

### **Description:**

This function is used to set the priority of an interrupt. When multiple interrupts are asserted simultaneously, the ones with the highest priority are processed before the lower priority interrupts. Smaller numbers correspond to higher interrupt priorities; priority 0 is the highest interrupt priority.

The hardware priority mechanism will only look at the upper 3 bits of the priority level, so any prioritization must be performed in those bits. The remaining bits can be used to subprioritize the interrupt sources, and may be used by the hardware priority mechanism on a future part. This arrangement allows priorities to migrate to different NVIC implementations without changing the gross prioritization of the interrupts.

### Returns:

None.

# 14 Memory Protection Unit (MPU)

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# 14.1 Introduction

The Memory Protection Unit (MPU) API provides functions to configure the MPU. The MPU is tightly coupled to the Cortex-M4 processor core and provides a means to establish access permissions on regions of memory.

Up to eight memory regions can be defined. Each region has a base address and a size. The size is specified as a power of 2 between 32 bytes and 4 GB, inclusive. The region's base address must be aligned to the size of the region. Each region also has access permissions. Code execution can be allowed or disallowed for a region. A region can be set for read-only access, read/write access, or no access for both privileged and user modes. This can be used to set up an environment where only kernel or system code can access certain hardware registers or sections of code.

The MPU creates 8 sub-regions within each region. Any sub-region or combination of sub-regions can be disabled, allowing creation of "holes" or complex overlaying regions with different permissions. The sub-regions can also be used to create an unaligned beginning or ending of a region by disabling one or more of the leading or trailing sub-regions.

Once the regions are defined and the MPU is enabled, any access violation of a region will cause a memory management fault, and the fault handler will be activated.

Generally, the memory protection regions should be defined before enabling the MPU. The regions can be configured by calling ROM\_MPURegionSet() once for each region to be configured.

A region that is defined by ROM\_MPURegionSet() can be initially enabled or disabled. If the region is not initially enabled, it can be enabled later by calling ROM\_MPURegionEnable(). An enabled region can be disabled by calling ROM\_MPURegionDisable(). When a region is disabled, its configuration is preserved as long as it is not overwritten. In this case it can be enabled again with ROM\_MPURegionEnable() without the need to reconfigure the region.

Care must be taken when setting up a protection region using ROM\_MPURegionSet(). The function will write to multiple registers and is not protected from interrupts. Therefore, it is possible that an interrupt which accesses a region may occur while that region is in the process of being changed. The safest way to protect against this is to make sure that a region is always disabled before making any changes. Otherwise, it is up to the caller to ensure that ROM\_MPURegionSet() is always called from within code that cannot be interrupted, or from code that will not be affected if an interrupt occurs while the region attributes are being changed.

The attributes of a region that has already been programmed can be retrieved and saved using the ROM\_MPURegionGet() function. This function is intended to save the attributes in a format that can be used later to reload the region using the ROM\_MPURegionSet() function. Note that the enable state of the region is saved with the attributes and will take effect when the region is reloaded.

When one or more regions are defined, the MPU can be enabled by calling ROM\_MPUEnable(). This turns on the MPU and also defines the behavior in privileged mode and in the Hard Fault and NMI fault handlers. The MPU can be configured so that when in privileged mode and no regions are

enabled, a default memory map is applied. If this feature is not enabled, then a memory management fault is generated if the MPU is enabled and no regions are configured and enabled. The MPU can also be set to use a default memory map when in the Hard Fault or NMI handlers, instead of using the configured regions. All of these features are selected when calling ROM\_MPUEnable(). When the MPU is enabled, it can be disabled by calling ROM\_MPUDisable().

# 14.2 Functions

# **Functions**

- void ROM\_MPUDisable (void)
- void ROM\_MPUEnable (uint32\_t ui32MPUConfig)
- uint32\_t ROM\_MPURegionCountGet (void)
- void ROM MPURegionDisable (uint32 t ui32Region)
- void ROM\_MPURegionEnable (uint32\_t ui32Region)
- void ROM MPURegionGet (uint32 t ui32Region, uint32 t \*pui32Addr, uint32 t \*pui32Flags)
- void ROM\_MPURegionSet (uint32\_t ui32Region, uint32\_t ui32Addr, uint32\_t ui32Flags)

# 14.2.1 Function Documentation

# 14.2.1.1 ROM MPUDisable

Disables the MPU for use.

### Prototype:

```
void
ROM_MPUDisable(void)
```

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_MPUTABLE is an array of pointers located at ROM_APITABLE[20].
ROM_MPUDisable is a function pointer located at ROM_MPUTABLE[1].
```

### **Description:**

This function disables the Cortex-M4 memory protection unit. When the MPU is disabled, the default memory map is used and memory management faults are not generated.

#### Returns:

None.

# 14.2.1.2 ROM MPUEnable

Enables and configures the MPU for use.

# Prototype:

```
void
ROM_MPUEnable(uint32_t ui32MPUConfig)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_MPUTABLE is an array of pointers located at ROM_APITABLE[20].

ROM_MPUEnable is a function pointer located at ROM_MPUTABLE[0].
```

#### Parameters:

*ui32MPUConfig* is the logical OR of the possible configurations.

### **Description:**

This function enables the Cortex-M4 memory protection unit. It also configures the default behavior when in privileged mode and while handling a hard fault or NMI. Prior to enabling the MPU, at least one region must be set by calling ROM\_MPURegionSet() or else by enabling the default region for privileged mode by passing the MPU\_CONFIG\_PRIV\_DEFAULT flag to ROM\_MPUEnable(). Once the MPU is enabled, a memory management fault is generated for any memory access violations.

The *ui32MPUConfig* parameter should be the logical OR of any of the following:

- MPU\_CONFIG\_PRIV\_DEFAULT enables the default memory map when in privileged mode and when no other regions are defined. If this option is not enabled, then there must be at least one valid region already defined when the MPU is enabled.
- MPU\_CONFIG\_HARDFLT\_NMI enables the MPU while in a hard fault or NMI exception handler. If this option is not enabled, then the MPU is disabled while in one of these exception handlers and the default memory map is applied.
- MPU\_CONFIG\_NONE chooses none of the above options. In this case, no default memory map is provided in privileged mode, and the MPU will not be enabled in the fault handlers.

### Returns:

None.

# 14.2.1.3 ROM MPURegionCountGet

Gets the count of regions supported by the MPU.

### Prototype:

```
uint32_t
ROM_MPURegionCountGet(void)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_MPUTABLE is an array of pointers located at ROM_APITABLE[20].
ROM_MPURegionCountGet is a function pointer located at ROM_MPUTABLE[2].
```

#### Description:

This function is used to get the number of regions that are supported by the MPU. This is the total number that are supported, including regions that are already programmed.

#### Returns:

The number of memory protection regions that are available for programming using ROM\_MPURegionSet().

# 14.2.1.4 ROM MPURegionDisable

Disables a specific region.

# Prototype:

```
void
ROM_MPURegionDisable(uint32_t ui32Region)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_MPUTABLE is an array of pointers located at ROM_APITABLE[20].

ROM_MPURegionDisable is a function pointer located at ROM_MPUTABLE[4].
```

### Parameters:

ui32Region is the region number to disable.

# **Description:**

This function is used to disable a previously enabled memory protection region. The region will remain configured if it is not overwritten with another call to ROM\_MPURegionSet(), and can be enabled again by calling ROM MPURegionEnable().

#### Returns:

None.

# 14.2.1.5 ROM MPURegionEnable

Enables a specific region.

# Prototype:

```
void
ROM_MPURegionEnable(uint32_t ui32Region)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_MPUTABLE is an array of pointers located at ROM_APITABLE[20].
ROM_MPURegionEnable is a function pointer located at ROM_MPUTABLE[3].
```

### Parameters:

ui32Region is the region number to enable.

### **Description:**

This function is used to enable a memory protection region. The region should already be set up with the ROM\_MPURegionSet() function. Once enabled, the memory protection rules of the region are applied and access violations will cause a memory management fault.

## Returns:

None.

# 14.2.1.6 ROM MPURegionGet

Gets the current settings for a specific region.

# **Prototype:**

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_MPUTABLE is an array of pointers located at ROM_APITABLE[20].

ROM_MPURegionGet is a function pointer located at ROM_MPUTABLE[6].
```

### Parameters:

ui32Region is the region number to get.pui32Addr points to storage for the base address of the region.pui32Flags points to the attribute flags for the region.

### **Description:**

This function retrieves the configuration of a specific region. The meanings and format of the parameters is the same as that of the ROM\_MPURegionSet() function.

This function can be used to save the configuration of a region for later use with the ROM\_MPURegionSet() function. The region's enable state is preserved in the attributes that are saved.

#### Returns:

None.

# 14.2.1.7 ROM MPURegionSet

Sets up the access rules for a specific region.

# Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_MPUTABLE is an array of pointers located at ROM_APITABLE[20].

ROM_MPURegionSet is a function pointer located at ROM_MPUTABLE[5].
```

# Parameters:

*ui32Region* is the region number to set up.

ui32Addr is the base address of the region. It must be aligned according to the size of the region specified in ui32Flags.

ui32Flags is a set of flags to define the attributes of the region.

### **Description:**

This function sets up the protection rules for a region. The region has a base address and a set of attributes including the size, which must be a power of 2. The base address parameter, *ui32Addr*, must be aligned according to the size.

The *ui32Flags* parameter is the logical OR of all of the attributes of the region. It is a combination of choices for region size, execute permission, read/write permissions, disabled subregions, and a flag to determine if the region is enabled.

The size flag determines the size of a region, and must be one of the following:

- MPU\_RGN\_SIZE\_32B
- MPU RGN SIZE 64B
- MPU RGN SIZE 128B
- MPU\_RGN\_SIZE\_256B
- MPU RGN SIZE 512B
- MPU RGN SIZE 1K
- MPU\_RGN\_SIZE\_2K
- MPU\_RGN\_SIZE\_4K
- MPU RGN SIZE 8K
- MPU RGN SIZE 16K
- MPU RGN SIZE 32K
- MPU RGN SIZE 64K
- MPU RGN SIZE 128K
- MPU RGN SIZE 256K
- MPU RGN SIZE 512K
- MPU\_RGN\_SIZE\_1M
- MPU RGN SIZE 2M
- MPU\_RGN\_SIZE\_4M
- MPU RGN SIZE 8M
- MPU RGN SIZE 16M
- MPU\_RGN\_SIZE\_32M
- MPU RGN SIZE 64M
- MPU\_RGN\_SIZE\_128M
- MPU RGN SIZE 256M
- MPU\_RGN\_SIZE\_512M
- MPU RGN SIZE 1G
- MPU\_RGN\_SIZE\_2G
- MPU RGN SIZE 4G

The execute permission flag must be one of the following:

- MPU\_RGN\_PERM\_EXEC enables the region for execution of code
- MPU RGN PERM NOEXEC disables the region for execution of code

The read/write access permissions are applied separately for the privileged and user modes. The read/write access flags must be one of the following:

- MPU RGN PERM PRV NO USR NO no access in privileged or user mode
- MPU RGN PERM PRV RW USR NO privileged read/write, user no access
- MPU RGN PERM PRV RW USR RO privileged read/write, user read-only
- MPU\_RGN\_PERM\_PRV\_RW\_USR\_RW privileged read/write, user read/write
- MPU RGN PERM PRV RO USR NO privileged read-only, user no access
- MPU\_RGN\_PERM\_PRV\_RO\_USR\_RO privileged read-only, user read-only

The region is automatically divided into 8 equally-sized sub-regions by the MPU. Sub-regions can only be used in regions of size 256 bytes or larger. Any of these 8 sub-regions can be disabled. This allows for creation of "holes" in a region which can be left open, or overlaid by another region with different attributes. Any of the 8 sub-regions can be disabled with a logical OR of any of the following flags:

```
■ MPU_SUB_RGN_DISABLE_0
■ MPU_SUB_RGN_DISABLE_1
■ MPU_SUB_RGN_DISABLE_2
■ MPU_SUB_RGN_DISABLE_3
■ MPU_SUB_RGN_DISABLE_4
■ MPU_SUB_RGN_DISABLE_5
■ MPU_SUB_RGN_DISABLE_6
■ MPU_SUB_RGN_DISABLE_6
```

Finally, the region can be initially enabled or disabled with one of the following flags:

MPU\_RGN\_ENABLEMPU RGN DISABLE

As an example, to set a region with the following attributes: size of 32 KB, execution enabled, read-only for both privileged and user, one sub-region disabled, and initially enabled; the *ui32Flags* parameter would have the following value:

```
(MPU_RG_SIZE_32K | MPU_RGN_PERM_EXEC | MPU_RGN_PERM_PRV_RO_USR_RO | MPU SUB RGN DISABLE 2 | MPU RGN ENABLE)
```

#### Note:

This function will write to multiple registers and is not protected from interrupts. It is possible that an interrupt which accesses a region may occur while that region is in the process of being changed. The safest way to handle this is to disable a region before changing it. Refer to the discussion of this in the introduction.

#### Returns:

None.

# 15 Pulse Width Modulator (PWM)

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# 15.1 Introduction

The PWM module provides up to four instances of a PWM generator block, and an output control block. Each generator block has two PWM output signals, which can be operated independently, or as a pair of signals with dead band delays inserted. Each generator block also has an interrupt output and a trigger output. The control block determines the polarity of the PWM signals, and which signals are passed through to the pins.

Some of the features of the PWM module are:

- Up to four generator blocks, each containing:
  - One 16-bit down or up/down counter
  - · Two comparators
  - PWM generator
  - Dead band generator
- Control block
  - · PWM output enable
  - · Output polarity control
  - Synchronization
  - Fault handling
  - Interrupt status

When discussing the various components of the PWM module, the following conventions are used:

- The four generator blocks are called **Gen0**, **Gen1**, **Gen2**, and **Gen3**.
- The two PWM output signals associated with each generator block are called **OutA** and **OutB**.
- The eight output signals are called PWM0, PWM1, PWM2, PWM3, PWM4, PWM5, PWM6, and PWM7.
- PWM0 and PWM1 are associated with Gen0, PWM2 and PWM3 are associated with Gen1, PWM4 and PWM5 are associated with Gen2, and PWM6 and PWM7 are associated with Gen3.

Also, as a simplifying assumption for this API, comparator A for each generator block is used exclusively to adjust the pulse width of the even numbered PWM outputs (**PWM0**, **PWM2**, **PWM4**, and **PWM6**). In addition, comparator B is used exclusively for the odd numbered PWM outputs (**PWM1**, **PWM3**, **PWM5**, and **PWM7**).

# 15.2 Functions

# **Functions**

■ void ROM\_PWMDeadBandDisable (uint32\_t ui32Base, uint32\_t ui32Gen)

- void ROM\_PWMDeadBandEnable (uint32\_t ui32Base, uint32\_t ui32Gen, uint16\_t ui16Rise, uint16\_t ui16Fall)
- void ROM\_PWMFaultIntClear (uint32\_t ui32Base)
- void ROM\_PWMFaultIntClearExt (uint32\_t ui32Base, uint32\_t ui32FaultInts)
- void ROM\_PWMGenConfigure (uint32\_t ui32Base, uint32\_t ui32Gen, uint32\_t ui32Config)
- void ROM PWMGenDisable (uint32 t ui32Base, uint32 t ui32Gen)
- void ROM\_PWMGenEnable (uint32\_t ui32Base, uint32\_t ui32Gen)
- void ROM\_PWMGenFaultClear (uint32\_t ui32Base, uint32\_t ui32Gen, uint32\_t ui32Group, uint32\_t ui32FaultTriggers)
- void ROM\_PWMGenFaultConfigure (uint32\_t ui32Base, uint32\_t ui32Gen, uint32\_t ui32MinFaultPeriod, uint32\_t ui32FaultSenses)
- uint32\_t ROM\_PWMGenFaultStatus (uint32\_t ui32Base, uint32\_t ui32Gen, uint32\_t ui32Group)
- uint32\_t ROM\_PWMGenFaultTriggerGet (uint32\_t ui32Base, uint32\_t ui32Gen, uint32\_t ui32Group)
- void ROM\_PWMGenFaultTriggerSet (uint32\_t ui32Base, uint32\_t ui32Gen, uint32\_t ui32Group, uint32\_t ui32FaultTriggers)
- void ROM PWMGenIntClear (uint32 t ui32Base, uint32 t ui32Gen, uint32 t ui32Ints)
- uint32 t ROM PWMGenIntStatus (uint32 t ui32Base, uint32 t ui32Gen, bool bMasked)
- void ROM PWMGenIntTrigDisable (uint32 t ui32Base, uint32 t ui32Gen, uint32 t ui32IntTrig)
- void ROM\_PWMGenIntTrigEnable (uint32\_t ui32Base, uint32\_t ui32Gen, uint32\_t ui32IntTrig)
- uint32 t ROM PWMGenPeriodGet (uint32 t ui32Base, uint32 t ui32Gen)
- void ROM PWMGenPeriodSet (uint32 t ui32Base, uint32 t ui32Gen, uint32 t ui32Period)
- void ROM PWMIntDisable (uint32 t ui32Base, uint32 t ui32GenFault)
- void ROM PWMIntEnable (uint32 t ui32Base, uint32 t ui32GenFault)
- uint32 t ROM PWMIntStatus (uint32 t ui32Base, bool bMasked)
- void ROM\_PWMOutputFault (uint32\_t ui32Base, uint32\_t ui32PWMOutBits, bool bFaultSuppress)
- void ROM\_PWMOutputFaultLevel (uint32\_t ui32Base, uint32\_t ui32PWMOutBits, bool bDrive-High)
- void ROM PWMOutputInvert (uint32 t ui32Base, uint32 t ui32PWMOutBits, bool bInvert)
- void ROM PWMOutputState (uint32 t ui32Base, uint32 t ui32PWMOutBits, bool bEnable)
- uint32 t ROM PWMPulseWidthGet (uint32 t ui32Base, uint32 t ui32PWMOut)
- void ROM\_PWMPulseWidthSet (uint32\_t ui32Base, uint32\_t ui32PWMOut, uint32\_t ui32Width)
- void ROM\_PWMSyncTimeBase (uint32\_t ui32Base, uint32\_t ui32GenBits)
- void ROM\_PWMSyncUpdate (uint32\_t ui32Base, uint32\_t ui32GenBits)

# 15.2.1 Function Documentation

# 15.2.1.1 ROM PWMDeadBandDisable

Disables the PWM dead band output.

#### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMDeadBandDisable is a function pointer located at ROM_PWMTABLE[8].
```

#### Parameters:

ui32Base is the base address of the PWM module.

ui32Gen is the PWM generator to modify. Must be one of PWM\_GEN\_0, PWM\_GEN\_1, PWM GEN 2, or PWM GEN 3.

# **Description:**

This function disables the dead band mode for the specified PWM generator. Doing so decouples the **OutA** and **OutB** signals.

#### Returns:

None.

# 15.2.1.2 ROM PWMDeadBandEnable

Enables the PWM dead band output, and sets the dead band delays.

# Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMDeadBandEnable is a function pointer located at ROM_PWMTABLE[7].
```

#### Parameters:

ui32Base is the base address of the PWM module.

ui32Gen is the PWM generator to modify. Must be one of PWM\_GEN\_0, PWM\_GEN\_1, PWM\_GEN\_2, or PWM\_GEN\_3.

ui16Rise specifies the width of delay from the rising edge.

*ui16Fall* specifies the width of delay from the falling edge.

## **Description:**

This function sets the dead bands for the specified PWM generator, where the dead bands are defined as the number of **PWM** clock ticks from the rising or falling edge of the generator's **OutA** signal. Note that this function causes the coupling of **OutB** to **OutA**.

# Returns:

None.

# 15.2.1.3 ROM PWMFaultIntClear

Clears the fault interrupt for a PWM module.

### Prototype:

```
void
ROM PWMFaultIntClear(uint32 t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMFaultIntClear is a function pointer located at ROM_PWMTABLE[20].
```

#### Parameters:

ui32Base is the base address of the PWM module.

# **Description:**

Clears the fault interrupt by writing to the appropriate bit of the interrupt status register for the selected PWM module.

This function clears only the FAULT0 interrupt and is retained for backwards compatibility. It is recommended that ROM\_PWMFaultIntClearExt() be used instead since it supports all fault interrupts supported on devices with and without extended PWM fault handling support.

### Note:

Because there is a write buffer in the Cortex-M4 processor, it may take several clock cycles before the interrupt source is actually cleared. Therefore, it is recommended that the interrupt source be cleared early in the interrupt handler (as opposed to the very last action) to avoid returning from the interrupt handler before the interrupt source is actually cleared. Failure to do so may result in the interrupt handler being immediately reentered (because the interrupt controller still sees the interrupt source asserted).

#### Returns:

None.

# 15.2.1.4 ROM PWMFaultIntClearExt

Clears the fault interrupt for a PWM module.

# Prototype:

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMFaultIntClearExt is a function pointer located at ROM_PWMTABLE[23].
```

### Parameters:

ui32Base is the base address of the PWM module.ui32FaultInts specifies the fault interrupts to clear.

# **Description:**

Clears one or more fault interrupts by writing to the appropriate bit of the PWM interrupt status register. The parameter *ui32FaultInts* must be the logical OR of any of **PWM\_INT\_FAULT0**, **PWM INT FAULT1**, **PWM INT FAULT2**, or **PWM INT FAULT3**.

When running on a device supporting extended PWM fault handling, the fault interrupts are derived by performing a logical OR of each of the configured fault trigger signals for a given generator. Therefore, these interrupts are not directly related to the four possible FAULTn inputs to the device but indicate that a fault has been signaled to one of the four possible PWM generators. On a device without extended PWM fault handling, the interrupt is directly related to the state of the single FAULT pin.

#### Note:

Because there is a write buffer in the Cortex-M4 processor, it may take several clock cycles before the interrupt source is actually cleared. Therefore, it is recommended that the interrupt source be cleared early in the interrupt handler (as opposed to the very last action) to avoid returning from the interrupt handler before the interrupt source is actually cleared. Failure to do so may result in the interrupt handler being immediately reentered (because the interrupt controller still sees the interrupt source asserted).

#### Returns:

None.

# 15.2.1.5 ROM PWMGenConfigure

Configures a PWM generator.

# Prototype:

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMGenConfigure is a function pointer located at ROM_PWMTABLE[1].
```

# Parameters:

ui32Base is the base address of the PWM module.

ui32Gen is the PWM generator to configure. Must be one of PWM\_GEN\_0, PWM\_GEN\_1, PWM\_GEN\_2, or PWM\_GEN\_3.

ui32Config is the configuration for the PWM generator.

# **Description:**

This function is used to set the mode of operation for a PWM generator. The counting mode, synchronization mode, and debug behavior are all configured. After configuration, the generator is left in the disabled state.

A PWM generator can count in two different modes: count down mode or count up/down mode. In count down mode, it will count from a value down to zero, and then reset to the preset value. This will produce left-aligned PWM signals (that is the rising edge of the two PWM signals produced by the generator will occur at the same time). In count up/down mode, it will count

up from zero to the preset value, count back down to zero, and then repeat the process. This will produce center-aligned PWM signals (that is, the middle of the high/low period of the PWM signals produced by the generator will occur at the same time).

When the PWM generator parameters (period and pulse width) are modified, their affect on the output PWM signals can be delayed. In synchronous mode, the parameter updates are not applied until a synchronization event occurs. This allows multiple parameters to be modified and take affect simultaneously, instead of one at a time. Additionally, parameters to multiple PWM generators in synchronous mode can be updated simultaneously, allowing them to be treated as if they were a unified generator. In non-synchronous mode, the parameter updates are not delayed until a synchronization event. In either mode, the parameter updates only occur when the counter is at zero to help prevent oddly formed PWM signals during the update (that is, a PWM pulse that is too short or too long).

The PWM generator can either pause or continue running when the processor is stopped via the debugger. If configured to pause, it will continue to count until it reaches zero, at which point it will pause until the processor is restarted. If configured to continue running, it will keep counting as if nothing had happened.

The *ui32Config* parameter contains the desired configuration. It is the logical OR of the following:

- PWM\_GEN\_MODE\_DOWN or PWM\_GEN\_MODE\_UP\_DOWN to specify the counting mode
- PWM\_GEN\_MODE\_SYNC or PWM\_GEN\_MODE\_NO\_SYNC to specify the counter load and comparator update synchronization mode
- PWM\_GEN\_MODE\_DBG\_RUN or PWM\_GEN\_MODE\_DBG\_STOP to specify the debug behavior
- PWM\_GEN\_MODE\_GEN\_NO\_SYNC, PWM\_GEN\_MODE\_GEN\_SYNC\_LOCAL, or PWM\_GEN\_MODE\_GEN\_SYNC\_GLOBAL to specify the update synchronization mode for generator counting mode changes
- PWM\_GEN\_MODE\_DB\_NO\_SYNC, PWM\_GEN\_MODE\_DB\_SYNC\_LOCAL, or PWM\_GEN\_MODE\_DB\_SYNC\_GLOBAL to specify the deadband parameter synchronization mode
- PWM\_GEN\_MODE\_FAULT\_LATCHED or PWM\_GEN\_MODE\_FAULT\_UNLATCHED to specify whether fault conditions are latched or not
- PWM\_GEN\_MODE\_FAULT\_MINPER or PWM\_GEN\_MODE\_FAULT\_NO\_MINPER to specify whether minimum fault period support is required
- PWM\_GEN\_MODE\_FAULT\_EXT or PWM\_GEN\_MODE\_FAULT\_LEGACY to specify whether extended fault source selection support is enabled or not

Setting **PWM\_GEN\_MODE\_FAULT\_MINPER** allows an application to set the minimum duration of a PWM fault signal. Faults will be signaled for at least this time even if the external fault pin deasserts earlier. Care should be taken when using this mode since during the fault signal period, the fault interrupt from the PWM generator will remain asserted. The fault interrupt handler may, therefore, reenter immediately if it exits prior to expiration of the fault timer.

#### Note:

Changes to the counter mode will affect the period of the PWM signals produced. ROM\_PWMGenPeriodSet() and ROM\_PWMPulseWidthSet() should be called after any changes to the counter mode of a generator.

#### Returns:

None.

# 15.2.1.6 ROM PWMGenDisable

Disables the timer/counter for a PWM generator block.

# Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMGenDisable is a function pointer located at ROM_PWMTABLE[5].
```

#### Parameters:

ui32Base is the base address of the PWM module.

ui32Gen is the PWM generator to be disabled. Must be one of PWM\_GEN\_0, PWM\_GEN\_1, PWM GEN 2, or PWM GEN 3.

# **Description:**

This function blocks the PWM clock from driving the timer/counter for the specified generator block.

#### Returns:

None.

# 15.2.1.7 ROM PWMGenEnable

Enables the timer/counter for a PWM generator block.

# **Prototype:**

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMGenEnable is a function pointer located at ROM_PWMTABLE[4].
```

#### **Parameters:**

ui32Base is the base address of the PWM module.

```
ui32Gen is the PWM generator to be enabled. Must be one of PWM_GEN_0, PWM_GEN_1, PWM GEN 2, or PWM GEN 3.
```

#### **Description:**

This function allows the PWM clock to drive the timer/counter for the specified generator block.

#### Returns:

None.

# 15.2.1.8 ROM PWMGenFaultClear

Clears one or more latched fault triggers for a given PWM generator.

### Prototype:

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMGenFaultClear is a function pointer located at ROM_PWMTABLE[28].
```

#### Parameters:

ui32Base is the base address of the PWM module.

ui32Gen is the PWM generator whose fault trigger states are being queried. Must be one of PWM GEN 0, PWM GEN 1, PWM GEN 2, or PWM GEN 3.

ui32Group indicates the subset of faults that are being queried. This must be PWM\_FAULT\_GROUP\_0 or PWM\_FAULT\_GROUP\_1.

ui32FaultTriggers is the set of fault triggers which are to be cleared.

# **Description:**

This function allows an application to clear the fault triggers for a given PWM generator. This is only required if ROM\_PWMGenConfigure() has previously been called with flag PWM\_GEN\_MODE\_LATCH\_FAULT in parameter *ui32Config*.

# Note:

This function is only available on devices supporting extended PWM fault handling.

#### Returns:

None.

# 15.2.1.9 ROM PWMGenFaultConfigure

Configures the minimum fault period and fault pin senses for a given PWM generator.

# **Prototype:**

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMGenFaultConfigure is a function pointer located at ROM_PWMTABLE[24].
```

#### Parameters:

ui32Base is the base address of the PWM module.

ui32Gen is the PWM generator whose fault configuration is being set. Must be one of PWM\_GEN\_0, PWM\_GEN\_1, PWM\_GEN\_2, or PWM\_GEN\_3.

ui32MinFaultPeriod is the minimum fault active period expressed in PWM clock cycles.

ui32FaultSenses indicates which sense of each FAULT input should be considered the "asserted" state. Valid values are logical OR combinations of PWM\_FAULTn\_SENSE\_HIGH and PWM FAULTn SENSE LOW.

#### **Description:**

This function sets the minimum fault period for a given generator along with the sense of each of the 4 possible fault inputs. The minimum fault period is expressed in PWM clock cycles and takes effect only if ROM\_PWMGenConfigure() is called with flag PWM\_GEN\_MODE\_FAULT\_PER set in the *ui32Config* parameter. When a fault input is asserted, the minimum fault period timer ensures that it remains asserted for at least the number of clock cycles specified.

#### Note:

This function is only available on devices supporting extended PWM fault handling.

#### Returns:

None.

# 15.2.1.10 ROM PWMGenFaultStatus

Returns the current state of the fault triggers for a given PWM generator.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMGenFaultStatus is a function pointer located at ROM_PWMTABLE[27].
```

#### Parameters:

ui32Base is the base address of the PWM module.

ui32Gen is the PWM generator whose fault trigger states are being queried. Must be one of PWM\_GEN\_0, PWM\_GEN\_1, PWM\_GEN\_2, or PWM\_GEN\_3.

ui32Group indicates the subset of faults that are being queried. This must be PWM\_FAULT\_GROUP\_0 or PWM\_FAULT\_GROUP\_1.

# **Description:**

This function allows an application to query the current state of each of the fault trigger inputs to a given PWM generator. The current state of each fault trigger input is returned unless ROM\_PWMGenConfigure() has previously been called with flag PWM\_GEN\_MODE\_LATCH\_FAULT in the *ui32Config* parameter in which case the returned status is the latched fault trigger status.

If latched faults are configured, the application must call ROM\_PWMGenFaultClear() to clear each trigger.

#### Note:

This function is only available on devices supporting extended PWM fault handling.

#### Returns:

Returns the current state of the fault triggers for the given PWM generator. A set bit indicates that the associated trigger is active. For PWM\_FAULT\_GROUP\_0, the returned value is a logical OR of PWM\_FAULT\_FAULT0, PWM\_FAULT\_FAULT1, PWM\_FAULT\_FAULT2, or PWM\_FAULT\_FAULT3. For PWM\_FAULT\_GROUP\_1, the return value is the logical OR of PWM\_FAULT\_DCMP0, PWM\_FAULT\_DCMP1, PWM\_FAULT\_DCMP2, PWM\_FAULT\_DCMP3, PWM\_FAULT\_DCMP4, PWM\_FAULT\_DCMP5, PWM\_FAULT\_DCMP6, or PWM\_FAULT\_DCMP7.

# 15.2.1.11 ROM\_PWMGenFaultTriggerGet

Returns the set of fault triggers currently configured for a given PWM generator.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMGenFaultTriggerGet is a function pointer located at ROM_PWMTABLE[26].
```

### Parameters:

ui32Base is the base address of the PWM module.

ui32Gen is the PWM generator whose fault triggers are being queried. Must be one of PWM\_GEN\_0, PWM\_GEN\_1, PWM\_GEN\_2, or PWM\_GEN\_3.

ui32Group indicates the subset of faults that are being queried. This must be PWM FAULT GROUP 0 or PWM FAULT GROUP 1.

### **Description:**

This function allows an application to query the current set of inputs that contribute towards the generation of a fault condition to a given PWM generator.

### Note:

This function is only available on devices supporting extended PWM fault handling.

#### Returns:

```
Returns the current fault triggers configured for the fault group provided. For PWM_FAULT_GROUP_0, the returned value is a logical OR of PWM_FAULT_FAULT0, PWM_FAULT_FAULT1, PWM_FAULT_FAULT2, or PWM_FAULT_FAULT3. For PWM_FAULT_GROUP_1, the return value is the logical OR of PWM_FAULT_DCMP0, PWM_FAULT_DCMP1, PWM_FAULT_DCMP2, PWM_FAULT_DCMP3, PWM_FAULT_DCMP4, PWM_FAULT_DCMP5, PWM_FAULT_DCMP6, or PWM_FAULT_DCMP7.
```

# 15.2.1.12 ROM PWMGenFaultTriggerSet

Configures the set of fault triggers for a given PWM generator.

### Prototype:

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMGenFaultTriggerSet is a function pointer located at ROM_PWMTABLE[25].
```

#### Parameters:

ui32Base is the base address of the PWM module.

ui32Gen is the PWM generator whose fault triggers are being set. Must be one of PWM GEN 0, PWM GEN 1, PWM GEN 2, or PWM GEN 3.

ui32Group indicates the subset of possible faults that are to be configured. This must be PWM\_FAULT\_GROUP\_0 or PWM\_FAULT\_GROUP\_1.

ui32FaultTriggers defines the set of inputs that are to contribute towards generation of the fault signal to the given PWM generator. For PWM\_FAULT\_GROUP\_0, this is the logical OR of PWM\_FAULT\_FAULT0, PWM\_FAULT\_FAULT1, PWM\_FAULT\_FAULT2, or PWM\_FAULT\_BULT3. For PWM\_FAULT\_GROUP\_1, this is the logical OR of PWM\_FAULT\_DCMP0, PWM\_FAULT\_DCMP1, PWM\_FAULT\_DCMP2, PWM\_FAULT\_DCMP3, PWM\_FAULT\_DCMP4, PWM\_FAULT\_DCMP5, PWM\_FAULT\_DCMP6, or PWM\_FAULT\_DCMP7.

#### **Description:**

This function allows selection of the set of fault inputs that is combined to generate a fault condition to a given PWM generator. By default, all generators use only FAULTO (for backwards compatibility) but if ROM\_PWMGenConfigure() is called with flag PWM\_GEN\_MODE\_FAULT\_SRC in the *ui32Config* parameter, extended fault handling is enabled and this function must be called to configure the fault triggers.

The fault signal to the PWM generator is generated by ORing together each of the signals whose inputs are specified in the *ui32FaultTriggers* parameter after having adjusted the sense of each FAULTn input based on the configuration previously set using a call to ROM\_PWMGenFaultConfigure().

#### Note:

This function is only available on devices supporting extended PWM fault handling.

#### Returns:

None.

# 15.2.1.13 ROM PWMGenIntClear

Clears the specified interrupt(s) for the specified PWM generator block.

# Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMGenIntClear is a function pointer located at ROM_PWMTABLE[17].
```

# Parameters:

ui32Base is the base address of the PWM module.

ui32Gen is the PWM generator to query. Must be one of PWM\_GEN\_0, PWM\_GEN\_1, PWM\_GEN\_2, or PWM\_GEN\_3.

ui32Ints specifies the interrupts to be cleared.

# **Description:**

Clears the specified interrupt(s) by writing a 1 to the specified bits of the interrupt status register for the specified PWM generator. The *ui32Ints* parameter is the logical OR of PWM\_INT\_CNT\_ZERO, PWM\_INT\_CNT\_LOAD, PWM\_INT\_CNT\_AU, PWM\_INT\_CNT\_AD, PWM\_INT\_CNT\_BU, or PWM\_INT\_CNT\_BD.

#### Note:

Because there is a write buffer in the Cortex-M4 processor, it may take several clock cycles before the interrupt source is actually cleared. Therefore, it is recommended that the interrupt source be cleared early in the interrupt handler (as opposed to the very last action) to avoid returning from the interrupt handler before the interrupt source is actually cleared. Failure to do so may result in the interrupt handler being immediately reentered (because the interrupt controller still sees the interrupt source asserted).

#### Returns:

None.

# 15.2.1.14 ROM\_PWMGenIntStatus

Gets interrupt status for the specified PWM generator block.

#### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMGenIntStatus is a function pointer located at ROM_PWMTABLE[16].
```

#### Parameters:

```
ui32Base is the base address of the PWM module.
```

ui32Gen is the PWM generator to query. Must be one of PWM\_GEN\_0, PWM\_GEN\_1, PWM GEN 2, or PWM GEN 3.

**bMasked** specifies whether masked or raw interrupt status is returned.

# **Description:**

If *bMasked* is set as **true**, then the masked interrupt status is returned; otherwise, the raw interrupt status is returned.

#### Returns:

Returns the contents of the interrupt status register, or the contents of the raw interrupt status register, for the specified PWM generator.

# 15.2.1.15 ROM\_PWMGenIntTrigDisable

Disables interrupts for the specified PWM generator block.

# Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMGenIntTrigDisable is a function pointer located at ROM_PWMTABLE[15].
```

#### Parameters:

ui32Base is the base address of the PWM module.

ui32Gen is the PWM generator to have interrupts and triggers disabled. Must be one of PWM GEN 0, PWM GEN 1, PWM GEN 2, or PWM GEN 3.

ui32IntTrig specifies the interrupts and triggers to be disabled.

# **Description:**

Masks the specified interrupt(s) and trigger(s) by clearing the specified bits of the interrupt/trigger enable register for the specified PWM generator. The *ui32IntTrig* parameter is the logical OR of PWM\_INT\_CNT\_ZERO, PWM\_INT\_CNT\_LOAD, PWM\_INT\_CNT\_AU, PWM\_INT\_CNT\_BD, PWM\_INT\_CNT\_BD, PWM\_TR\_CNT\_ZERO, PWM\_TR\_CNT\_LOAD, PWM\_TR\_CNT\_AU, PWM\_TR\_CNT\_AD, PWM\_TR\_CNT\_BU, or PWM\_TR\_CNT\_BD.

### Returns:

None.

# 15.2.1.16 ROM\_PWMGenIntTrigEnable

Enables interrupts and triggers for the specified PWM generator block.

#### Prototype:

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMGenIntTrigEnable is a function pointer located at ROM_PWMTABLE[14].
```

#### Parameters:

ui32Base is the base address of the PWM module.

ui32Gen is the PWM generator to have interrupts and triggers enabled. Must be one of PWM GEN 0, PWM GEN 1, PWM GEN 2, or PWM GEN 3.

ui32IntTrig specifies the interrupts and triggers to be enabled.

### **Description:**

Unmasks the specified interrupt(s) and trigger(s) by setting the specified bits of the interrupt/trigger enable register for the specified PWM generator. The *ui32IntTrig* parameter is the logical OR of PWM\_INT\_CNT\_ZERO, PWM\_INT\_CNT\_LOAD, PWM\_INT\_CNT\_AU, PWM\_INT\_CNT\_BD, PWM\_INT\_CNT\_BD, PWM\_TR\_CNT\_ZERO, PWM\_TR\_CNT\_LOAD, PWM\_TR\_CNT\_AU, PWM\_TR\_CNT\_AD, PWM\_TR\_CNT\_BU, or PWM\_TR\_CNT\_BD.

#### Returns:

None.

# 15.2.1.17 ROM PWMGenPeriodGet

Gets the period of a PWM generator block.

### Prototype:

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMGenPeriodGet is a function pointer located at ROM_PWMTABLE[3].
```

#### Parameters:

ui32Base is the base address of the PWM module.

ui32Gen is the PWM generator to query. Must be one of PWM\_GEN\_0, PWM\_GEN\_1, PWM\_GEN\_2, or PWM\_GEN\_3.

### **Description:**

This function gets the period of the specified PWM generator block. The period of the generator block is defined as the number of PWM clock ticks between pulses on the generator block zero signal.

If the update of the counter for the specified PWM generator has yet to be completed, the value returned may not be the active period. The value returned is the programmed period, measured in PWM clock ticks.

### Returns:

Returns the programmed period of the specified generator block in PWM clock ticks.

# 15.2.1.18 ROM PWMGenPeriodSet

Set the period of a PWM generator.

# Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMGenPeriodSet is a function pointer located at ROM_PWMTABLE[2].
```

#### Parameters:

ui32Base is the base address of the PWM module.

ui32Gen is the PWM generator to be modified. Must be one of PWM\_GEN\_0, PWM\_GEN\_1, PWM\_GEN\_2, or PWM\_GEN\_3.

ui32Period specifies the period of PWM generator output, measured in clock ticks.

#### **Description:**

This function sets the period of the specified PWM generator block, where the period of the generator block is defined as the number of PWM clock ticks between pulses on the generator block zero signal.

#### Note:

Any subsequent calls made to this function before an update occurs will cause the previous values to be overwritten.

### Returns:

None.

# 15.2.1.19 ROM PWMIntDisable

Disables generator and fault interrupts for a PWM module.

# Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMIntDisable is a function pointer located at ROM_PWMTABLE[19].
```

#### Parameters:

ui32Base is the base address of the PWM module.

ui32GenFault contains the interrupts to be disabled. Must be a logical OR of any of PWM\_INT\_GEN\_0, PWM\_INT\_GEN\_1, PWM\_INT\_GEN\_2, PWM\_INT\_GEN\_3, PWM\_INT\_FAULT0, PWM\_INT\_FAULT1, PWM\_INT\_FAULT2, or PWM\_INT\_FAULT3.

# **Description:**

Masks the specified interrupt(s) by clearing the specified bits of the interrupt enable register for the selected PWM module.

# Returns:

None.

# 15.2.1.20 ROM\_PWMIntEnable

Enables generator and fault interrupts for a PWM module.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMIntEnable is a function pointer located at ROM_PWMTABLE[18].
```

#### Parameters:

ui32Base is the base address of the PWM module.

```
ui32GenFault contains the interrupts to be enabled. Must be a logical OR of
any of PWM_INT_GEN_0, PWM_INT_GEN_1, PWM_INT_GEN_2, PWM_INT_GEN_3,
PWM_INT_FAULT0, PWM_INT_FAULT1, PWM_INT_FAULT2, or PWM_INT_FAULT3.
```

#### **Description:**

Unmasks the specified interrupt(s) by setting the specified bits of the interrupt enable register for the selected PWM module.

#### Returns:

None.

# 15.2.1.21 ROM PWMIntStatus

Gets the interrupt status for a PWM module.

# **Prototype:**

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMIntStatus is a function pointer located at ROM_PWMTABLE[21].
```

### Parameters:

ui32Base is the base address of the PWM module.

**bMasked** specifies whether masked or raw interrupt status is returned.

# **Description:**

If *bMasked* is set as **true**, then the masked interrupt status is returned; otherwise, the raw interrupt status is returned.

#### Returns:

The current interrupt status, enumerated as a bit field of PWM\_INT\_GEN\_0, PWM\_INT\_GEN\_1, PWM\_INT\_GEN\_2, PWM\_INT\_GEN\_3, PWM\_INT\_FAULT0, PWM\_INT\_FAULT1, PWM\_INT\_FAULT2, and PWM\_INT\_FAULT3.

# 15.2.1.22 ROM\_PWMOutputFault

Specifies the state of PWM outputs in response to a fault condition.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMOutputFault is a function pointer located at ROM_PWMTABLE[13].
```

#### Parameters:

ui32Base is the base address of the PWM module.

ui32PWMOutBits are the PWM outputs to be modified. Must be the logical OR of any of PWM\_OUT\_0\_BIT, PWM\_OUT\_1\_BIT, PWM\_OUT\_2\_BIT, PWM\_OUT\_3\_BIT, PWM\_OUT\_4\_BIT, PWM\_OUT\_5\_BIT, PWM\_OUT\_6\_BIT, or PWM\_OUT\_7\_BIT.

**bFaultSuppress** determines if the signal is suppressed or passed through during an active fault condition.

### **Description:**

This function sets the fault handling characteristics of the selected PWM outputs. The outputs are selected using the parameter *ui32PWMOutBits*. The parameter *bFaultSuppress* determines the fault handling characteristics for the selected outputs. If *bFaultSuppress* is **true**, then the selected outputs are made inactive. If *bFaultSuppress* is **false**, then the selected outputs are unaffected by the detected fault.

On devices supporting extended PWM fault handling, the state the affected output pins are driven to can be configured with ROM\_PWMOutputFaultLevel(). If not configured, or if the device does not support extended PWM fault handling, affected outputs are driven low on a fault condition.

#### Returns:

None.

# 15.2.1.23 ROM PWMOutputFaultLevel

Specifies the level of PWM outputs suppressed in response to a fault condition.

# Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMOutputFaultLevel is a function pointer located at ROM_PWMTABLE[22].
```

### Parameters:

ui32Base is the base address of the PWM module.

```
ui32PWMOutBits are the PWM outputs to be modified. Must be the logical OR of any of PWM_OUT_0_BIT, PWM_OUT_1_BIT, PWM_OUT_2_BIT, PWM_OUT_3_BIT, PWM OUT 4 BIT, PWM OUT 5 BIT, PWM OUT 6 BIT, or PWM OUT 7 BIT.
```

**bDriveHigh** determines if the signal is driven high or low during an active fault condition.

# Description:

This function determines whether a PWM output pin that is suppressed in response to a fault condition is driven high or low. The affected outputs are selected using the parameter ui32PWMOutBits. The parameter bDriveHigh determines the output level for the pins identified by ui32PWMOutBits. If bDriveHigh is **true** then the selected outputs are driven high when a fault is detected. If it is false, the pins are driven low.

In a fault condition, pins which have not been configured to be suppressed via a call to ROM PWMOutputFault() are unaffected by this function.

### Note:

This function is available only on devices which support extended PWM fault handling.

#### Returns:

None.

# 15.2.1.24 ROM PWMOutputInvert

Selects the inversion mode for PWM outputs.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMOutputInvert is a function pointer located at ROM_PWMTABLE[12].
```

### Parameters:

ui32Base is the base address of the PWM module.

ui32PWMOutBits are the PWM outputs to be modified. Must be the logical OR of any of PWM\_OUT\_0\_BIT, PWM\_OUT\_1\_BIT, PWM\_OUT\_2\_BIT, PWM\_OUT\_3\_BIT, PWM\_OUT\_4\_BIT, PWM\_OUT\_5\_BIT, PWM\_OUT\_6\_BIT, or PWM\_OUT\_7\_BIT.

**blnvert** determines if the signal is inverted or passed through.

# **Description:**

This function is used to select the inversion mode for the selected PWM outputs. The outputs are selected using the parameter *ui32PWMOutBits*. The parameter *bInvert* determines the inversion mode for the selected outputs. If *bInvert* is **true**, this function will cause the specified PWM output signals to be inverted, or made active low. If *bInvert* is **false**, the specified outputs are passed through as is, or be made active high.

#### Returns:

None.

# 15.2.1.25 ROM PWMOutputState

Enables or disables PWM outputs.

# Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMOutputState is a function pointer located at ROM_PWMTABLE[11].
```

### Parameters:

ui32Base is the base address of the PWM module.

ui32PWMOutBits are the PWM outputs to be modified. Must be the logical OR of any of PWM\_OUT\_0\_BIT, PWM\_OUT\_1\_BIT, PWM\_OUT\_2\_BIT, PWM\_OUT\_3\_BIT, PWM\_OUT\_4\_BIT, PWM\_OUT\_5\_BIT, PWM\_OUT\_6\_BIT, or PWM\_OUT\_7\_BIT.

**bEnable** determines if the signal is enabled or disabled.

# **Description:**

This function is used to enable or disable the selected PWM outputs. The outputs are selected using the parameter *ui32PWMOutBits*. The parameter *bEnable* determines the state of the selected outputs. If *bEnable* is **true**, then the selected PWM outputs are enabled, or placed in the active state. If *bEnable* is **false**, then the selected outputs are disabled, or placed in the inactive state.

#### Returns:

None.

# 15.2.1.26 ROM\_PWMPulseWidthGet

Gets the pulse width of a PWM output.

# Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMPulseWidthGet is a function pointer located at ROM_PWMTABLE[6].
```

#### Parameters:

ui32Base is the base address of the PWM module.

```
ui32PWMOut is the PWM output to query. Must be one of PWM_OUT_0, PWM_OUT_1,
    PWM_OUT_2, PWM_OUT_3, PWM_OUT_4, PWM_OUT_5, PWM_OUT_6, or
    PWM OUT 7.
```

# **Description:**

This function gets the currently programmed pulse width for the specified PWM output. If the update of the comparator for the specified output has yet to be completed, the value returned may not be the active pulse width. The value returned is the programmed pulse width, measured in PWM clock ticks.

### Returns:

Returns the width of the pulse in PWM clock ticks.

# 15.2.1.27 ROM PWMPulseWidthSet

Sets the pulse width for the specified PWM output.

#### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMPulseWidthSet is a function pointer located at ROM_PWMTABLE[0].
```

#### Parameters:

```
ui32Base is the base address of the PWM module.
```

```
ui32PWMOut is the PWM output to modify. Must be one of PWM_OUT_0, PWM_OUT_1,
    PWM_OUT_2, PWM_OUT_3, PWM_OUT_4, PWM_OUT_5, PWM_OUT_6, or
    PWM_OUT_7.
```

ui32Width specifies the width of the positive portion of the pulse.

#### **Description:**

This function sets the pulse width for the specified PWM output, where the pulse width is defined as the number of PWM clock ticks.

# Note:

Any subsequent calls made to this function before an update occurs will cause the previous values to be overwritten.

### Returns:

None.

# 15.2.1.28 ROM\_PWMSyncTimeBase

Synchronizes the counters in one or multiple PWM generator blocks.

# Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMSyncTimeBase is a function pointer located at ROM_PWMTABLE[10].
```

#### Parameters:

ui32Base is the base address of the PWM module.

```
ui32GenBits are the PWM generator blocks to be synchronized. Must be the logical OR of any of PWM_GEN_0_BIT, PWM_GEN_1_BIT, PWM_GEN_2_BIT, or PWM_GEN_3_BIT.
```

# **Description:**

For the selected PWM module, this function synchronizes the time base of the generator blocks by causing the specified generator counters to be reset to zero.

### Returns:

None.

# 15.2.1.29 ROM PWMSyncUpdate

Synchronizes all pending updates.

# Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_PWMTABLE is an array of pointers located at ROM_APITABLE[8].

ROM_PWMSyncUpdate is a function pointer located at ROM_PWMTABLE[9].
```

### Parameters:

ui32Base is the base address of the PWM module.

ui32GenBits are the PWM generator blocks to be updated. Must be the logical OR of any of PWM\_GEN\_0\_BIT, PWM\_GEN\_1\_BIT, PWM\_GEN\_2\_BIT, or PWM\_GEN\_3\_BIT.

# **Description:**

For the selected PWM generators, this function causes all queued updates to the period or pulse width to be applied the next time the corresponding counter becomes zero.

Returns:

None.

# 16 Quadrature Encoder (QEI)

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# 16.1 Introduction

The quadrature encoder API provides a set of functions for dealing with the Quadrature Encoder with Index (QEI). Functions are provided to configure and read the position and velocity captures, register a QEI interrupt handler, and handle QEI interrupt masking/clearing.

The quadrature encoder module provides hardware encoding of the two channels and the index signal from a quadrature encoder device into an absolute or relative position. There is additional hardware for capturing a measure of the encoder velocity, which is simply a count of encoder pulses during a fixed time period; the number of pulses is directly proportional to the encoder speed. Note that the velocity capture can only operate when the position capture is enabled.

The QEI module supports two modes of operation: phase mode and clock/direction mode. In phase mode, the encoder produces two clocks that are 90 degrees out of phase; the edge relationship is used to determine the direction of rotation. In clock/direction mode, the encoder produces a clock signal to indicate steps and a direction signal to indicate the direction of rotation.

When in phase mode, edges on the first channel or edges on both channels can be counted; counting edges on both channels provides higher encoder resolution if required. In either mode, the input signals can be swapped before being processed; this allows wiring mistakes on the circuit board to be corrected without modifying the board.

The index pulse can be used to reset the position counter; this causes the position counter to maintain the absolute encoder position. Otherwise, the position counter maintains the relative position and is never reset.

The velocity capture has a timer to measure equal periods of time. The number of encoder pulses over each time period is accumulated as a measure of the encoder velocity. The running total for the current time period and the final count for the previous time period are available to be read. The final count for the previous time period is usually used as the velocity measure.

The QEI module will generate interrupts when the index pulse is detected, when the velocity timer expires, when the encoder direction changes, and when a phase signal error is detected. These interrupt sources can be individually masked so that only the events of interest cause a processor interrupt.

# 16.2 Functions

# **Functions**

- void ROM QEIConfigure (uint32 t ui32Base, uint32 t ui32Config, uint32 t ui32MaxPosition)
- int32\_t ROM\_QEIDirectionGet (uint32\_t ui32Base)
- void ROM QEIDisable (uint32 t ui32Base)
- void ROM\_QEIEnable (uint32\_t ui32Base)

- bool ROM QEIErrorGet (uint32 t ui32Base)
- void ROM\_QEIIntClear (uint32\_t ui32Base, uint32\_t ui32IntFlags)
- void ROM\_QEIIntDisable (uint32\_t ui32Base, uint32\_t ui32IntFlags)
- void ROM\_QEIIntEnable (uint32\_t ui32Base, uint32\_t ui32IntFlags)
- uint32\_t ROM\_QEIIntStatus (uint32\_t ui32Base, bool bMasked)
- uint32 t ROM QEIPositionGet (uint32 t ui32Base)
- void ROM\_QEIPositionSet (uint32\_t ui32Base, uint32\_t ui32Position)
- void ROM\_QEIVelocityConfigure (uint32\_t ui32Base, uint32\_t ui32PreDiv, uint32\_t ui32Period)
- void ROM QEIVelocityDisable (uint32 t ui32Base)
- void ROM\_QEIVelocityEnable (uint32\_t ui32Base)
- uint32 t ROM QEIVelocityGet (uint32 t ui32Base)

# 16.2.1 Function Documentation

# 16.2.1.1 ROM\_QEIConfigure

Configures the quadrature encoder.

### Prototype:

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_QEITABLE is an array of pointers located at ROM_APITABLE[9].

ROM_QEIConfigure is a function pointer located at ROM_QEITABLE[3].
```

#### Parameters:

ui32Base is the base address of the quadrature encoder module.

*ui32Config* is the configuration for the quadrature encoder. See below for a description of this parameter.

ui32MaxPosition specifies the maximum position value.

### **Description:**

This will configure the operation of the quadrature encoder. The *ui32Config* parameter provides the configuration of the encoder and is the logical OR of several values:

- QEI\_CONFIG\_CAPTURE\_A or QEI\_CONFIG\_CAPTURE\_A\_B to specify if edges on channel A or on both channels A and B should be counted by the position integrator and velocity accumulator.
- QEI\_CONFIG\_NO\_RESET or QEI\_CONFIG\_RESET\_IDX to specify if the position integrator should be reset when the index pulse is detected.
- QEI\_CONFIG\_QUADRATURE or QEI\_CONFIG\_CLOCK\_DIR to specify if quadrature signals are being provided on ChA and ChB, or if a direction signal and a clock are being provided instead.
- QEI\_CONFIG\_NO\_SWAP or QEI\_CONFIG\_SWAP to specify if the signals provided on ChA and ChB should be swapped before being processed.

*ui32MaxPosition* is the maximum value of the position integrator, and is the value used to reset the position capture when in index reset mode and moving in the reverse (negative) direction.

#### Returns:

None.

# 16.2.1.2 ROM QEIDirectionGet

Gets the current direction of rotation.

### Prototype:

```
int32_t
ROM QEIDirectionGet(uint32 t ui32Base)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_QEITABLE is an array of pointers located at ROM_APITABLE[9].
ROM_QEIDirectionGet is a function pointer located at ROM_QEITABLE[5].
```

#### Parameters:

ui32Base is the base address of the quadrature encoder module.

# **Description:**

This returns the current direction of rotation. In this case, current means the most recently detected direction of the encoder; it may not be presently moving but this is the direction it last moved before it stopped.

#### Returns:

Returns 1 if moving in the forward direction or -1 if moving in the reverse direction.

# 16.2.1.3 ROM QEIDisable

Disables the quadrature encoder.

# Prototype:

```
void
ROM QEIDisable(uint32 t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_QEITABLE is an array of pointers located at ROM_APITABLE[9].
ROM_QEIDisable is a function pointer located at ROM_QEITABLE[2].
```

#### Parameters:

ui32Base is the base address of the quadrature encoder module.

# **Description:**

This will disable operation of the quadrature encoder module.

# Returns:

None.

# 16.2.1.4 ROM QEIEnable

Enables the quadrature encoder.

# Prototype:

```
void
ROM_QEIEnable(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_QEITABLE is an array of pointers located at ROM_APITABLE[9].

ROM_QEIEnable is a function pointer located at ROM_QEITABLE[1].
```

#### Parameters:

ui32Base is the base address of the quadrature encoder module.

#### **Description:**

This will enable operation of the quadrature encoder module. It must be configured before it is enabled.

### See also:

ROM\_QEIConfigure()

#### Returns:

None.

# 16.2.1.5 ROM QEIErrorGet

Gets the encoder error indicator.

### Prototype:

```
bool
ROM_QEIErrorGet(uint32_t ui32Base)
```

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_QEITABLE is an array of pointers located at ROM_APITABLE[9].

ROM_QEIErrorGet is a function pointer located at ROM_QEITABLE[6].
```

#### Parameters:

ui32Base is the base address of the quadrature encoder module.

# **Description:**

This returns the error indicator for the quadrature encoder. It is an error for both of the signals of the quadrature input to change at the same time.

### Returns:

Returns true if an error has occurred and false otherwise.

# 16.2.1.6 ROM QEIIntClear

Clears quadrature encoder interrupt sources.

# Prototype:

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_QEITABLE is an array of pointers located at ROM_APITABLE[9].

ROM_QEIIntClear is a function pointer located at ROM_QEITABLE[14].
```

#### Parameters:

ui32Base is the base address of the quadrature encoder module.

ui32IntFlags is a bit mask of the interrupt sources to be cleared. Can be any of the QEI\_INTERROR, QEI\_INTDIR, QEI\_INTTIMER, or QEI\_INTINDEX values.

### **Description:**

The specified quadrature encoder interrupt sources are cleared, so that they no longer assert. This must be done in the interrupt handler to keep it from being called again immediately upon exit.

#### Note:

Because there is a write buffer in the Cortex-M4 processor, it may take several clock cycles before the interrupt source is actually cleared. Therefore, it is recommended that the interrupt source be cleared early in the interrupt handler (as opposed to the very last action) to avoid returning from the interrupt handler before the interrupt source is actually cleared. Failure to do so may result in the interrupt handler being immediately reentered (because the interrupt controller still sees the interrupt source asserted).

#### Returns:

None.

# 16.2.1.7 ROM QEIIntDisable

Disables individual quadrature encoder interrupt sources.

# Prototype:

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_QEITABLE is an array of pointers located at ROM_APITABLE[9].

ROM_QEIIntDisable is a function pointer located at ROM_QEITABLE[12].
```

#### Parameters:

ui32Base is the base address of the quadrature encoder module.

ui32IntFlags is a bit mask of the interrupt sources to be disabled. Can be any of the QEI INTERROR, QEI INTDIR, QEI INTTIMER, or QEI INTINDEX values.

# **Description:**

Disables the indicated quadrature encoder interrupt sources. Only the sources that are enabled can be reflected to the processor interrupt; disabled sources have no effect on the processor.

#### Returns:

None.

# 16.2.1.8 ROM\_QEIIntEnable

Enables individual quadrature encoder interrupt sources.

# Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_QEITABLE is an array of pointers located at ROM_APITABLE[9].

ROM_QEIIntEnable is a function pointer located at ROM_QEITABLE[11].
```

#### Parameters:

ui32Base is the base address of the quadrature encoder module.

ui32IntFlags is a bit mask of the interrupt sources to be enabled. Can be any of the QEI\_INTERROR, QEI\_INTDIR, QEI\_INTTIMER, or QEI\_INTINDEX values.

# Description:

Enables the indicated quadrature encoder interrupt sources. Only the sources that are enabled can be reflected to the processor interrupt; disabled sources have no effect on the processor.

#### Returns:

None.

# 16.2.1.9 ROM QEIIntStatus

Gets the current interrupt status.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_QEITABLE is an array of pointers located at ROM_APITABLE[9].

ROM_QEIIntStatus is a function pointer located at ROM_QEITABLE[13].
```

#### Parameters:

ui32Base is the base address of the quadrature encoder module.

**bMasked** is false if the raw interrupt status is required and true if the masked interrupt status is required.

## **Description:**

This returns the interrupt status for the quadrature encoder module. Either the raw interrupt status or the status of interrupts that are allowed to reflect to the processor can be returned.

#### Returns:

Returns the current interrupt status, enumerated as a bit field of **QEI\_INTERROR**, **QEI\_INTIMER**, and **QEI\_INTINDEX**.

## 16.2.1.10 ROM QEIPositionGet

Gets the current encoder position.

## Prototype:

```
uint32_t
ROM_QEIPositionGet(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_QEITABLE is an array of pointers located at ROM_APITABLE[9].

ROM_QEIPositionGet is a function pointer located at ROM_QEITABLE[0].
```

#### Parameters:

ui32Base is the base address of the quadrature encoder module.

#### **Description:**

This returns the current position of the encoder. Depending upon the configuration of the encoder, and the incident of an index pulse, this value may or may not contain the expected data (that is, if in reset on index mode, if an index pulse has not been encountered, the position counter will not be aligned with the index pulse yet).

#### Returns:

The current position of the encoder.

## 16.2.1.11 ROM QEIPositionSet

Sets the current encoder position.

## Prototype:

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_QEITABLE is an array of pointers located at ROM_APITABLE[9].
ROM_QEIPositionSet is a function pointer located at ROM_QEITABLE[4].
```

## Parameters:

ui32Base is the base address of the quadrature encoder module.ui32Position is the new position for the encoder.

## **Description:**

This sets the current position of the encoder; the encoder position will then be measured relative to this value.

#### Returns:

None.

## 16.2.1.12 ROM\_QEIVelocityConfigure

Configures the velocity capture.

## Prototype:

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_QEITABLE is an array of pointers located at ROM_APITABLE[9].

ROM_QEIVelocityConfigure is a function pointer located at ROM_QEITABLE[9].
```

#### Parameters:

ui32Base is the base address of the quadrature encoder module.

```
ui32PreDiv specifies the predivider applied to the input quadrature signal before it is counted; can be one of QEI_VELDIV_1, QEI_VELDIV_2, QEI_VELDIV_4, QEI_VELDIV_8, QEI_VELDIV_16, QEI_VELDIV_32, QEI_VELDIV_64, or QEI_VELDIV_128.
```

ui32Period specifies the number of clock ticks over which to measure the velocity; must be non-zero.

#### Description:

This will configure the operation of the velocity capture portion of the quadrature encoder. The position increment signal is predivided as specified by *ui32PreDiv* before being accumulated by the velocity capture. The divided signal is accumulated over *ui32Period* system clock before being saved and resetting the accumulator.

#### Returns:

None.

## 16.2.1.13 ROM QEIVelocityDisable

Disables the velocity capture.

## Prototype:

```
void
ROM_QEIVelocityDisable(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_QEITABLE is an array of pointers located at ROM_APITABLE[9].

ROM_QEIVelocityDisable is a function pointer located at ROM_QEITABLE[8].
```

### Parameters:

ui32Base is the base address of the quadrature encoder module.

## **Description:**

This will disable operation of the velocity capture in the quadrature encoder module.

#### Returns:

None.

## 16.2.1.14 ROM QEIVelocityEnable

Enables the velocity capture.

## Prototype:

```
void
ROM_QEIVelocityEnable(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_QEITABLE is an array of pointers located at ROM_APITABLE[9].
ROM_QEIVelocityEnable is a function pointer located at ROM_QEITABLE[7].
```

### Parameters:

ui32Base is the base address of the quadrature encoder module.

### **Description:**

This will enable operation of the velocity capture in the quadrature encoder module. It must be configured before it is enabled. Velocity capture will not occur if the quadrature encoder is not enabled.

#### See also:

```
ROM_QEIVelocityConfigure() and ROM_QEIEnable()
```

### Returns:

None.

## 16.2.1.15 ROM QEIVelocityGet

Gets the current encoder speed.

## Prototype:

```
uint32_t
ROM_QEIVelocityGet(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_QEITABLE is an array of pointers located at ROM_APITABLE[9].

ROM_QEIVelocityGet is a function pointer located at ROM_QEITABLE[10].
```

#### **Parameters:**

ui32Base is the base address of the quadrature encoder module.

## Description:

This returns the current speed of the encoder. The value returned is the number of pulses detected in the specified time period; this number can be multiplied by the number of time periods per second and divided by the number of pulses per revolution to obtain the number of revolutions per second.

## Returns:

Returns the number of pulses captured in the given time period.

# 17 Synchronous Serial Interface (SSI)

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## 17.1 Introduction

The Synchronous Serial Interface (SSI) module provides the functionality for synchronous serial communications with peripheral devices, and can be configured to use either the Motorola® SPI™, National Semiconductor® Microwire, or the Texas Instruments® synchronous serial interface frame formats. The size of the data frame is also configurable, and can be set to be between 4 and 16 bits, inclusive.

The SSI module performs serial-to-parallel data conversion on data received from a peripheral device, and parallel-to-serial conversion on data transmitted to a peripheral device. The TX and RX paths are buffered with internal FIFOs allowing up to eight 16-bit values to be stored independently.

The SSI module can be configured as either a master or a slave device. As a slave device, the SSI module can also be configured to disable its output, which allows a master device to be coupled with multiple slave devices.

The SSI module also includes a programmable bit rate clock divider and prescaler to generate the output serial clock derived from the SSI module's input clock. Bit rates are generated based on the input clock and the maximum bit rate supported by the connected peripheral.

For devices that include a DMA controller, the SSI module also provides a DMA interface to facilitate data transfer via DMA.

## 17.2 Functions

## **Functions**

- bool ROM SSIBusy (uint32 t ui32Base)
- uint32 t ROM SSIClockSourceGet (uint32 t ui32Base)
- void ROM SSIClockSourceSet (uint32 t ui32Base, uint32 t ui32Source)
- void ROM\_SSIConfigSetExpClk (uint32\_t ui32Base, uint32\_t ui32SIClk, uint32\_t ui32Protocol, uint32\_t ui32Mode, uint32\_t ui32BitRate, uint32\_t ui32DataWidth)
- void ROM SSIDataGet (uint32 t ui32Base, uint32 t \*pui32Data)
- int32\_t ROM\_SSIDataGetNonBlocking (uint32\_t ui32Base, uint32\_t \*pui32Data)
- void ROM SSIDataPut (uint32 t ui32Base, uint32 t ui32Data)
- int32 t ROM SSIDataPutNonBlocking (uint32 t ui32Base, uint32 t ui32Data)
- void ROM SSIDisable (uint32 t ui32Base)
- void ROM\_SSIDMADisable (uint32\_t ui32Base, uint32\_t ui32DMAFlags)
- void ROM SSIDMAEnable (uint32 t ui32Base, uint32 t ui32DMAFlags)
- void ROM\_SSIEnable (uint32\_t ui32Base)
- void ROM SSIIntClear (uint32 t ui32Base, uint32 t ui32IntFlags)
- void ROM\_SSIIntDisable (uint32\_t ui32Base, uint32\_t ui32IntFlags)

- void ROM\_SSIIntEnable (uint32\_t ui32Base, uint32\_t ui32IntFlags)
- uint32\_t ROM\_SSIIntStatus (uint32\_t ui32Base, bool bMasked)
- void ROM UpdateSSI (void)

## 17.2.1 Function Documentation

## 17.2.1.1 ROM\_SSIBusy

Determines whether the SSI transmitter is busy or not.

## Prototype:

```
bool
ROM_SSIBusy(uint32_t ui32Base)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_SSITABLE is an array of pointers located at ROM_APITABLE[2].
ROM_SSIBusy is a function pointer located at ROM_SSITABLE[14].
```

#### Parameters:

ui32Base is the base address of the SSI port.

## **Description:**

Allows the caller to determine whether all transmitted bytes have cleared the transmitter hardware. If **false** is returned, then the transmit FIFO is empty and all bits of the last transmitted word have left the hardware shift register.

#### Returns:

Returns **true** if the SSI is transmitting or **false** if all transmissions are complete.

## 17.2.1.2 ROM SSIClockSourceGet

Gets the data clock source for the specified SSI peripheral.

## Prototype:

```
uint32_t
ROM_SSIClockSourceGet(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SSITABLE is an array of pointers located at ROM_APITABLE[2].

ROM_SSIClockSourceGet is a function pointer located at ROM_SSITABLE[15].
```

## Parameters:

ui32Base is the base address of the SSI port.

### **Description:**

This function returns the data clock source for the specified SSI. The possible data clock source are the system clock (SSI\_CLOCK\_SYSTEM) or the precision internal oscillator (SSI\_CLOCK\_PIOSC).

None.

## 17.2.1.3 ROM SSIClockSourceSet

Sets the data clock source for the specified SSI peripheral.

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SSITABLE is an array of pointers located at ROM_APITABLE[2].

ROM_SSIClockSourceSet is a function pointer located at ROM_SSITABLE[16].
```

#### Parameters:

```
ui32Base is the base address of the SSI port.ui32Source is the baud clock source for the SSI.
```

## **Description:**

This function allows the baud clock source for the SSI to be selected. The possible clock source are the system clock (SSI\_CLOCK\_SYSTEM) or the precision internal oscillator (SSI\_CLOCK\_PIOSC).

Changing the baud clock source will change the data rate generated by the SSI. Therefore, the data rate should be reconfigured after any change to the SSI clock source.

## Returns:

None.

## 17.2.1.4 ROM SSIConfigSetExpClk

Configures the synchronous serial interface.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SSITABLE is an array of pointers located at ROM_APITABLE[2].

ROM_SSIConfigSetExpClk is a function pointer located at ROM_SSITABLE[1].
```

### Parameters:

ui32Base specifies the SSI module base address.

```
ui32SSICIk is the rate of the clock supplied to the SSI module.
```

ui32Protocol specifies the data transfer protocol.

ui32Mode specifies the mode of operation.

ui32BitRate specifies the clock rate.

*ui32DataWidth* specifies number of bits transferred per frame.

## **Description:**

This function configures the synchronous serial interface. It sets the SSI protocol, mode of operation, bit rate, and data width.

The *ui32Protocol* parameter defines the data frame format. The *ui32Protocol* parameter can be one of the following values: SSI\_FRF\_MOTO\_MODE\_0, SSI\_FRF\_MOTO\_MODE\_1, SSI\_FRF\_MOTO\_MODE\_2, SSI\_FRF\_MOTO\_MODE\_3, SSI\_FRF\_TI, or SSI\_FRF\_NMW. The Motorola frame formats imply the following polarity and phase configurations:

```
        Polarity
        Phase
        Mode

        0
        0
        SSI_FRF_MOTO_MODE_0

        0
        1
        SSI_FRF_MOTO_MODE_1

        1
        0
        SSI_FRF_MOTO_MODE_2

        1
        1
        SSI_FRF_MOTO_MODE_3
```

The *ui32Mode* parameter defines the operating mode of the SSI module. The SSI module can operate as a master or slave; if a slave, the SSI can be configured to disable output on its serial output line. The *ui32Mode* parameter can be one of the following values: **SSI MODE MASTER, SSI MODE SLAVE**, or **SSI MODE SLAVE OD**.

The *ui32BitRate* parameter defines the bit rate for the SSI. This bit rate must satisfy the following clock ratio criteria:

```
■ FSSI >= 2 * bit rate (master mode)
```

■ FSSI >= 12 \* bit rate (slave modes)

where FSSI is the frequency of the clock supplied to the SSI module.

The *ui32DataWidth* parameter defines the width of the data transfers, and can be a value between 4 and 16, inclusive.

The peripheral clock is the same as the processor clock. This is the value returned by ROM\_SysCtlClockGet(), or it can be explicitly hard-coded if it is constant and known (to save the code/execution overhead of a call to ROM\_SysCtlClockGet()).

#### Returns:

None.

## 17.2.1.5 ROM SSIDataGet

Gets a data element from the SSI receive FIFO.

## Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_SSITABLE is an array of pointers located at ROM_APITABLE[2].
ROM_SSIDataGet is a function pointer located at ROM_SSITABLE[9].
```

#### Parameters:

ui32Base specifies the SSI module base address.

pui32Data is a pointer to a storage location for data that was received over the SSI interface.

#### **Description:**

This function gets received data from the receive FIFO of the specified SSI module and places that data into the location specified by the *pui32Data* parameter.

#### Note:

Only the lower N bits of the value written to *pui32Data* contain valid data, where N is the data width as configured by ROM\_SSIConfigSetExpClk(). For example, if the interface is configured for 8-bit data width, only the lower 8 bits of the value written to *pui32Data* contain valid data.

#### Returns:

None.

## 17.2.1.6 ROM SSIDataGetNonBlocking

Gets a data element from the SSI receive FIFO.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SSITABLE is an array of pointers located at ROM_APITABLE[2].

ROM_SSIDataGetNonBlocking is a function pointer located at ROM_SSITABLE[10].
```

#### Parameters:

ui32Base specifies the SSI module base address.

pui32Data is a pointer to a storage location for data that was received over the SSI interface.

### **Description:**

This function gets received data from the receive FIFO of the specified SSI module and places that data into the location specified by the *ui32Data* parameter. If there is no data in the FIFO, then this function returns a zero.

### Note:

Only the lower N bits of the value written to *pui32Data* contain valid data, where N is the data width as configured by ROM\_SSIConfigSetExpClk(). For example, if the interface is configured for 8-bit data width, only the lower 8 bits of the value written to *pui32Data* contain valid data.

## Returns:

Returns the number of elements read from the SSI receive FIFO.

## 17.2.1.7 ROM SSIDataPut

Puts a data element into the SSI transmit FIFO.

## Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_SSITABLE is an array of pointers located at ROM_APITABLE[2].
ROM_SSIDataPut is a function pointer located at ROM_SSITABLE[0].
```

#### Parameters:

ui32Base specifies the SSI module base address.ui32Data is the data to be transmitted over the SSI interface.

## **Description:**

This function places the supplied data into the transmit FIFO of the specified SSI module.

#### Note:

The upper 32 - N bits of the *ui32Data* are discarded by the hardware, where N is the data width as configured by ROM\_SSIConfigSetExpClk(). For example, if the interface is configured for 8-bit data width, the upper 24 bits of *ui32Data* are discarded.

### Returns:

None.

## 17.2.1.8 ROM SSIDataPutNonBlocking

Puts a data element into the SSI transmit FIFO.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SSITABLE is an array of pointers located at ROM_APITABLE[2].

ROM_SSIDataPutNonBlocking is a function pointer located at ROM_SSITABLE[8].
```

#### **Parameters:**

ui32Base specifies the SSI module base address.ui32Data is the data to be transmitted over the SSI interface.

## **Description:**

This function places the supplied data into the transmit FIFO of the specified SSI module. If there is no space in the FIFO, then this function returns a zero.

#### Note:

The upper 32 - N bits of the *ui32Data* are discarded by the hardware, where N is the data width as configured by ROM\_SSIConfigSetExpClk(). For example, if the interface is configured for 8-bit data width, the upper 24 bits of *ui32Data* are discarded.

#### Returns:

Returns the number of elements written to the SSI transmit FIFO.

## 17.2.1.9 ROM SSIDisable

Disables the synchronous serial interface.

## Prototype:

```
void
ROM_SSIDisable(uint32_t ui32Base)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_SSITABLE is an array of pointers located at ROM_APITABLE[2].
ROM_SSIDisable is a function pointer located at ROM_SSITABLE[3].
```

#### Parameters:

ui32Base specifies the SSI module base address.

## **Description:**

This function disables operation of the synchronous serial interface.

### Returns:

None.

## 17.2.1.10 ROM SSIDMADisable

Disable SSI DMA operation.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SSITABLE is an array of pointers located at ROM_APITABLE[2].

ROM_SSIDMADisable is a function pointer located at ROM_SSITABLE[13].
```

## Parameters:

```
ui32Base is the base address of the SSI port.ui32DMAFlags is a bit mask of the DMA features to disable.
```

## **Description:**

This function is used to disable SSI DMA features that were enabled by ROM\_SSIDMAEnable(). The specified SSI DMA features are disabled. The *ui32DMAFlags* parameter is the logical OR of any of the following values:

- SSI DMA RX disable DMA for receive
- SSI\_DMA\_TX disable DMA for transmit

None.

## 17.2.1.11 ROM\_SSIDMAEnable

Enable SSI DMA operation.

## Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SSITABLE is an array of pointers located at ROM_APITABLE[2].

ROM_SSIDMAEnable is a function pointer located at ROM_SSITABLE[12].
```

#### Parameters:

```
ui32Base is the base address of the SSI port.ui32DMAFlags is a bit mask of the DMA features to enable.
```

## Description:

The specified SSI DMA features are enabled. The SSI can be configured to use DMA for transmit and/or receive data transfers. The *ui32DMAFlags* parameter is the logical OR of any of the following values:

- SSI DMA RX enable DMA for receive
- SSI\_DMA\_TX enable DMA for transmit

### Note:

The uDMA controller must also be set up before DMA can be used with the SSI.

### Returns:

None.

## 17.2.1.12 ROM SSIEnable

Enables the synchronous serial interface.

## Prototype:

```
void
ROM_SSIEnable(uint32_t ui32Base)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_SSITABLE is an array of pointers located at ROM_APITABLE[2].
ROM_SSIEnable is a function pointer located at ROM_SSITABLE[2].
```

## Parameters:

ui32Base specifies the SSI module base address.

## **Description:**

This function enables operation of the synchronous serial interface. The synchronous serial interface must be configured before it is enabled.

#### Returns:

None.

## 17.2.1.13 ROM\_SSIIntClear

Clears SSI interrupt sources.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SSITABLE is an array of pointers located at ROM_APITABLE[2].

ROM_SSIIntClear is a function pointer located at ROM_SSITABLE[7].
```

#### Parameters:

ui32Base specifies the SSI module base address.ui32IntFlags is a bit mask of the interrupt sources to be cleared.

### **Description:**

The specified SSI interrupt sources are cleared so that they no longer assert. This function must be called in the interrupt handler to keep the interrupts from being recognized again immediately upon exit. The *ui32IntFlags* parameter can consist of either or both the **SSI\_RXTO** and **SSI\_RXOR** values.

### Note:

Because there is a write buffer in the Cortex-M4 processor, it may take several clock cycles before the interrupt source is actually cleared. Therefore, it is recommended that the interrupt source be cleared early in the interrupt handler (as opposed to the very last action) to avoid returning from the interrupt handler before the interrupt source is actually cleared. Failure to do so may result in the interrupt handler being immediately reentered (because the interrupt controller still sees the interrupt source asserted).

#### Returns:

None.

## 17.2.1.14 ROM SSIIntDisable

Disables individual SSI interrupt sources.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SSITABLE is an array of pointers located at ROM_APITABLE[2].

ROM_SSIIntDisable is a function pointer located at ROM_SSITABLE[5].
```

#### Parameters:

ui32Base specifies the SSI module base address.ui32IntFlags is a bit mask of the interrupt sources to be disabled.

## **Description:**

Disables the indicated SSI interrupt sources. The *ui32IntFlags* parameter can be any of the **SSI TXFF**, **SSI RXFP**, **SSI RXTO**, or **SSI RXOR** values.

### Returns:

None.

## 17.2.1.15 ROM\_SSIIntEnable

Enables individual SSI interrupt sources.

## Prototype:

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_SSITABLE is an array of pointers located at ROM_APITABLE[2].
ROM_SSIIntEnable is a function pointer located at ROM_SSITABLE[4].
```

### Parameters:

```
ui32Base specifies the SSI module base address.ui32IntFlags is a bit mask of the interrupt sources to be enabled.
```

#### **Description:**

Enables the indicated SSI interrupt sources. Only the sources that are enabled can be reflected to the processor interrupt; disabled sources have no effect on the processor. The *ui32IntFlags* parameter can be any of the **SSI\_TXFF**, **SSI\_RXFF**, **SSI\_RXTO**, or **SSI\_RXOR** values.

## Returns:

None.

## 17.2.1.16 ROM SSIIntStatus

Gets the current interrupt status.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SSITABLE is an array of pointers located at ROM_APITABLE[2].

ROM_SSIIntStatus is a function pointer located at ROM_SSITABLE[6].
```

### Parameters:

ui32Base specifies the SSI module base address.

**bMasked** is **false** if the raw interrupt status is required or **true** if the masked interrupt status is required.

## **Description:**

This function returns the interrupt status for the SSI module. Either the raw interrupt status or the status of interrupts that are allowed to reflect to the processor can be returned.

#### Returns:

The current interrupt status, enumerated as a bit field of SSI\_TXFF, SSI\_RXFF, SSI\_RXTO, and SSI\_RXOR.

## 17.2.1.17 ROM UpdateSSI

Starts an update over the SSI0 interface.

### Prototype:

```
void
ROM_UpdateSSI(void)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_SSITABLE is an array of pointers located at ROM_APITABLE[2].
ROM_UpdateSSI is a function pointer located at ROM_SSITABLE[11].
```

## Description:

Calling this function commences an update of the firmware via the SSI0 interface. This function assumes that the SSI0 interface has already been configured and is currently oprational.

#### Returns:

Never returns.

# 18 System Control

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## 18.1 Introduction

System control determines the overall operation of the device. It controls the clocking of the device, the set of peripherals that are enabled, configuration of the device and its resets, and provides information about the device.

The device has a set of read-only registers that indicate the size of the memories, the peripherals that are present, and the pins that are present for peripherals that have a varying number of pins. This information can be used to write adaptive software that will run on more than one device.

The device can be clocked from one of five sources: an external oscillator, the main oscillator, the internal oscillator, the internal oscillator divided by four, or the PLL. The PLL can use any of the four oscillators as its input. When using the PLL, the input clock frequency is constrained to specific frequencies between 5 MHz and 25 MHz (that is, the standard crystal frequencies in that range). When direct clocking with an external oscillator or the main oscillator, the frequency is constrained to between 0 Hz and 80 MHz (depending on the device). The internal oscillator is 16 MHz, +/- 1%; its frequency will vary by device, with voltage, and with temperature.

Three modes of operation are supported: run mode, sleep mode, and deep-sleep mode. In run mode, the processor is actively executing code. In sleep mode, the clocking of the device is unchanged but the processor no longer executes code (and is no longer clocked). In deep-sleep mode, the clocking of the device may change (depending upon the run mode clock configuration) and the processor no longer executes code (and is no longer clocked). An interrupt will return the device to run mode from one of the sleep modes; the sleep modes are entered upon request from the code.

There are several system events that, when detected, will cause system control to reset the device. These events are the input voltage dropping too low, the LDO voltage dropping too low, an external reset, a software reset request, and a watchdog timeout. The properties of some of these events can be configured, and the reason for a reset can be determined from system control.

Each peripheral in the device can be individually enabled, disabled, or reset. Additionally, the set of peripherals that remain enabled during sleep mode and deep-sleep mode can be configured, allowing custom sleep and deep-sleep modes to be defined. Care must be taken with deep-sleep mode, though, since in this mode the PLL is no longer used and the system is clocked by the input crystal. Peripherals that depend upon a particular input clock rate (such as a timer) will not operate as expected in deep-sleep mode due to the clock rate change; these peripherals must either be reconfigured upon entry to and exit from deep-sleep mode, or simply not enabled in deep-sleep mode.

There are various system events that, when detected, will cause system control to generate a processor interrupt. These events are the PLL achieving lock, the internal LDO current limit being exceeded, the internal oscillator failing, the main oscillator failing, the input voltage dropping too low, the internal LDO voltage dropping too low, and the PLL failing. Each of these interrupts can be individually enabled or disabled, and the sources must be cleared by the interrupt handler when they occur.

## 18.2 Functions

## **Functions**

- uint32 t ROM SysCtlClockGet (void)
- void ROM\_SysCtlClockSet (uint32\_t ui32Config)
- void ROM\_SysCtlDeepSleep (void)
- void ROM\_SysCtlDeepSleepClockSet (uint32\_t ui32Config)
- void ROM\_SysCtlDelay (uint32\_t ui32Count)
- uint32\_t ROM\_SysCtlFlashSizeGet (void)
- void ROM\_SysCtlIntClear (uint32\_t ui32Ints)
- void ROM SysCtlIntDisable (uint32 t ui32Ints)
- void ROM\_SysCtlIntEnable (uint32\_t ui32Ints)
- uint32 t ROM SysCtlIntStatus (bool bMasked)
- void ROM SysCtlMOSCConfigSet (uint32 t ui32Config)
- void ROM\_SysCtlPeripheralClockGating (bool bEnable)
- void ROM SysCtlPeripheralDeepSleepDisable (uint32 t ui32Peripheral)
- void ROM SysCtlPeripheralDeepSleepEnable (uint32 t ui32Peripheral)
- void ROM\_SysCtlPeripheralDisable (uint32\_t ui32Peripheral)
- void ROM SysCtlPeripheralEnable (uint32 t ui32Peripheral)
- void ROM\_SysCtlPeripheralPowerOff (uint32\_t ui32Peripheral)
- void ROM SysCtlPeripheralPowerOn (uint32 t ui32Peripheral)
- bool ROM SysCtlPeripheralPresent (uint32 t ui32Peripheral)
- bool ROM\_SysCtlPeripheralReady (uint32\_t ui32Peripheral)
- void ROM SysCtlPeripheralReset (uint32 t ui32Peripheral)
- void ROM\_SysCtlPeripheralSleepDisable (uint32\_t ui32Peripheral)
- void ROM SysCtlPeripheralSleepEnable (uint32 t ui32Peripheral)
- uint32 t ROM SysCtlPIOSCCalibrate (uint32 t ui32Type)
- uint32 t ROM SysCtlPWMClockGet (void)
- void ROM\_SysCtlPWMClockSet (uint32\_t ui32Config)
- void ROM SysCtlReset (void)
- void ROM SysCtlResetCauseClear (uint32 t ui32Causes)
- uint32 t ROM SysCtlResetCauseGet (void)
- void ROM\_SysCtlSleep (void)
- uint32 t ROM SysCtISRAMSizeGet (void)
- void ROM\_SysCtlUSBPLLDisable (void)
- void ROM SysCtlUSBPLLEnable (void)

## 18.2.1 Function Documentation

## 18.2.1.1 ROM SysCtlClockGet

Gets the processor clock rate.

## **Prototype:**

uint32\_t
ROM\_SysCtlClockGet(void)

#### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_SYSCTLTABLE is an array of pointers located at ROM\_APITABLE[13].

ROM\_SysCtlClockGet is a function pointer located at ROM\_SYSCTLTABLE[24].

## **Description:**

This function determines the clock rate of the processor clock. This is also the clock rate of all the peripheral modules (with the exception of PWM, which has its own clock divider).

#### Note:

This will not return accurate results if ROM\_SysCtlClockSet() has not been called to configure the clocking of the device, or if the device is directly clocked from a crystal (or a clock source) that is not one of the supported crystal frequencies. In the later case, this function should be modified to directly return the correct system clock rate.

#### Returns:

The processor clock rate.

## 18.2.1.2 ROM\_SysCtlClockSet

Sets the clocking of the device.

## Prototype:

void
ROM\_SysCtlClockSet(uint32\_t ui32Config)

#### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_SYSCTLTABLE is an array of pointers located at ROM\_APITABLE[13].

ROM\_SYSCtlClockSet is a function pointer located at ROM\_SYSCTLTABLE[23].

#### Parameters:

ui32Config is the required configuration of the device clocking.

### **Description:**

This function configures the clocking of the device. The input crystal frequency, oscillator to be used, use of the PLL, and the system clock divider are all configured with this function.

The *ui32Config* parameter is the logical OR of several different values, many of which are grouped into sets where only one can be chosen.

The system clock divider is chosen with one of the following values: SYSCTL\_SYSDIV\_1, SYSCTL\_SYSDIV\_2, SYSCTL\_SYSDIV\_3, ... SYSCTL\_SYSDIV\_64.

The use of the PLL is chosen with either SYSCTL USE PLL or SYSCTL USE OSC.

The external crystal frequency is chosen with one of the following values: SYSCTL\_XTAL\_1MHZ, SYSCTL\_XTAL\_1\_84MHZ, SYSCTL\_XTAL\_2MHZ, SYSCTL\_XTAL\_2\_45MHZ, SYSCTL\_XTAL\_3\_57MHZ, SYSCTL\_XTAL\_3\_68MHZ, SYSCTL\_XTAL\_4MHZ, SYSCTL\_XTAL\_4 09MHZ, SYSCTL\_XTAL\_4 91MHZ,

SYSCTL XTAL 5MHZ, SYSCTL XTAL 5 12MHZ, SYSCTL XTAL 6MHZ, SYSCTL XTAL 6 14MHZ, SYSCTL\_XTAL 7 37MHZ. SYSCTL XTAL 8MHZ. SYSCTL XTAL 8 19MHZ, SYSCTL XTAL 10MHZ, SYSCTL XTAL 12MHZ, SYSCTL\_XTAL\_14\_3MHZ, SYSCTL\_XTAL\_12\_2MHZ, SYSCTL\_XTAL\_13\_5MHZ, SYSCTL XTAL 16MHZ, SYSCTL XTAL 16 3MHZ. Values below or **SYSCTL XTAL 3 57MHZ** are not valid when the PLL is in operation.

The oscillator source is chosen with one of the following values: SYSCTL\_OSC\_MAIN, SYSCTL\_OSC\_INT, SYSCTL\_OSC\_INT4, SYSCTL\_OSC\_EXT32, or SYSCTL\_OSC\_INT30. SYSCTL\_OSC\_EXT32 is only available when the hibernate module has been enabled.

The internal and main oscillators are disabled with the SYSCTL\_INT\_OSC\_DIS and SYSCTL\_MAIN\_OSC\_DIS flags, respectively. The external oscillator must be enabled in order to use an external clock source. Note that attempts to disable the oscillator used to clock the device is prevented by the hardware.

To clock the system from an external source (such as an external crystal oscillator), use SYSCTL\_USE\_OSC | SYSCTL\_OSC\_MAIN. To clock the system from the main oscillator, use SYSCTL\_USE\_OSC | SYSCTL\_OSC\_MAIN. To clock the system from the PLL, use SYSCTL\_USE\_PLL | SYSCTL\_OSC\_MAIN, and select the appropriate crystal with one of the SYSCTL\_XTAL\_xxx values.

#### Note:

If selecting the PLL as the system clock source (that is, via SYSCTL\_USE\_PLL), this function will poll the PLL lock interrupt to determine when the PLL has locked. If an interrupt handler for the system control interrupt is in place, and it responds to and clears the PLL lock interrupt, this function will delay until its timeout has occurred instead of completing as soon as PLL lock is achieved.

## Returns:

None.

## 18.2.1.3 ROM SysCtlDeepSleep

Puts the processor into deep-sleep mode.

#### Prototype:

void

ROM\_SysCtlDeepSleep(void)

### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_SYSCTLTABLE is an array of pointers located at ROM\_APITABLE[13].

ROM\_SysCtlDeepSleep is a function pointer located at ROM\_SYSCTLTABLE[20].

### **Description:**

This function places the processor into deep-sleep mode; it will not return until the processor returns to run mode. The peripherals that are enabled via ROM\_SysCtlPeripheralDeepSleepEnable() continue to operate and can wake up the processor (if automatic clock gating is enabled with ROM\_SysCtlPeripheralClockGating(), otherwise all peripherals continue to operate).

#### Returns:

None.

## 18.2.1.4 ROM SysCtlDeepSleepClockSet

Sets the clocking of the device while in deep-sleep mode.

## Prototype:

```
void
ROM SysCtlDeepSleepClockSet(uint32 t ui32Config)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSCTLTABLE is an array of pointers located at ROM_APITABLE[13].

ROM_SysCtlDeepSleepClockSet is a function pointer located at ROM_SYSCTLTABLE[46].
```

#### Parameters:

ui32Config is the required configuration of the device clocking while in deep-sleep mode.

## Description:

This function configures the clocking of the device while in deep-sleep mode. The oscillator to be used and the system clock divider are configured with this function.

The *ui32Config* parameter is the logical OR of the following values:

The system clock divider is chosen with one of the following values: SYSCTL\_DSLP\_DIV\_1, SYSCTL\_DSLP\_DIV\_2, SYSCTL\_DSLP\_DIV\_3, ... SYSCTL\_DSLP\_DIV\_64.

The oscillator source is chosen with one of the following values: SYSCTL\_DSLP\_OSC\_MAIN, SYSCTL\_DSLP\_OSC\_INT30, or SYSCTL\_DSLP\_OSC\_EXT32. SYSCTL\_OSC\_EXT32 is only available on devices with the hibernate module, and then only when the hibernate module has been enabled.

The precision internal oscillator can be powered down in deep-sleep mode by specifying **SYSCTL\_DSLP\_PIOSC\_PD**. If it is required for operation while in deep-sleep (based on other configuration settings), it will not be powered down.

### Returns:

None.

## 18.2.1.5 ROM SysCtlDelay

Provides a small delay.

### Prototype:

```
void
ROM_SysCtlDelay(uint32_t ui32Count)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSCTLTABLE is an array of pointers located at ROM_APITABLE[13].

ROM_SysCtlDelay is a function pointer located at ROM_SYSCTLTABLE[34].
```

#### Parameters:

*ui32Count* is the number of delay loop iterations to perform.

## **Description:**

This function provides a means of generating a constant length delay. It is written in assembly to keep the delay consistent across tool chains, avoiding the need to tune the delay based on the tool chain in use.

The loop takes 3 cycles/loop.

#### Returns:

None.

## 18.2.1.6 ROM\_SysCtlFlashSizeGet

Gets the size of the flash.

## Prototype:

```
uint32_t
ROM_SysCtlFlashSizeGet(void)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSCTLTABLE is an array of pointers located at ROM_APITABLE[13].

ROM_SysCtlFlashSizeGet is a function pointer located at ROM_SYSCTLTABLE[2].
```

## **Description:**

This function determines the size of the flash.

#### Returns:

The total number of bytes of flash.

## 18.2.1.7 ROM\_SysCtlIntClear

Clears system control interrupt sources.

## Prototype:

```
void
ROM_SysCtlIntClear(uint32_t ui32Ints)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSCTLTABLE is an array of pointers located at ROM_APITABLE[13].

ROM_SysCtlIntClear is a function pointer located at ROM_SYSCTLTABLE[15].
```

#### Parameters:

```
ui32Ints is a bit mask of the interrupt sources to be cleared. Must be a logical OR of
SYSCTL_INT_PLL_LOCK, SYSCTL_INT_CUR_LIMIT, SYSCTL_INT_IOSC_FAIL,
SYSCTL_INT_MOSC_FAIL, SYSCTL_INT_POR, SYSCTL_INT_BOR, and/or
SYSCTL_INT_PLL_FAIL.
```

## Description:

The specified system control interrupt sources are cleared, so that they no longer assert. This must be done in the interrupt handler to keep it from being called again immediately upon exit.

#### Note:

Because there is a write buffer in the Cortex-M4 processor, it may take several clock cycles before the interrupt source is actually cleared. Therefore, it is recommended that the interrupt source be cleared early in the interrupt handler (as opposed to the very last action) to avoid returning from the interrupt handler before the interrupt source is actually cleared. Failure to do so may result in the interrupt handler being immediately reentered (because the interrupt controller still sees the interrupt source asserted).

#### Returns:

None.

## 18.2.1.8 ROM\_SysCtlIntDisable

Disables individual system control interrupt sources.

## Prototype:

```
void
ROM_SysCtlIntDisable(uint32_t ui32Ints)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSCTLTABLE is an array of pointers located at ROM_APITABLE[13].

ROM_SYSCTLINEDisable is a function pointer located at ROM_SYSCTLTABLE[14].
```

#### Parameters:

```
ui32Ints is a bit mask of the interrupt sources to be disabled. Must be a logical OR of
SYSCTL_INT_PLL_LOCK, SYSCTL_INT_CUR_LIMIT, SYSCTL_INT_IOSC_FAIL,
SYSCTL_INT_MOSC_FAIL, SYSCTL_INT_POR, SYSCTL_INT_BOR, and/or
SYSCTL_INT_PLL_FAIL.
```

## **Description:**

Disables the indicated system control interrupt sources. Only the sources that are enabled can be reflected to the processor interrupt; disabled sources have no effect on the processor.

#### Returns:

None.

## 18.2.1.9 ROM SysCtlIntEnable

Enables individual system control interrupt sources.

## Prototype:

```
void
ROM_SysCtlIntEnable(uint32_t ui32Ints)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_SYSCTLTABLE is an array of pointers located at ROM_APITABLE [13].
ROM_SysCtlIntEnable is a function pointer located at ROM_SYSCTLTABLE [13].
```

### Parameters:

ui32Ints is a bit mask of the interrupt sources to be enabled. Must be a logical OR of SYSCTL\_INT\_PLL\_LOCK, SYSCTL\_INT\_CUR\_LIMIT, SYSCTL\_INT\_IOSC\_FAIL, SYSCTL\_INT\_MOSC\_FAIL, SYSCTL\_INT\_POR, SYSCTL\_INT\_BOR, and/or SYSCTL\_INT\_PLL\_FAIL.

## **Description:**

Enables the indicated system control interrupt sources. Only the sources that are enabled can be reflected to the processor interrupt; disabled sources have no effect on the processor.

### Returns:

None.

## 18.2.1.10 ROM\_SysCtlIntStatus

Gets the current interrupt status.

## Prototype:

```
uint32_t
ROM_SysCtlIntStatus(bool bMasked)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSCTLTABLE is an array of pointers located at ROM_APITABLE[13].

ROM_SysCtlIntStatus is a function pointer located at ROM_SYSCTLTABLE[16].
```

#### Parameters:

**bMasked** is false if the raw interrupt status is required and true if the masked interrupt status is required.

## **Description:**

This returns the interrupt status for the system controller. Either the raw interrupt status or the status of interrupts that are allowed to reflect to the processor can be returned.

### Returns:

```
The current interrupt status, enumerated as a bit field of SYSCTL_INT_PLL_LOCK, SYSCTL_INT_CUR_LIMIT, SYSCTL_INT_IOSC_FAIL, SYSCTL_INT_MOSC_FAIL, SYSCTL_INT_POR, SYSCTL_INT_BOR, and SYSCTL_INT_PLL_FAIL.
```

## 18.2.1.11 ROM SysCtlMOSCConfigSet

Sets the configuration of the main oscillator (MOSC) control.

## Prototype:

void

ROM\_SysCtlMOSCConfigSet(uint32\_t ui32Config)

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSCTLTABLE is an array of pointers located at ROM_APITABLE[13].

ROM_SysCtlMOSCConfigSet is a function pointer located at ROM_SYSCTLTABLE[44].
```

### Parameters:

*ui32Config* is the required configuration of the MOSC control.

#### **Description:**

This function configures the control of the main oscillator. The *ui32Config* is specified as follows:

- SYSCTL\_MOSC\_VALIDATE enables the MOSC verification circuit that detects a failure of the main oscillator (such as a loss of the clock).
- SYSCTL\_MOSC\_INTERRUPT indicates that a MOSC failure should generate an interrupt instead of resetting the processor.
- SYSCTL\_MOSC\_NO\_XTAL indicates that there is no crystal connected to the OSC0/OSC1 pins, allowing power consumption to be reduced.

#### Returns:

None.

## 18.2.1.12 ROM\_SysCtlPeripheralClockGating

Controls peripheral clock gating in sleep and deep-sleep mode.

## Prototype:

void

ROM\_SysCtlPeripheralClockGating(bool bEnable)

## **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_SYSCTLTABLE is an array of pointers located at ROM\_APITABLE [13].

ROM\_SysCtlPeripheralClockGating is a function pointer located at ROM\_SYSCTLTABLE[12].

#### Parameters:

**bEnable** is a boolean that is **true** if the sleep and deep-sleep peripheral configuration should be used and **false** if not.

## **Description:**

This function controls how peripherals are clocked when the processor goes into sleep or deep-sleep mode. By default, the peripherals are clocked the same as in run mode; if peripheral clock gating is enabled they are clocked according to the configuration set by ROM\_SysCtlPeripheralSleepEnable(), ROM\_SysCtlPeripheralSleepDisable(), ROM\_SysCtlPeripheralDeepSleepDisable().

### Returns:

None.

## 18.2.1.13 ROM SysCtlPeripheralDeepSleepDisable

Disables a peripheral in deep-sleep mode.

### Prototype:

void

ROM\_SysCtlPeripheralDeepSleepDisable(uint32\_t ui32Peripheral)

## **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_SYSCTLTABLE is an array of pointers located at ROM\_APITABLE[13].

ROM\_SYSCTLTABLE[11].

ROM\_SYSCTLTABLE[11].

#### Parameters:

ui32Peripheral is the peripheral to disable in deep-sleep mode.

### **Description:**

This function causes a peripheral to stop operating when the processor goes into deep-sleep mode. Disabling peripherals while in deep-sleep mode helps to lower the current draw of the device, and can keep peripherals that require a particular clock frequency from operating when the clock changes as a result of entering deep-sleep mode. If enabled (via ROM\_SysCtlPeripheralEnable()), the peripheral will automatically resume operation when the processor leaves deep-sleep mode, maintaining its entire state from before deep-sleep mode was entered.

Deep-sleep mode clocking of peripherals must be enabled via ROM\_SysCtlPeripheralClockGating(); if disabled, the peripheral deep-sleep mode configuration is maintained but has no effect when deep-sleep mode is entered.

```
The
      ui32Peripheral
                    parameter
                                      be
                                           only
                                                        of
                                                            the
                                                                  follow-
                               must
                                                  one
                                                   SYSCTL PERIPH ADC1,
                        SYSCTL PERIPH ADCO.
ing
       values:
                                                  SYSCTL_PERIPH CAN2,
SYSCTL PERIPH CANO.
                         SYSCTL PERIPH CAN1,
SYSCTL PERIPH COMPO.
                        SYSCTL PERIPH COMP1,
                                                 SYSCTL PERIPH COMP2.
SYSCTL PERIPH EEPROMO,
                          SYSCTL_PERIPH GPIOA.
                                                  SYSCTL PERIPH_GPIOB,
SYSCTL PERIPH GPIOC
                         SYSCTL PERIPH GPIOD,
                                                  SYSCTL PERIPH GPIOE,
SYSCTL_PERIPH_GPIOF,
                        SYSCTL PERIPH GPIOG,
                                                  SYSCTL PERIPH GPIOH,
SYSCTL PERIPH GPIOJ,
                        SYSCTL PERIPH GPIOK,
                                                  SYSCTL PERIPH GPIOL,
SYSCTL PERIPH GPIOM.
                         SYSCTL PERIPH GPION.
                                                  SYSCTL PERIPH GPIOP.
                                                    SYSCTL PERIPH 12C0.
SYSCTL PERIPH GPIOQ.
                       SYSCTL PERIPH HIBERNATE.
SYSCTL PERIPH 12C1,
                         SYSCTL PERIPH 12C2,
                                                    SYSCTL PERIPH 12C3,
SYSCTL PERIPH 12C4,
                         SYSCTL PERIPH 12C5,
                                                  SYSCTL PERIPH PWM0,
SYSCTL_PERIPH_PWM1,
                          SYSCTL_PERIPH_QEI0,
                                                   SYSCTL_PERIPH_QEI1,
                          SYSCTL PERIPH SSI1,
SYSCTL PERIPH SSIO,
                                                   SYSCTL PERIPH SSI2,
SYSCTL PERIPH SSI3,
                       SYSCTL PERIPH TIMERO,
                                                 SYSCTL PERIPH TIMER1,
SYSCTL PERIPH TIMER2,
                        SYSCTL PERIPH TIMER3,
                                                 SYSCTL PERIPH TIMER4.
SYSCTL PERIPH TIMER5,
                         SYSCTL PERIPH UARTO,
                                                  SYSCTL PERIPH UART1,
                         SYSCTL_PERIPH_UART3,
                                                  SYSCTL_PERIPH_UART4,
SYSCTL PERIPH UART2,
SYSCTL PERIPH UART5,
                        SYSCTL PERIPH UART6,
                                                  SYSCTL PERIPH UART7,
SYSCTL PERIPH UDMA.
                        SYSCTL PERIPH USBO.
                                                 SYSCTL PERIPH WDOGO,
SYSCTL PERIPH WDOG1, SYSCTL PERIPH WTIMERO,
                                               SYSCTL PERIPH WTIMER1.
SYSCTL PERIPH WTIMER2,
                                               SYSCTL_PERIPH_WTIMER3,
SYSCTL PERIPH WTIMER4, or SYSCTL PERIPH WTIMER5.
```

#### Returns:

None.

## 18.2.1.14 ROM SysCtlPeripheralDeepSleepEnable

Enables a peripheral in deep-sleep mode.

## Prototype:

void

ROM\_SysCtlPeripheralDeepSleepEnable(uint32\_t ui32Peripheral)

#### **ROM Location:**

ROM\_APITABLE is an array of pointers located at  $0 \times 0100.0010$ . ROM\_SYSCTLTABLE is an array of pointers located at ROM\_APITABLE[13]. ROM\_SYSCTLTABLE[10].

#### Parameters:

ui32Peripheral is the peripheral to enable in deep-sleep mode.

### **Description:**

This function allows a peripheral to continue operating when the processor goes into deepsleep mode. Since the clocking configuration of the device may change, not all peripherals can safely continue operating while the processor is in sleep mode. Those that must run at a particular frequency (such as a timer) will not work as expected if the clock changes. It is the responsibility of the caller to make sensible choices.

Deep-sleep mode clocking of peripherals must be enabled via ROM\_SysCtlPeripheralClockGating(); if disabled, the peripheral deep-sleep mode configuration is maintained but has no effect when deep-sleep mode is entered.

```
The
      ui32Peripheral
                    parameter
                               must
                                      be
                                           only
                                                       of
                                                            the
                                                                  follow-
                                                  SYSCTL PERIPH ADC1,
ing
       values:
                       SYSCTL PERIPH ADCO.
SYSCTL PERIPH CANO,
                         SYSCTL PERIPH CAN1,
                                                  SYSCTL PERIPH CAN2,
SYSCTL PERIPH COMPO.
                        SYSCTL PERIPH COMP1,
                                                 SYSCTL PERIPH COMP2.
                          SYSCTL_PERIPH GPIOA.
SYSCTL PERIPH EEPROMO.
                                                 SYSCTL PERIPH GPIOB.
SYSCTL PERIPH_GPIOC,
                                                  SYSCTL PERIPH GPIOE,
                         SYSCTL PERIPH GPIOD,
                        SYSCTL PERIPH GPIOG,
                                                 SYSCTL PERIPH GPIOH,
SYSCTL_PERIPH_GPIOF,
SYSCTL PERIPH GPIOJ,
                        SYSCTL PERIPH GPIOK,
                                                  SYSCTL PERIPH GPIOL,
SYSCTL PERIPH GPIOM.
                         SYSCTL PERIPH GPION.
                                                 SYSCTL PERIPH GPIOP.
SYSCTL PERIPH GPIOQ.
                       SYSCTL PERIPH HIBERNATE.
                                                   SYSCTL PERIPH 12C0.
SYSCTL PERIPH 12C1,
                         SYSCTL PERIPH 12C2,
                                                   SYSCTL PERIPH 12C3,
SYSCTL PERIPH 12C4,
                         SYSCTL PERIPH 12C5,
                                                  SYSCTL PERIPH PWM0,
SYSCTL PERIPH PWM1,
                          SYSCTL_PERIPH_QEI0,
                                                   SYSCTL PERIPH QEI1,
                          SYSCTL PERIPH SSI1,
                                                   SYSCTL PERIPH SSI2,
SYSCTL PERIPH SSIO,
SYSCTL PERIPH SSI3,
                       SYSCTL PERIPH TIMERO,
                                                 SYSCTL PERIPH TIMER1,
SYSCTL PERIPH TIMER2.
                        SYSCTL PERIPH TIMER3.
                                                 SYSCTL PERIPH TIMER4.
                         SYSCTL PERIPH UARTO,
                                                 SYSCTL PERIPH UART1,
SYSCTL PERIPH TIMER5,
SYSCTL PERIPH UART2,
                         SYSCTL PERIPH UART3,
                                                 SYSCTL PERIPH UART4,
SYSCTL PERIPH UART5,
                        SYSCTL PERIPH UART6,
                                                 SYSCTL PERIPH UART7,
SYSCTL PERIPH UDMA,
                        SYSCTL PERIPH USBO,
                                                 SYSCTL PERIPH WDOGO,
SYSCTL_PERIPH_WDOG1, SYSCTL_PERIPH_WTIMER0, SYSCTL PERIPH WTIMER1,
SYSCTL PERIPH WTIMER2.
                                               SYSCTL PERIPH WTIMER3,
SYSCTL PERIPH WTIMER4, or SYSCTL PERIPH WTIMER5.
```

### Returns:

None.

## 18.2.1.15 ROM SysCtlPeripheralDisable

Disables a peripheral.

## Prototype:

void

ROM\_SysCtlPeripheralDisable(uint32\_t ui32Peripheral)

#### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_SYSCTLTABLE is an array of pointers located at ROM\_APITABLE[13].

ROM\_SysCtlPeripheralDisable is a function pointer located at ROM\_SYSCTLTABLE[7].

### Parameters:

ui32Peripheral is the peripheral to disable.

### **Description:**

Peripherals are disabled with this function. Once disabled, they will not operate or respond to register reads/writes.

```
The
      ui32Peripheral
                    parameter
                               must
                                      be
                                           only
                                                  one
                                                       of
                                                            the
                                                                  follow-
ing
       values:
                       SYSCTL PERIPH ADCO.
                                                  SYSCTL PERIPH ADC1,
SYSCTL_PERIPH_CAN0,
                                                  SYSCTL_PERIPH_CAN2,
                         SYSCTL_PERIPH_CAN1,
SYSCTL PERIPH COMPO,
                        SYSCTL PERIPH COMP1,
                                                 SYSCTL PERIPH COMP2,
                                                  SYSCTL PERIPH GPIOB,
SYSCTL PERIPH EEPROMO,
                          SYSCTL PERIPH GPIOA,
SYSCTL PERIPH GPIOC,
                         SYSCTL PERIPH GPIOD,
                                                  SYSCTL PERIPH GPIOE,
SYSCTL PERIPH GPIOF,
                        SYSCTL PERIPH GPIOG,
                                                  SYSCTL PERIPH GPIOH,
SYSCTL PERIPH GPIOJ,
                                                  SYSCTL PERIPH GPIOL,
                         SYSCTL PERIPH GPIOK,
SYSCTL PERIPH GPIOM,
                         SYSCTL PERIPH GPION
                                                  SYSCTL PERIPH GPIOP,
SYSCTL PERIPH GPIOQ,
                       SYSCTL PERIPH HIBERNATE,
                                                   SYSCTL PERIPH 12C0,
SYSCTL PERIPH 12C1.
                          SYSCTL PERIPH 12C2.
                                                   SYSCTL PERIPH 12C3.
SYSCTL PERIPH 12C4.
                         SYSCTL PERIPH 12C5,
                                                  SYSCTL PERIPH PWM0.
                          SYSCTL PERIPH QEIO,
SYSCTL PERIPH PWM1,
                                                   SYSCTL PERIPH QEI1,
SYSCTL_PERIPH_SSI0,
                          SYSCTL_PERIPH_SSI1,
                                                   SYSCTL_PERIPH_SSI2,
SYSCTL PERIPH SSI3,
                       SYSCTL PERIPH TIMERO,
                                                 SYSCTL PERIPH TIMER1,
SYSCTL PERIPH TIMER2,
                        SYSCTL PERIPH TIMER3.
                                                 SYSCTL PERIPH TIMER4,
SYSCTL PERIPH TIMER5.
                         SYSCTL PERIPH UARTO,
                                                  SYSCTL PERIPH UART1.
SYSCTL_PERIPH_UART2,
                         SYSCTL_PERIPH_UART3,
                                                  SYSCTL_PERIPH_UART4,
SYSCTL PERIPH UART5,
                         SYSCTL PERIPH UART6,
                                                  SYSCTL PERIPH UART7,
SYSCTL_PERIPH_UDMA,
                        SYSCTL PERIPH USBO,
                                                 SYSCTL_PERIPH_WDOG0,
SYSCTL_PERIPH_WDOG1, SYSCTL_PERIPH_WTIMER0, SYSCTL_PERIPH_WTIMER1,
                                               SYSCTL PERIPH WTIMER3,
SYSCTL PERIPH WTIMER2,
SYSCTL PERIPH WTIMER4, or SYSCTL PERIPH WTIMER5.
```

#### Returns:

None.

## 18.2.1.16 ROM\_SysCtlPeripheralEnable

Enables a peripheral.

#### Prototype:

void

ROM\_SysCtlPeripheralEnable(uint32\_t ui32Peripheral)

### **ROM Location:**

ROM\_APITABLE is an array of pointers located at  $0 \times 0100.0010$ .

ROM\_SYSCTLTABLE is an array of pointers located at ROM\_APITABLE[13].

ROM\_SysCtlPeripheralEnable is a function pointer located at ROM\_SYSCTLTABLE[6].

#### Parameters:

ui32Peripheral is the peripheral to enable.

### **Description:**

Peripherals are enabled with this function. At power-up, all peripherals are disabled; they must be enabled in order to operate or respond to register reads/writes.

•	rameter must be o	
ing values:	SYSCTL_PERIPH_ADC0,	
SYSCTL_PERIPH_CAN0,	SYSCTL_PERIPH_CAN	1, SYSCTL_PERIPH_CAN2,
SYSCTL_PERIPH_COMP0,	SYSCTL_PERIPH_COMP	P1, SYSCTL_PERIPH_COMP2,
SYSCTL_PERIPH_EEPROM	D, SYSCTL_PERIPH_GPI	IOA, SYSCTL_PERIPH_GPIOB,
SYSCTL_PERIPH_GPIOC,	SYSCTL_PERIPH_GPIO	D, SYSCTL_PERIPH_GPIOE,
SYSCTL PERIPH GPIOF,	SYSCTL PERIPH GPIO	G, SYSCTL_PERIPH_GPIOH,
SYSCTL_PERIPH_GPIOJ,	SYSCTL_PERIPH_GPIO	
SYSCTL_PERIPH_GPIOM,	SYSCTL_PERIPH_GPIO	N, SYSCTL_PERIPH_GPIOP,
SYSCTL_PERIPH_GPIOQ,	SYSCTL_PERIPH_HIBER	NATE, SYSCTL_PERIPH_I2C0,
SYSCTL_PERIPH_I2C1,	SYSCTL_PERIPH_I2C2	sysctl_periph_i2C3,
SYSCTL_PERIPH_I2C4,	SYSCTL_PERIPH_I2C5,	SYSCTL_PERIPH_PWM0,
SYSCTL_PERIPH_PWM1,	SYSCTL_PERIPH_QEI	0, SYSCTL_PERIPH_QEI1,
SYSCTL_PERIPH_SSI0,	SYSCTL_PERIPH_SSI1	, SYSCTL_PERIPH_SSI2,
SYSCTL_PERIPH_SSI3,	SYSCTL_PERIPH_TIMERO	, SYSCTL_PERIPH_TIMER1,
SYSCTL_PERIPH_TIMER2,	SYSCTL_PERIPH_TIMEF	R3, SYSCTL_PERIPH_TIMER4,
SYSCTL_PERIPH_TIMER5,	SYSCTL_PERIPH_UART	TO, SYSCTL_PERIPH_UART1,
SYSCTL_PERIPH_UART2,	SYSCTL_PERIPH_UART	3, SYSCTL_PERIPH_UART4,
SYSCTL_PERIPH_UART5,	SYSCTL_PERIPH_UART	6, SYSCTL_PERIPH_UART7,
SYSCTL_PERIPH_UDMA,	SYSCTL_PERIPH_USB0,	SYSCTL_PERIPH_WDOG0,
SYSCTL_PERIPH_WDOG1,	SYSCTL_PERIPH_WTIMEF	RO, SYSCTL_PERIPH_WTIMER1,
SYSCTL_PERIPH_WTIMER2	,	SYSCTL_PERIPH_WTIMER3,
SYSCTL_PERIPH_WTIMER4	, or SYSCTL_PERIPH_WTII	MER5.

## Note:

It takes five clock cycles after the write to enable a peripheral before the the peripheral is actually enabled. During this time, attempts to access the peripheral will result in a bus fault. Care should be taken to ensure that the peripheral is not accessed during this brief time period.

### Returns:

None.

## 18.2.1.17 ROM SysCtlPeripheralPowerOff

Powers off a peripheral.

## Prototype:

void

ROM\_SysCtlPeripheralPowerOff(uint32\_t ui32Peripheral)

## **ROM Location:**

ROM\_APITABLE is an array of pointers located at  $0 \times 0100.0010$ . ROM\_SYSCTLTABLE is an array of pointers located at ROM\_APITABLE [13].

ROM\_SysCtlPeripheralPowerOff is a function pointer located at ROM\_SYSCTLTABLE[37].

#### Parameters:

ui32Peripheral is the peripheral to be powered off.

### **Description:**

This function allows the power to a peripheral to be turned off. The peripheral will continue to receive power when its clock is enabled, but the power will be removed when its clock is disabled.

The <i>ui32Peripheral</i> paing values:	ramter must be only SYSCTL_PERIPH_ADC0,	one of the follow- SYSCTL_PERIPH_ADC1,
SYSCTL_PERIPH_CANO,	SYSCTL PERIPH CAN1,	SYSCTL_PERIPH_CAN2,
SYSCTL PERIPH COMPO,	SYSCTL PERIPH COMP1	
SYSCTL PERIPH EEPROM	<del> </del>	
SYSCTL PERIPH GPIOC,	SYSCTL PERIPH GPIOD,	
SYSCTL PERIPH GPIOF,	SYSCTL PERIPH GPIOG,	
SYSCTL_PERIPH_GPIOJ,	SYSCTL_PERIPH_GPIOK,	SYSCTL_PERIPH_GPIOL,
SYSCTL_PERIPH_GPIOM,	SYSCTL_PERIPH_GPION,	SYSCTL_PERIPH_GPIOP,
SYSCTL_PERIPH_GPIOQ,	SYSCTL_PERIPH_HIBERNA	ATE, SYSCTL_PERIPH_I2CO,
SYSCTL_PERIPH_I2C1,	SYSCTL_PERIPH_I2C2,	SYSCTL_PERIPH_I2C3,
SYSCTL_PERIPH_I2C4,	SYSCTL_PERIPH_I2C5,	SYSCTL_PERIPH_PWM0,
SYSCTL_PERIPH_PWM1,	SYSCTL_PERIPH_QEI0,	SYSCTL_PERIPH_QEI1,
SYSCTL_PERIPH_SSI0,	SYSCTL_PERIPH_SSI1,	SYSCTL_PERIPH_SSI2,
SYSCTL_PERIPH_SSI3,	SYSCTL_PERIPH_TIMER0,	SYSCTL_PERIPH_TIMER1,
SYSCTL_PERIPH_TIMER2,	SYSCTL_PERIPH_TIMER3	, SYSCTL_PERIPH_TIMER4,
SYSCTL_PERIPH_TIMER5,	SYSCTL_PERIPH_UART0	, SYSCTL_PERIPH_UART1,
SYSCTL_PERIPH_UART2,	SYSCTL_PERIPH_UART3,	SYSCTL_PERIPH_UART4,
SYSCTL_PERIPH_UART5,	SYSCTL_PERIPH_UART6,	
SYSCTL_PERIPH_UDMA,	SYSCTL_PERIPH_USB0,	SYSCTL_PERIPH_WDOG0,
SYSCTL_PERIPH_WDOG1,	SYSCTL_PERIPH_WTIMER0	
SYSCTL_PERIPH_WTIMER2	-	SYSCTL_PERIPH_WTIMER3,
SYSCTL_PERIPH_WTIMER4	I, or SYSCTL_PERIPH_WTIME	ER5.

### Returns:

None.

## 18.2.1.18 ROM\_SysCtlPeripheralPowerOn

Powers on a peripheral.

## Prototype:

void

ROM\_SysCtlPeripheralPowerOn(uint32\_t ui32Peripheral)

#### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_SYSCTLTABLE is an array of pointers located at ROM\_APITABLE[13].

ROM\_SysCtlPeripheralPowerOn is a function pointer located at ROM\_SYSCTLTABLE[36].

## Parameters:

ui32Peripheral is the peripheral to be powered on.

## **Description:**

This function turns on the power to a peripheral. It will continue to receive power even when its clock is not enabled.

The <i>ui32Peripheral</i> pa	ramter must	be only	one of	the follow-
ing values:	SYSCTL_PERI	PH ADCO,	SYSCTL	PERIPH ADC1,
SYSCTL_PERIPH_CANO,	SYSCTL_PE		SYSCTL	PERIPH_CAN2,
SYSCTL_PERIPH_COMPO,	SYSCTL_PER	IPH_COMP1,	SYSCTL_F	PERIPH_COMP2,
SYSCTL_PERIPH_EEPROM	IO, SYSCTL_P	ERIPH_GPIOA,	SYSCTL	PERIPH_GPIOB,
SYSCTL_PERIPH_GPIOC,	SYSCTL_PER	RIPH_GPIOD,	SYSCTL_	PERIPH_GPIOE,
SYSCTL_PERIPH_GPIOF,	SYSCTL_PER	RIPH_GPIOG,	SYSCTL_	PERIPH_GPIOH,
SYSCTL_PERIPH_GPIOJ,	SYSCTL_PEF	RIPH_GPIOK,	SYSCTL_	PERIPH_GPIOL,
SYSCTL_PERIPH_GPIOM,	SYSCTL_PER	RIPH_GPION,	SYSCTL_	PERIPH_GPIOP,
SYSCTL_PERIPH_GPIOQ,	SYSCTL_PERI	PH_HIBERNAT	E, SYSCT	L_PERIPH_I2C0,
SYSCTL_PERIPH_I2C1,	SYSCTL_PE	RIPH_I2C2,	SYSCT	L_PERIPH_I2C3,
SYSCTL_PERIPH_I2C4,	SYSCTL_PER	RIPH_I2C5,	SYSCTL_	PERIPH_PWM0,
SYSCTL_PERIPH_PWM1,	SYSCTL_PI	ERIPH_QEI0,	SYSCTI	_PERIPH_QEI1,
SYSCTL_PERIPH_SSI0,	SYSCTL_PE	RIPH_SSI1,	SYSCT	L_PERIPH_SSI2,
SYSCTL_PERIPH_SSI3,	SYSCTL_PERIF	PH_TIMERO,	SYSCTL_P	ERIPH_TIMER1,
SYSCTL_PERIPH_TIMER2,	SYSCTL_PER	IPH_TIMER3,	SYSCTL_P	ERIPH_TIMER4,
SYSCTL_PERIPH_TIMER5,	SYSCTL_PE	RIPH_UARTO,	SYSCTL_	PERIPH_UART1,
SYSCTL_PERIPH_UART2,	SYSCTL_PEF	RIPH_UART3,	SYSCTL_	PERIPH_UART4,
SYSCTL_PERIPH_UART5,	SYSCTL_PEF	RIPH_UART6,	SYSCTL_	PERIPH_UART7,
SYSCTL_PERIPH_UDMA,	SYSCTL_PER	IPH_USB0,	SYSCTL_P	ERIPH_WDOG0,
SYSCTL_PERIPH_WDOG1,	SYSCTL_PERIP	H_WTIMER0,	SYSCTL_PE	RIPH_WTIMER1,
SYSCTL_PERIPH_WTIMER2	2,		SYSCTL_PE	RIPH_WTIMER3,
SYSCTL PERIPH WTIMER	4, or SYSCTL PE	RIPH WTIMER	<b>R5</b> .	

## Returns:

None.

## 18.2.1.19 ROM SysCtlPeripheralPresent

Determines if a peripheral is present.

### Prototype:

bool

ROM\_SysCtlPeripheralPresent(uint32\_t ui32Peripheral)

### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_SYSCTLTABLE is an array of pointers located at ROM\_APITABLE[13].

ROM\_SysCtlPeripheralPresent is a function pointer located at ROM\_SYSCTLTABLE[4].

## Parameters:

ui32Peripheral is the peripheral in question.

## **Description:**

Determines if a particular peripheral is present in the device.

The *ui32Peripheral* parameter must be only one of the following values: SYSCTL\_PERIPH\_ADC1, SYSCTL\_PERIPH\_CAN0, SYSCTL\_PERIPH\_CAN2, SYSCTL\_PERIPH\_COMP0,

SYSCTL_PERIPH_COMP1,	SYSCTL_PERIPH_COMP2,	SYSCTL_PERIPH_EPI0,
SYSCTL_PERIPH_ETH,	SYSCTL_PERIPH_GPIOA,	SYSCTL_PERIPH_GPIOB,
SYSCTL_PERIPH_GPIOC,	SYSCTL_PERIPH_GPIOD,	SYSCTL_PERIPH_GPIOE,
SYSCTL_PERIPH_GPIOF,	SYSCTL_PERIPH_GPIOG,	SYSCTL_PERIPH_GPIOH,
SYSCTL_PERIPH_GPIOJ,	SYSCTL_PERIPH_HIBERNATE,	SYSCTL_PERIPH_I2C0,
SYSCTL_PERIPH_I2C1,	SYSCTL_PERIPH_I2S0, S	YSCTL_PERIPH_IEEE1588,
SYSCTL_PERIPH_MPU,	SYSCTL_PERIPH_PLL,	SYSCTL_PERIPH_PWM,
SYSCTL_PERIPH_QEI0,	SYSCTL_PERIPH_QEI1,	SYSCTL_PERIPH_SSI0,
SYSCTL_PERIPH_SSI1,	SYSCTL_PERIPH_TIMER0,	SYSCTL_PERIPH_TIMER1,
SYSCTL_PERIPH_TIMER2,	SYSCTL_PERIPH_TIMER3,	SYSCTL_PERIPH_TEMP,
SYSCTL_PERIPH_UART0,	SYSCTL_PERIPH_UART1,	SYSCTL_PERIPH_UART2,
SYSCTL_PERIPH_UDMA,	SYSCTL_PERIPH_USB0, SYS	CTL_PERIPH_WDOG0, or
SYSCTL PERIPH WDOG1.		

Returns **true** if the specified peripheral is present and **false** if it is not.

## 18.2.1.20 ROM SysCtlPeripheralReady

Determines if a peripheral is ready.

## Prototype:

bool

ROM\_SysCtlPeripheralReady(uint32\_t ui32Peripheral)

#### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_SYSCTLTABLE is an array of pointers located at ROM\_APITABLE[13].

ROM\_SysCtlPeripheralReady is a function pointer located at ROM\_SYSCTLTABLE[35].

#### Parameters:

*ui32Peripheral* is the peripheral in question.

#### **Description:**

Determines if a particular peripheral is ready to be accessed. The peripheral may be in a non-ready state if it is not enabled, is being held in reset, or is in the process of becoming ready after be enabled or taken out of reset.

```
The
      ui32Peripheral
                                                                  follow-
                    paramter
                               must
                                           only
                                                        of
                                                             the
                                      be
                                                  one
       values:
                        SYSCTL PERIPH ADCO,
                                                   SYSCTL PERIPH ADC1,
ing
SYSCTL PERIPH CANO,
                         SYSCTL PERIPH CAN1,
                                                   SYSCTL PERIPH CAN2,
SYSCTL PERIPH COMPO,
                        SYSCTL PERIPH COMP1,
                                                  SYSCTL PERIPH COMP2,
SYSCTL PERIPH EEPROMO,
                          SYSCTL PERIPH GPIOA,
                                                  SYSCTL PERIPH GPIOB,
SYSCTL PERIPH GPIOC,
                         SYSCTL PERIPH GPIOD,
                                                  SYSCTL PERIPH GPIOE,
                         SYSCTL_PERIPH_GPIOG,
                                                  SYSCTL_PERIPH_GPIOH,
SYSCTL_PERIPH_GPIOF,
                                                  SYSCTL PERIPH GPIOL,
SYSCTL PERIPH GPIOJ,
                         SYSCTL PERIPH GPIOK,
SYSCTL PERIPH GPIOM,
                         SYSCTL PERIPH GPION.
                                                  SYSCTL PERIPH GPIOP,
SYSCTL PERIPH GPIOQ,
                        SYSCTL PERIPH HIBERNATE,
                                                    SYSCTL PERIPH 12C0,
SYSCTL PERIPH 12C1,
                          SYSCTL PERIPH 12C2,
                                                    SYSCTL PERIPH 12C3,
SYSCTL_PERIPH_I2C4,
                         SYSCTL_PERIPH_I2C5,
                                                  SYSCTL_PERIPH_PWM0,
SYSCTL PERIPH PWM1,
                          SYSCTL PERIPH QEIO,
                                                    SYSCTL PERIPH QEI1,
SYSCTL PERIPH SSIO,
                          SYSCTL PERIPH SSI1,
                                                    SYSCTL PERIPH SSI2,
```

```
SYSCTL PERIPH SSI3.
                      SYSCTL PERIPH TIMERO.
                                                SYSCTL PERIPH TIMER1.
SYSCTL PERIPH TIMER2,
                        SYSCTL PERIPH TIMER3,
                                                SYSCTL PERIPH TIMER4,
SYSCTL PERIPH TIMER5,
                        SYSCTL PERIPH UARTO,
                                                SYSCTL PERIPH UART1,
                        SYSCTL_PERIPH_UART3,
                                                SYSCTL_PERIPH_UART4,
SYSCTL_PERIPH_UART2,
SYSCTL PERIPH UART5,
                        SYSCTL PERIPH UART6,
                                                SYSCTL PERIPH UART7,
SYSCTL PERIPH UDMA,
                       SYSCTL PERIPH USBO,
                                                SYSCTL PERIPH WDOGO,
SYSCTL PERIPH WDOG1, SYSCTL PERIPH WTIMERO,
                                              SYSCTL PERIPH WTIMER1,
SYSCTL PERIPH WTIMER2,
                                              SYSCTL PERIPH WTIMER3,
SYSCTL PERIPH WTIMER4, or SYSCTL PERIPH WTIMER5.
```

Returns **true** if the specified peripheral is ready and **false** if it is not.

## 18.2.1.21 ROM SysCtlPeripheralReset

Performs a software reset of a peripheral.

## Prototype:

void

ROM\_SysCtlPeripheralReset(uint32\_t ui32Peripheral)

#### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_SYSCTLTABLE is an array of pointers located at ROM\_APITABLE[13].

ROM\_SYSCTLTABLE[13].

### Parameters:

ui32Peripheral is the peripheral to reset.

## **Description:**

This function performs a software reset of the specified peripheral. An individual peripheral reset signal is asserted for a brief period and then deasserted, returning the internal state of the peripheral to its reset condition.

```
The
      ui32Peripheral
                                                                  follow-
                    parameter
                               must
                                      be
                                           only
                                                  one
                                                        of
                                                             the
                        SYSCTL PERIPH ADCO.
ing
       values:
                                                   SYSCTL PERIPH ADC1.
SYSCTL PERIPH CANO,
                         SYSCTL PERIPH CAN1,
                                                   SYSCTL PERIPH CAN2,
SYSCTL PERIPH COMPO,
                        SYSCTL_PERIPH_COMP1,
                                                 SYSCTL_PERIPH_COMP2,
                          SYSCTL PERIPH GPIOA,
                                                  SYSCTL PERIPH GPIOB,
SYSCTL PERIPH EEPROMO,
SYSCTL PERIPH GPIOC.
                         SYSCTL PERIPH GPIOD.
                                                  SYSCTL PERIPH GPIOE.
SYSCTL PERIPH GPIOF.
                         SYSCTL PERIPH GPIOG.
                                                  SYSCTL PERIPH GPIOH.
                                                  SYSCTL_PERIPH GPIOL,
SYSCTL PERIPH GPIOJ,
                         SYSCTL PERIPH GPIOK,
SYSCTL PERIPH GPIOM,
                         SYSCTL PERIPH GPION,
                                                  SYSCTL PERIPH GPIOP,
SYSCTL PERIPH GPIOQ,
                        SYSCTL PERIPH HIBERNATE,
                                                    SYSCTL PERIPH 12C0,
                                                    SYSCTL PERIPH 12C3,
SYSCTL PERIPH 12C1,
                          SYSCTL PERIPH 12C2,
                                                  SYSCTL PERIPH PWM0,
SYSCTL PERIPH 12C4,
                         SYSCTL PERIPH 12C5,
SYSCTL PERIPH PWM1,
                          SYSCTL PERIPH QEIO,
                                                    SYSCTL PERIPH QEI1,
SYSCTL PERIPH SSIO,
                          SYSCTL PERIPH SSI1,
                                                    SYSCTL_PERIPH_SSI2,
                       SYSCTL PERIPH TIMERO,
SYSCTL PERIPH SSI3,
                                                 SYSCTL PERIPH TIMER1,
SYSCTL_PERIPH_TIMER2,
                        SYSCTL_PERIPH_TIMER3,
                                                 SYSCTL_PERIPH_TIMER4,
SYSCTL PERIPH TIMER5,
                         SYSCTL PERIPH UARTO,
                                                  SYSCTL PERIPH UART1,
                                                  SYSCTL PERIPH UART4,
SYSCTL PERIPH UART2,
                         SYSCTL PERIPH UART3,
```

```
SYSCTL_PERIPH_UART5, SYSCTL_PERIPH_UART6, SYSCTL_PERIPH_UART7, SYSCTL_PERIPH_UDMA, SYSCTL_PERIPH_USB0, SYSCTL_PERIPH_WDOG0, SYSCTL_PERIPH_WDOG1, SYSCTL_PERIPH_WTIMER0, SYSCTL_PERIPH_WTIMER1, SYSCTL_PERIPH_WTIMER2, SYSCTL_PERIPH_WTIMER3, SYSCTL_PERIPH_WTIMER4, or SYSCTL_PERIPH_WTIMER5.
```

None.

## 18.2.1.22 ROM SysCtlPeripheralSleepDisable

Disables a peripheral in sleep mode.

## Prototype:

void

ROM\_SysCtlPeripheralSleepDisable(uint32\_t ui32Peripheral)

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSCTLTABLE is an array of pointers located at ROM_APITABLE[13].

ROM_SYSCTlPeripheralSleepDisable is a function pointer located at ROM_SYSCTLTABLE[9].
```

#### Parameters:

ui32Peripheral is the peripheral to disable in sleep mode.

### **Description:**

This function causes a peripheral to stop operating when the processor goes into sleep mode. Disabling peripherals while in sleep mode helps to lower the current draw of the device. If enabled (via ROM\_SysCtlPeripheralEnable()), the peripheral will automatically resume operation when the processor leaves sleep mode, maintaining its entire state from before sleep mode was entered.

Sleep mode clocking of peripherals must be enabled via ROM\_SysCtlPeripheralClockGating(); if disabled, the peripheral sleep mode configuration is maintained but has no effect when sleep mode is entered.

```
The
      ui32Peripheral
                    parameter
                                      be
                                            only
                                                  one
                                                        of
                                                             the
                                                                  follow-
                               must
                        SYSCTL PERIPH ADCO,
                                                   SYSCTL_PERIPH_ADC1,
ing
       values:
SYSCTL PERIPH CANO,
                         SYSCTL PERIPH CAN1,
                                                   SYSCTL PERIPH CAN2,
SYSCTL PERIPH COMPO,
                        SYSCTL PERIPH COMP1,
                                                  SYSCTL PERIPH COMP2,
                                                  SYSCTL PERIPH GPIOB,
SYSCTL PERIPH EEPROMO.
                           SYSCTL PERIPH GPIOA.
                                                  SYSCTL PERIPH GPIOE,
SYSCTL PERIPH GPIOC,
                         SYSCTL PERIPH GPIOD,
SYSCTL PERIPH GPIOF,
                         SYSCTL PERIPH GPIOG,
                                                  SYSCTL PERIPH GPIOH,
SYSCTL PERIPH GPIOJ,
                         SYSCTL PERIPH GPIOK,
                                                  SYSCTL PERIPH GPIOL,
                         SYSCTL_PERIPH_GPION,
                                                  SYSCTL_PERIPH_GPIOP,
SYSCTL_PERIPH_GPIOM,
SYSCTL PERIPH GPIOQ,
                        SYSCTL PERIPH HIBERNATE,
                                                    SYSCTL PERIPH 12C0,
SYSCTL PERIPH 12C1,
                          SYSCTL PERIPH 12C2,
                                                    SYSCTL PERIPH 12C3,
SYSCTL PERIPH 12C4,
                         SYSCTL PERIPH 12C5,
                                                  SYSCTL PERIPH PWM0,
SYSCTL PERIPH PWM1,
                          SYSCTL PERIPH QEIO,
                                                    SYSCTL PERIPH QEI1,
SYSCTL_PERIPH_SSIO,
                          SYSCTL_PERIPH_SSI1,
                                                    SYSCTL_PERIPH_SSI2,
SYSCTL PERIPH SSI3,
                       SYSCTL PERIPH TIMERO,
                                                 SYSCTL PERIPH TIMER1,
                        SYSCTL PERIPH TIMER3,
SYSCTL PERIPH TIMER2,
                                                 SYSCTL PERIPH TIMER4,
```

```
SYSCTL PERIPH TIMER5.
                        SYSCTL PERIPH UARTO.
                                                SYSCTL PERIPH UART1.
SYSCTL PERIPH UART2,
                        SYSCTL PERIPH UART3,
                                                SYSCTL PERIPH UART4,
SYSCTL PERIPH UART5,
                        SYSCTL PERIPH UART6,
                                                SYSCTL PERIPH UART7,
                       SYSCTL_PERIPH_USB0,
                                               SYSCTL_PERIPH_WDOG0,
SYSCTL_PERIPH_UDMA,
SYSCTL PERIPH WDOG1, SYSCTL PERIPH WTIMER0, SYSCTL PERIPH WTIMER1,
SYSCTL PERIPH WTIMER2,
                                              SYSCTL PERIPH WTIMER3,
SYSCTL PERIPH WTIMER4, or SYSCTL PERIPH WTIMER5.
```

None.

## 18.2.1.23 ROM SysCtlPeripheralSleepEnable

Enables a peripheral in sleep mode.

## Prototype:

void

ROM\_SysCtlPeripheralSleepEnable(uint32\_t ui32Peripheral)

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_SYSCTLTABLE is an array of pointers located at ROM_APITABLE[13].
ROM_SysCtlPeripheralSleepEnable is a function pointer located at ROM_SYSCTLTABLE[8].
```

#### Parameters:

ui32Peripheral is the peripheral to enable in sleep mode.

## **Description:**

This function allows a peripheral to continue operating when the processor goes into sleep mode. Since the clocking configuration of the device does not change, any peripheral can safely continue operating while the processor is in sleep mode, and can therefore wake the processor from sleep mode.

Sleep mode clocking of peripherals must be enabled via ROM\_SysCtlPeripheralClockGating(); if disabled, the peripheral sleep mode configuration is maintained but has no effect when sleep mode is entered.

```
The
      ui32Peripheral
                                                        of
                                                                  follow-
                    parameter
                               must
                                      be
                                            only
                                                  one
                                                             the
                        SYSCTL PERIPH ADCO,
                                                   SYSCTL PERIPH ADC1,
ing
       values:
SYSCTL PERIPH CANO,
                         SYSCTL PERIPH CAN1,
                                                   SYSCTL PERIPH CAN2,
SYSCTL PERIPH COMPO.
                        SYSCTL PERIPH COMP1.
                                                  SYSCTL PERIPH COMP2.
                                                  SYSCTL PERIPH GPIOB,
SYSCTL PERIPH EEPROMO,
                           SYSCTL PERIPH GPIOA,
SYSCTL PERIPH GPIOC,
                         SYSCTL PERIPH GPIOD,
                                                  SYSCTL PERIPH GPIOE,
SYSCTL PERIPH_GPIOF,
                         SYSCTL PERIPH_GPIOG,
                                                  SYSCTL PERIPH_GPIOH,
SYSCTL_PERIPH_GPIOJ,
                         SYSCTL_PERIPH_GPIOK,
                                                  SYSCTL_PERIPH_GPIOL,
SYSCTL PERIPH GPIOM,
                         SYSCTL PERIPH GPION,
                                                  SYSCTL PERIPH GPIOP,
                                                    SYSCTL_PERIPH_I2C0,
SYSCTL PERIPH GPIOQ,
                        SYSCTL PERIPH HIBERNATE,
SYSCTL PERIPH 12C1,
                          SYSCTL PERIPH 12C2,
                                                    SYSCTL_PERIPH_I2C3,
SYSCTL PERIPH 12C4,
                         SYSCTL PERIPH 12C5,
                                                  SYSCTL PERIPH PWM0,
SYSCTL_PERIPH_PWM1,
                          SYSCTL_PERIPH_QEI0,
                                                    SYSCTL_PERIPH_QEI1,
SYSCTL PERIPH SSIO,
                          SYSCTL PERIPH SSI1,
                                                    SYSCTL PERIPH SSI2,
SYSCTL PERIPH SSI3,
                       SYSCTL PERIPH TIMERO,
                                                 SYSCTL PERIPH TIMER1,
```

```
SYSCTL PERIPH TIMER2,
                        SYSCTL PERIPH TIMER3.
                                               SYSCTL PERIPH TIMER4.
SYSCTL PERIPH TIMER5,
                        SYSCTL PERIPH UARTO,
                                                SYSCTL PERIPH UART1,
SYSCTL PERIPH UART2,
                        SYSCTL PERIPH UART3,
                                                SYSCTL PERIPH UART4,
SYSCTL_PERIPH UART5.
                        SYSCTL_PERIPH_UART6,
                                                SYSCTL_PERIPH_UART7,
                                               SYSCTL PERIPH WDOGO,
SYSCTL PERIPH UDMA,
                       SYSCTL PERIPH USBO,
SYSCTL PERIPH WDOG1, SYSCTL PERIPH WTIMER0, SYSCTL PERIPH WTIMER1,
SYSCTL PERIPH WTIMER2,
                                              SYSCTL PERIPH WTIMER3,
SYSCTL_PERIPH_WTIMER4, or SYSCTL_PERIPH_WTIMER5.
```

None.

## 18.2.1.24 ROM SysCtlPIOSCCalibrate

Calibrates the precision internal oscillator.

## Prototype:

```
uint32_t
ROM_SysCtlPIOSCCalibrate(uint32_t ui32Type)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSCTLTABLE is an array of pointers located at ROM_APITABLE[13].

ROM_SysCtlPIOSCCalibrate is a function pointer located at ROM_SYSCTLTABLE[45].
```

#### Parameters:

ui32Type is the type of calibration to perform.

### **Description:**

This function performs a calibration of the PIOSC. There are three types of calibration available; the desired calibration type as specified in *ui32Type* is one of:

- SYSCTL\_PIOSC\_CAL\_AUTO to perform automatic calibration using the 32 kHz clock from the hibernate module as a reference. This is only possible on parts that have a hibernate module and then only if it is enabled and the hibernate module's RTC is also enabled.
- SYSCTL\_PIOSC\_CAL\_FACT to reset the PIOSC calibration to the factory provided calibration.
- SYSCTL\_PIOSC\_CAL\_USER to set the PIOSC calibration to a user-supplied value. The value to be used is ORed into the lower 7-bits of this value, with 0x40 being the "nominal" value (in other words, if everything were perfect, this would provide exactly 16 MHz). Values larger than 0x40 will slow down PIOSC, and values smaller than 0x40 will speed up PIOSC.

## Returns:

None.

## 18.2.1.25 ROM SysCtlPWMClockGet

Gets the current PWM clock configuration.

## **Prototype:**

uint32\_t
ROM\_SysCtlPWMClockGet(void)

#### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_SYSCTLTABLE is an array of pointers located at ROM\_APITABLE[13].

ROM\_SYSCTLPWMClockGet is a function pointer located at ROM\_SYSCTLTABLE[26].

### **Description:**

This function returns the current PWM clock configuration.

#### Returns:

Returns the current PWM clock configuration; is one of SYSCTL\_PWMDIV\_1, SYSCTL\_PWMDIV\_2, SYSCTL\_PWMDIV\_4, SYSCTL\_PWMDIV\_8, SYSCTL\_PWMDIV\_16, SYSCTL\_PWMDIV\_32, or SYSCTL\_PWMDIV\_64.

## 18.2.1.26 ROM SysCtlPWMClockSet

Sets the PWM clock configuration.

### Prototype:

void
ROM\_SysCtlPWMClockSet(uint32\_t ui32Config)

#### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_SYSCTLTABLE is an array of pointers located at ROM\_APITABLE[13].

ROM\_SYSCTLPWMClockSet is a function pointer located at ROM\_SYSCTLTABLE[25].

#### Parameters:

```
ui32Config is the configuration for the PWM clock; it must be one of SYSCTL_PWMDIV_1, SYSCTL_PWMDIV_2, SYSCTL_PWMDIV_4, SYSCTL_PWMDIV_8, SYSCTL_PWMDIV 16, SYSCTL_PWMDIV 32, or SYSCTL_PWMDIV 64.
```

#### **Description:**

This function sets the rate of the clock provided to the PWM module as a ratio of the processor clock. This clock is used by the PWM module to generate PWM signals; its rate forms the basis for all PWM signals.

## Note:

The clocking of the PWM is dependent upon the system clock rate as configured by ROM\_SysCtlClockSet().

#### Returns:

None.

## 18.2.1.27 ROM SysCtlReset

Resets the device.

## Prototype:

void

ROM\_SysCtlReset (void)

#### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_SYSCTLTABLE is an array of pointers located at ROM\_APITABLE[13].

ROM\_SYSCtlReset is a function pointer located at ROM\_SYSCTLTABLE[19].

## **Description:**

This function will perform a software reset of the entire device. The processor and all peripherals are reset and all device registers will return to their default values (with the exception of the reset cause register, which will maintain its current value but have the software reset bit set as well).

### Returns:

This function does not return.

## 18.2.1.28 ROM SysCtlResetCauseClear

Clears reset reasons.

## Prototype:

void

ROM\_SysCtlResetCauseClear(uint32\_t ui32Causes)

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSCTLTABLE is an array of pointers located at ROM_APITABLE[13].

ROM_SysCtlResetCauseClear is a function pointer located at ROM_SYSCTLTABLE[22].
```

#### Parameters:

```
ui32Causes are the reset causes to be cleared; must be a logical OR of
SYSCTL_CAUSE_LDO, SYSCTL_CAUSE_SW, SYSCTL_CAUSE_WDOG,
SYSCTL_CAUSE_BOR, SYSCTL_CAUSE_POR, and/or SYSCTL_CAUSE_EXT.
```

## Description:

This function clears the specified sticky reset reasons. Once cleared, another reset for the same reason can be detected, and a reset for a different reason can be distinguished (instead of having two reset causes set). If the reset reason is used by an application, all reset causes should be cleared after they are retrieved with ROM\_SysCtlResetCauseGet().

### Returns:

None.

## 18.2.1.29 ROM SysCtlResetCauseGet

Gets the reason for a reset.

## Prototype:

```
uint32_t
ROM_SysCtlResetCauseGet(void)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSCTLTABLE is an array of pointers located at ROM_APITABLE[13].

ROM_SysCtlResetCauseGet is a function pointer located at ROM_SYSCTLTABLE[21].
```

#### **Description:**

This function will return the reason(s) for a reset. Since the reset reasons are sticky until either cleared by software or an external reset, multiple reset reasons may be returned if multiple resets have occurred. The reset reason is a logical OR of SYSCTL\_CAUSE\_LDO, SYSCTL\_CAUSE\_SW, SYSCTL\_CAUSE\_WDOG, SYSCTL\_CAUSE\_BOR, SYSCTL\_CAUSE\_POR, and/or SYSCTL\_CAUSE\_EXT.

#### Returns:

Returns the reason(s) for a reset.

## 18.2.1.30 ROM SysCtlSleep

Puts the processor into sleep mode.

## Prototype:

```
void
ROM_SysCtlSleep(void)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_SYSCTLTABLE is an array of pointers located at ROM_APITABLE[13].
ROM_SYSCTLTABLE is a function pointer located at ROM_SYSCTLTABLE[0].
```

## **Description:**

This function places the processor into sleep mode; it will not return until the processor returns to run mode. The peripherals that are enabled via ROM\_SysCtlPeripheralSleepEnable() continue to operate and can wake up the processor (if automatic clock gating is enabled with ROM\_SysCtlPeripheralClockGating(), otherwise all peripherals continue to operate).

#### Returns:

None.

## 18.2.1.31 ROM SysCtlSRAMSizeGet

Gets the size of the SRAM.

## Prototype:

```
uint32_t
ROM_SysCtlSRAMSizeGet(void)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSCTLTABLE is an array of pointers located at ROM_APITABLE[13].

ROM_SYSCtlSRAMSizeGet is a function pointer located at ROM_SYSCTLTABLE[1].
```

## Description:

This function determines the size of the SRAM.

#### Returns:

The total number of bytes of SRAM.

## 18.2.1.32 ROM\_SysCtlUSBPLLDisable

Powers down the USB PLL.

#### **Prototype:**

void

ROM\_SysCtlUSBPLLDisable(void)

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSCTLTABLE is an array of pointers located at ROM_APITABLE[13].

ROM_SysCtlUSBPLLDisable is a function pointer located at ROM_SYSCTLTABLE[32].
```

#### **Description:**

This function will disable the USB controller's PLL which is used by it's physical layer. The USB registers are still accessible, but the physical layer will no longer function.

#### Returns:

None.

## 18.2.1.33 ROM\_SysCtlUSBPLLEnable

Powers up the USB PLL.

## Prototype:

void

ROM\_SysCtlUSBPLLEnable(void)

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_SYSCTLTABLE is an array of pointers located at ROM_APITABLE[13].
ROM_SysCtlUSBPLLEnable is a function pointer located at ROM_SYSCTLTABLE[31].
```

#### **Description:**

This function will enable the USB controller's PLL which is used by it's physical layer. This call is necessary before connecting to any external devices.

#### Returns:

None.

# 19 System Exception Module

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## 19.1 Introduction

The system exception module provides an interrupt mechanism for handling system exceptions, such as errors from the floating-point unit.

## 19.2 Functions

## **Functions**

- void ROM\_SysExcIntClear (uint32\_t ui32IntFlags)
- void ROM\_SysExcIntDisable (uint32\_t ui32IntFlags)
- void ROM SysExcIntEnable (uint32 t ui32IntFlags)
- uint32\_t ROM\_SysExcIntStatus (bool bMasked)

## 19.2.1 Function Documentation

## 19.2.1.1 ROM\_SysExcIntClear

Clears system exception interrupt sources.

## Prototype:

```
void
ROM_SysExcIntClear(uint32_t ui32IntFlags)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSEXCTABLE is an array of pointers located at ROM_APITABLE[30].

ROM_SysExcIntClear is a function pointer located at ROM_SYSEXCTABLE[1].
```

#### Parameters:

ui32IntFlags is a bit mask of the interrupt sources to be cleared.

#### Description:

The specified system exception interrupt sources are cleared, so that they no longer assert. This function must be called in the interrupt handler to keep the interrupt from being recognized again immediately upon exit.

The ui32IntFlags parameter is the logical OR of any of the following:

- SYSEXCP\_INT\_FP\_IXC Floating-point inexact exception interrupt
- SYSEXCP\_INT\_FP\_OFC Floating-point overflow exception interrupt

- SYSEXCP INT FP UFC Floating-point underflow exception interrupt
- SYSEXCP\_INT\_FP\_IOC Floating-point invalid operation interrupt
- SYSEXCP\_INT\_FP\_DZC Floating-point divide by zero exception interrupt
- SYSEXCP\_INT\_FP\_IDC Floating-point input denormal exception interrupt

#### Note:

Because there is a write buffer in the Cortex-M processor, it may take several clock cycles before the interrupt source is actually cleared. Therefore, it is recommended that the interrupt source be cleared early in the interrupt handler (as opposed to the very last action) to avoid returning from the interrupt handler before the interrupt source is actually cleared. Failure to do so may result in the interrupt handler being immediately reentered (because the interrupt controller still sees the interrupt source asserted).

#### Returns:

None.

## 19.2.1.2 ROM SysExcIntDisable

Disables individual system exception interrupt sources.

## Prototype:

```
void
ROM_SysExcIntDisable(uint32_t ui32IntFlags)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSEXCTABLE is an array of pointers located at ROM_APITABLE[30].

ROM_SysExcIntDisable is a function pointer located at ROM_SYSEXCTABLE[2].
```

## Parameters:

ui32IntFlags is the bit mask of the interrupt sources to be disabled.

#### **Description:**

This function disables the indicated system exception interrupt sources. Only sources that are enabled can be reflected to the processor interrupt; disabled sources have no effect on the processor.

The *ui32IntFlags* parameter is the logical OR of any of the following:

- SYSEXCP INT FP IXC Floating-point inexact exception interrupt
- SYSEXCP\_INT\_FP\_OFC Floating-point overflow exception interrupt
- SYSEXCP INT FP UFC Floating-point underflow exception interrupt
- SYSEXCP\_INT\_FP\_IOC Floating-point invalid operation interrupt
- SYSEXCP INT FP DZC Floating-point divide by zero exception interrupt
- SYSEXCP\_INT\_FP\_IDC Floating-point input denormal exception interrupt

#### Returns:

None.

## 19.2.1.3 ROM SysExcIntEnable

Enables individual system exception interrupt sources.

### Prototype:

```
void
ROM_SysExcIntEnable(uint32_t ui32IntFlags)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSEXCTABLE is an array of pointers located at ROM_APITABLE[30].

ROM_SYSExcIntEnable is a function pointer located at ROM_SYSEXCTABLE[3].
```

#### Parameters:

ui32IntFlags is the bit mask of the interrupt sources to be enabled.

## **Description:**

This function enables the indicated system exception interrupt sources. Only the sources that are enabled can be reflected to the processor interrupt; disabled sources have no effect on the processor.

The *ui32IntFlags* parameter is the logical OR of any of the following:

- SYSEXCP\_INT\_FP\_IXC Floating-point inexact exception interrupt
- SYSEXCP\_INT\_FP\_OFC Floating-point overflow exception interrupt
- SYSEXCP INT FP UFC Floating-point underflow exception interrupt
- SYSEXCP\_INT\_FP\_IOC Floating-point invalid operation interrupt
- SYSEXCP INT FP DZC Floating-point divide by zero exception interrupt
- SYSEXCP INT FP IDC Floating-point input denormal exception interrupt

#### Returns:

None.

## 19.2.1.4 ROM SysExcIntStatus

Gets the current system exception interrupt status.

#### Prototype:

```
uint32_t
ROM_SysExcIntStatus(bool bMasked)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSEXCTABLE is an array of pointers located at ROM_APITABLE[30].

ROM_SysExcIntStatus is a function pointer located at ROM_SYSEXCTABLE[0].
```

#### Parameters:

**bMasked** is **false** if the raw interrupt status is required and **true** if the masked interrupt status is required.

### **Description:**

This function returns the system exception interrupt status. Either the raw interrupt status or the status of interrupts that are allowed to reflect to the processor can be returned.

## Returns:

Returns the current system exception interrupt status, enumerated as the logical OR of SYSEXCP\_INT\_FP\_IXC, SYSEXCP\_INT\_FP\_OFC, SYSEXCP\_INT\_FP\_UFC, SYSEXCP\_INT\_FP\_IDC, SYSEXCP\_INT\_FP\_IDC.

# 20 System Tick (SysTick)

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## 20.1 Introduction

SysTick is a simple timer that is part of the NVIC controller in the Cortex-M4 microprocessor. Its intended purpose is to provide a periodic interrupt for a RTOS, but it can be used for other simple timing purposes.

The SysTick interrupt handler does not need to clear the SysTick interrupt source. This will be done automatically by NVIC when the SysTick interrupt handler is called.

## 20.2 Functions

## **Functions**

- void ROM\_SysTickDisable (void)
- void ROM\_SysTickEnable (void)
- void ROM SysTickIntDisable (void)
- void ROM\_SysTickIntEnable (void)
- uint32\_t ROM\_SysTickPeriodGet (void)
- void ROM\_SysTickPeriodSet (uint32\_t ui32Period)
- uint32 t ROM SysTickValueGet (void)

## 20.2.1 Function Documentation

## 20.2.1.1 ROM SysTickDisable

Disables the SysTick counter.

#### Prototype:

```
void
ROM_SysTickDisable(void)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSTICKTABLE is an array of pointers located at ROM_APITABLE[10].

ROM_SysTickDisable is a function pointer located at ROM_SYSTICKTABLE[2].
```

### **Description:**

This will stop the SysTick counter. If an interrupt handler has been registered, it will no longer be called until SysTick is restarted.

#### Returns:

None.

## 20.2.1.2 ROM\_SysTickEnable

Enables the SysTick counter.

### Prototype:

void
ROM\_SysTickEnable(void)

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_SYSTICKTABLE is an array of pointers located at ROM_APITABLE[10].
ROM_SysTickEnable is a function pointer located at ROM_SYSTICKTABLE[1].
```

#### **Description:**

This will start the SysTick counter. If an interrupt handler has been registered, it is called when the SysTick counter rolls over.

#### Note:

Calling this function will cause the SysTick counter to (re)commence counting from its current value. The counter is not automatically reloaded with the period as specified in a previous call to ROM\_SysTickPeriodSet(). If an immediate reload is required, the NVIC\_ST\_CURRENT register must be written to force this. Any write to this register clears the SysTick counter to 0 and will cause a reload with the supplied period on the next clock.

#### Returns:

None.

## 20.2.1.3 ROM SysTickIntDisable

Disables the SysTick interrupt.

#### Prototype:

```
void
ROM_SysTickIntDisable(void)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSTICKTABLE is an array of pointers located at ROM_APITABLE[10].

ROM_SysTickIntDisable is a function pointer located at ROM_SYSTICKTABLE[4].
```

#### **Description:**

This function will disable the SysTick interrupt, preventing it from being reflected to the processor

#### Returns:

None.

## 20.2.1.4 ROM SysTickIntEnable

Enables the SysTick interrupt.

### Prototype:

```
void
ROM_SysTickIntEnable(void)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSTICKTABLE is an array of pointers located at ROM_APITABLE[10].

ROM_SysTickIntEnable is a function pointer located at ROM_SYSTICKTABLE[3].
```

### **Description:**

This function will enable the SysTick interrupt, allowing it to be reflected to the processor.

#### Note:

The SysTick interrupt handler does not need to clear the SysTick interrupt source as this is done automatically by NVIC when the interrupt handler is called.

#### Returns:

None.

## 20.2.1.5 ROM SysTickPeriodGet

Gets the period of the SysTick counter.

## Prototype:

```
uint32_t
ROM_SysTickPeriodGet(void)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSTICKTABLE is an array of pointers located at ROM_APITABLE[10].

ROM_SysTickPeriodGet is a function pointer located at ROM_SYSTICKTABLE[6].
```

#### **Description:**

This function returns the rate at which the SysTick counter wraps; this equates to the number of processor clocks between interrupts.

#### Returns:

Returns the period of the SysTick counter.

## 20.2.1.6 ROM SysTickPeriodSet

Sets the period of the SysTick counter.

#### Prototype:

```
void
ROM_SysTickPeriodSet(uint32_t ui32Period)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSTICKTABLE is an array of pointers located at ROM_APITABLE[10].

ROM_SysTickPeriodSet is a function pointer located at ROM_SYSTICKTABLE[5].
```

#### Parameters:

*ui32Period* is the number of clock ticks in each period of the SysTick counter; must be between 1 and 16,777,216, inclusive.

### **Description:**

This function sets the rate at which the SysTick counter wraps; this equates to the number of processor clocks between interrupts.

#### Note:

Calling this function does not cause the SysTick counter to reload immediately. If an immediate reload is required, the **NVIC\_ST\_CURRENT** register must be written. Any write to this register clears the SysTick counter to 0 and will cause a reload with the *ui32Period* supplied here on the next clock after the SysTick is enabled.

#### Returns:

None.

## 20.2.1.7 ROM\_SysTickValueGet

Gets the current value of the SysTick counter.

## Prototype:

```
uint32_t
ROM_SysTickValueGet(void)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_SYSTICKTABLE is an array of pointers located at ROM_APITABLE[10].

ROM_SysTickValueGet is a function pointer located at ROM_SYSTICKTABLE[0].
```

#### **Description:**

This function returns the current value of the SysTick counter; this will be a value between the period - 1 and zero, inclusive.

### Returns:

Returns the current value of the SysTick counter.

## 21 Timer

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## 21.1 Introduction

The timer API provides a set of functions for dealing with the timer module. Functions are provided to configure and control the timer, along with functions to modify timer/counter values, and to manage interrupt handling for the timer.

The timer module provides two 16-bit timer/counters that can be configured to operate independently as timers or event counters, or they can be configured to operate as one 32-bit timer or one 32-bit Real Time Clock (RTC). For the purpose of this API, the two timers provided by the timer are referred to as TimerA and TimerB.

When configured as either a 32-bit or 16-bit timer, a timer can be set up to run as a one-shot timer or a continuous timer. If configured as a one-shot timer, when it reaches zero the timer will cease counting. If configured as a continuous timer, when it reaches zero the timer will continue counting from a reloaded value. When configured as a 32-bit timer, the timer can also be configured to operate as an RTC. In that case, the timer expects to be driven by a 32 KHz external clock, which is divided down to produce 1 second clock ticks.

When in 16-bit mode, the timer can also be configured for event capture or as a Pulse Width Modulation (PWM) generator. When configured for event capture, the timer acts as a counter. It can be configured to either count the time between events, or it can count the events themselves. The type of event being counted can be configured as a positive edge, a negative edge, or both edges. When a timer is configured as a PWM generator, the input line used to capture events becomes an output line, and the timer is used to drive an edge-aligned pulse onto that line.

The timer module also provides the ability to control other functional parameters, such as output inversion, output triggers, and timer behavior during stalls.

Control is also provided over interrupt sources and events. Interrupts can be generated to indicate that an event has been captured, or that a certain number of events have been captured. Interrupts can also be generated when the timer has counted down to zero, or when the RTC matches a certain value.

## 21.2 Functions

## **Functions**

- void ROM\_TimerConfigure (uint32\_t ui32Base, uint32\_t ui32Config)
- void ROM\_TimerControlEvent (uint32\_t ui32Base, uint32\_t ui32Timer, uint32\_t ui32Event)
- void ROM TimerControlLevel (uint32 t ui32Base, uint32 t ui32Timer, bool bInvert)
- void ROM\_TimerControlStall (uint32\_t ui32Base, uint32\_t ui32Timer, bool bStall)
- void ROM TimerControlTrigger (uint32 t ui32Base, uint32 t ui32Timer, bool bEnable)
- void ROM TimerControlWaitOnTrigger (uint32 t ui32Base, uint32 t ui32Timer, bool bWait)

- void ROM\_TimerDisable (uint32\_t ui32Base, uint32\_t ui32Timer)
- void ROM\_TimerEnable (uint32\_t ui32Base, uint32\_t ui32Timer)
- void ROM\_TimerIntClear (uint32\_t ui32Base, uint32\_t ui32IntFlags)
- void ROM TimerIntDisable (uint32 t ui32Base, uint32 t ui32IntFlags)
- void ROM\_TimerIntEnable (uint32\_t ui32Base, uint32\_t ui32IntFlags)
- uint32 t ROM TimerIntStatus (uint32 t ui32Base, bool bMasked)
- uint32 t ROM TimerLoadGet (uint32 t ui32Base, uint32 t ui32Timer)
- uint64\_t ROM\_TimerLoadGet64 (uint32\_t ui32Base)
- void ROM\_TimerLoadSet (uint32\_t ui32Base, uint32\_t ui32Timer, uint32\_t ui32Value)
- void ROM TimerLoadSet64 (uint32 t ui32Base, uint64 t ui64Value)
- uint32\_t ROM\_TimerMatchGet (uint32\_t ui32Base, uint32\_t ui32Timer)
- uint64\_t ROM\_TimerMatchGet64 (uint32\_t ui32Base)
- void ROM\_TimerMatchSet (uint32\_t ui32Base, uint32\_t ui32Timer, uint32\_t ui32Value)
- void ROM TimerMatchSet64 (uint32 t ui32Base, uint64 t ui64Value)
- uint32\_t ROM\_TimerPrescaleGet (uint32\_t ui32Base, uint32\_t ui32Timer)
- uint32 t ROM TimerPrescaleMatchGet (uint32 t ui32Base, uint32 t ui32Timer)
- void ROM\_TimerPrescaleMatchSet (uint32\_t ui32Base, uint32\_t ui32Timer, uint32\_t ui32Value)
- void ROM\_TimerPrescaleSet (uint32\_t ui32Base, uint32\_t ui32Timer, uint32\_t ui32Value)
- void ROM\_TimerRTCDisable (uint32\_t ui32Base)
- void ROM\_TimerRTCEnable (uint32\_t ui32Base)
- uint32 t ROM TimerValueGet (uint32 t ui32Base, uint32 t ui32Timer)
- uint64 t ROM TimerValueGet64 (uint32 t ui32Base)

## 21.2.1 Function Documentation

## 21.2.1.1 ROM TimerConfigure

Configures the timer(s).

#### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].

ROM_TimerConfigure is a function pointer located at ROM_TIMERTABLE[3].
```

#### Parameters:

ui32Base is the base address of the timer module.ui32Config is the configuration for the timer.

#### **Description:**

This function configures the operating mode of the timer(s). The timer module is disabled before being configured, and is left in the disabled state. There are two types of timers; a 16/32-bit variety and a 32/64-bit variety. The 16/32-bit variety is comprised of two 16-bit timers

that can operate independently or be concatenated to form a 32-bit timer. Similarly, the 32/64-bit variety is comprised of two 32-bit timers that can operate independently or be concatenated to form a 64-bit timer.

The configuration is specified in *ui32Config* as one of the following values:

- TIMER CFG ONE SHOT Full-width one-shot timer
- TIMER\_CFG\_ONE\_SHOT\_UP Full-width one-shot timer that counts up instead of down (not available on all parts)
- TIMER\_CFG\_PERIODIC Full-width periodic timer
- TIMER\_CFG\_PERIODIC\_UP Full-width periodic timer that counts up instead of down (not available on all parts)
- TIMER CFG RTC Full-width real time clock timer
- TIMER CFG\_SPLIT\_PAIR Two half-width timers

When configured for a pair of half-width timers, each timer is separately configured. The first timer is configured by setting *ui32Config* to the result of a logical OR operation between one of the following values and *ui32Config*:

- TIMER CFG A ONE SHOT Half-width one-shot timer
- TIMER\_CFG\_A\_ONE\_SHOT\_UP Half-width one-shot timer that counts up instead of down (not available on all parts)
- TIMER CFG A PERIODIC Half-width periodic timer
- TIMER\_CFG\_A\_PERIODIC\_UP Half-width periodic timer that counts up instead of down (not available on all parts)
- TIMER CFG A CAP COUNT Half-width edge count capture
- TIMER\_CFG\_A\_CAP\_COUNT\_UP Half-width edge count capture that counts up instead of down (not available on all parts)
- TIMER CFG A CAP TIME Half-width edge time capture
- TIMER\_CFG\_A\_CAP\_TIME\_UP Half-width edge time capture that counts up instead of down (not available on all parts)
- TIMER CFG A PWM Half-width PWM output

Similarly, the second timer is configured by setting *ui32Config* to the result of a logical OR operation between one of the corresponding **TIMER\_CFG\_B\_\*** values and *ui32Config*.

#### Returns:

None.

## 21.2.1.2 ROM TimerControlEvent

Controls the event type.

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].
ROM_TimerControlEvent is a function pointer located at ROM_TIMERTABLE[6].
```

#### Parameters:

ui32Base is the base address of the timer module.

ui32Timer specifies the timer(s) to be adjusted; must be one of TIMER\_A, TIMER\_B, or TIMER\_BOTH.

ui32Event specifies the type of event; must be one of TIMER\_EVENT\_POS\_EDGE, TIMER EVENT NEG EDGE, or TIMER EVENT BOTH EDGES.

## **Description:**

This function sets the signal edge(s) that triggers the timer when in capture mode.

#### Returns:

None.

## 21.2.1.3 ROM TimerControlLevel

Controls the output level.

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].
ROM_TimerControlLevel is a function pointer located at ROM_TIMERTABLE[4].
```

#### **Parameters:**

ui32Base is the base address of the timer module.

ui32Timer specifies the timer(s) to adjust; must be one of TIMER\_A, TIMER\_B, or TIMER BOTH.

binvert specifies the output level.

#### **Description:**

This function sets the PWM output level for the specified timer. If the *blnvert* parameter is **true**, then the timer's output is made active low; otherwise, it is made active high.

#### Returns:

None.

## 21.2.1.4 ROM\_TimerControlStall

Controls the stall handling.

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].
ROM_TimerControlStall is a function pointer located at ROM_TIMERTABLE[7].
```

#### Parameters:

ui32Base is the base address of the timer module.

ui32Timer specifies the timer(s) to be adjusted; must be one of TIMER\_A, TIMER\_B, or TIMER BOTH.

**bStall** specifies the response to a stall signal.

#### **Description:**

This function controls the stall response for the specified timer. If the *bStall* parameter is **true**, then the timer will stop counting if the processor enters debug mode; otherwise the timer will keep running while in debug mode.

#### Returns:

None.

## 21.2.1.5 ROM\_TimerControlTrigger

Enables or disables the trigger output.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].

ROM_TimerControlTrigger is a function pointer located at ROM_TIMERTABLE[5].
```

## Parameters:

ui32Base is the base address of the timer module.

ui32Timer specifies the timer to adjust; must be one of TIMER\_A, TIMER\_B, or TIMER BOTH.

**bEnable** specifies the desired trigger state.

#### **Description:**

This function controls the trigger output for the specified timer. If the *bEnable* parameter is **true**, then the timer's output trigger is enabled; otherwise it is disabled.

#### Returns:

None.

## 21.2.1.6 ROM TimerControlWaitOnTrigger

Controls the wait on trigger handling.

## Prototype:

void

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.

ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].

ROM_TimerControlWaitOnTrigger is a function pointer located at ROM_TIMERTABLE[22].
```

#### Parameters:

ui32Base is the base address of the timer module.

ui32Timer specifies the timer(s) to be adjusted; must be one of TIMER\_A, TIMER\_B, or TIMER BOTH.

**bWait** specifies if the timer should wait for a trigger input.

#### **Description:**

This function controls whether or not a timer waits for a trigger input to start counting. When enabled, the previous timer in the trigger chain must count to its timeout in order for this timer to start counting. Refer to the data sheet for a description of the trigger chain.

## Returns:

None.

## 21.2.1.7 ROM TimerDisable

Disables the timer(s).

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].
ROM_TimerDisable is a function pointer located at ROM_TIMERTABLE[2].
```

#### Parameters:

ui32Base is the base address of the timer module.

ui32Timer specifies the timer(s) to disable; must be one of TIMER\_A, TIMER\_B, or TIMER BOTH.

#### **Description:**

This will disable operation of the timer module.

#### Returns:

None.

## 21.2.1.8 ROM TimerEnable

Enables the timer(s).

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].

ROM_TimerEnable is a function pointer located at ROM_TIMERTABLE[1].
```

#### Parameters:

ui32Base is the base address of the timer module.

ui32Timer specifies the timer(s) to enable; must be one of TIMER\_A, TIMER\_B, or TIMER BOTH.

### **Description:**

This will enable operation of the timer module. The timer must be configured before it is enabled.

#### Returns:

None.

## 21.2.1.9 ROM\_TimerIntClear

Clears timer interrupt sources.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].
ROM_TimerIntClear is a function pointer located at ROM_TIMERTABLE[0].
```

#### Parameters:

ui32Base is the base address of the timer module.ui32IntFlags is a bit mask of the interrupt sources to be cleared.

#### **Description:**

The specified timer interrupt sources are cleared, so that they no longer assert. This must be done in the interrupt handler to keep it from being called again immediately upon exit.

The *ui32IntFlags* parameter has the same definition as the *ui32IntFlags* parameter to ROM\_TimerIntEnable().

#### Note:

Because there is a write buffer in the Cortex-M4 processor, it may take several clock cycles before the interrupt source is actually cleared. Therefore, it is recommended that the interrupt source be cleared early in the interrupt handler (as opposed to the very last action) to avoid returning from the interrupt handler before the interrupt source is actually cleared. Failure to do so may result in the interrupt handler being immediately reentered (because the interrupt controller still sees the interrupt source asserted).

#### Returns:

None.

## 21.2.1.10 ROM TimerIntDisable

Disables individual timer interrupt sources.

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].

ROM_TimerIntDisable is a function pointer located at ROM_TIMERTABLE[20].
```

## Parameters:

ui32Base is the base address of the timer module.ui32IntFlags is the bit mask of the interrupt sources to be disabled.

### **Description:**

Disables the indicated timer interrupt sources. Only the sources that are enabled can be reflected to the processor interrupt; disabled sources have no effect on the processor.

The *ui32IntFlags* parameter has the same definition as the *ui32IntFlags* parameter to ROM\_TimerIntEnable().

#### Returns:

None.

## 21.2.1.11 ROM\_TimerIntEnable

Enables individual timer interrupt sources.

## Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].

ROM_TimerIntEnable is a function pointer located at ROM_TIMERTABLE[19].
```

#### Parameters:

ui32Base is the base address of the timer module.

ui32IntFlags is the bit mask of the interrupt sources to be enabled.

#### **Description:**

Enables the indicated timer interrupt sources. Only the sources that are enabled can be reflected to the processor interrupt; disabled sources have no effect on the processor.

The ui32IntFlags parameter must be the logical OR of any combination of the following:

- TIMER CAPB EVENT Capture B event interrupt
- TIMER CAPB MATCH Capture B match interrupt
- TIMER\_TIMB\_TIMEOUT Timer B timeout interrupt
- TIMER\_RTC\_MATCH RTC interrupt mask
- TIMER CAPA EVENT Capture A event interrupt
- TIMER CAPA MATCH Capture A match interrupt
- TIMER TIMA TIMEOUT Timer A timeout interrupt

#### Returns:

None.

## 21.2.1.12 ROM TimerIntStatus

Gets the current interrupt status.

## Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].

ROM_TimerIntStatus is a function pointer located at ROM_TIMERTABLE[21].
```

#### Parameters:

ui32Base is the base address of the timer module.

**bMasked** is false if the raw interrupt status is required and true if the masked interrupt status is required.

#### **Description:**

This returns the interrupt status for the timer module. Either the raw interrupt status or the status of interrupts that are allowed to reflect to the processor can be returned.

#### Returns:

The current interrupt status, enumerated as a bit field of values described in ROM\_TimerIntEnable().

## 21.2.1.13 ROM TimerLoadGet

Gets the timer load value.

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].
ROM_TimerLoadGet is a function pointer located at ROM_TIMERTABLE[15].
```

#### Parameters:

ui32Base is the base address of the timer module.

ui32Timer specifies the timer; must be one of TIMER\_A or TIMER\_B. Only TIMER\_A should be used when the timer is configured for full-width operation.

## **Description:**

This function gets the currently programmed interval load value for the specified timer.

#### Note:

This function can be used for both full- and half-width modes of 16/32-bit timers, and for half-width modes of 32/64-bit timers. Use ROM\_TimerLoadGet64() for full-width modes of 32/64-bit timers.

#### Returns:

Returns the load value for the timer.

## 21.2.1.14 ROM TimerLoadGet64

Gets the timer load value for a 64-bit timer.

## Prototype:

```
uint64_t
ROM_TimerLoadGet64(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].

ROM_TimerLoadGet 64 is a function pointer located at ROM_TIMERTABLE[24].
```

#### **Parameters:**

ui32Base is the base address of the timer module.

#### **Description:**

This function gets the currently programmed interval load value for the specified 64-bit timer.

#### Returns:

Returns the load value for the timer.

## 21.2.1.15 ROM TimerLoadSet

Sets the timer load value.

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE [11].
ROM_TimerLoadSet is a function pointer located at ROM_TIMERTABLE [14].
```

#### Parameters:

ui32Base is the base address of the timer module.

ui32Timer specifies the timer(s) to adjust; must be one of TIMER\_A, TIMER\_B, or TIMER\_BOTH. Only TIMER\_A should be used when the timer is configured for full-width operation.

ui32Value is the load value.

#### **Description:**

This function sets the timer load value; if the timer is running then the value is immediately loaded into the timer.

#### Note:

This function can be used for both full- and half-width modes of 16/32-bit timers, and for half-width modes of 32/64-bit timers. Use ROM\_TimerLoadSet64() for full-width modes of 32/64-bit timers.

#### Returns:

None.

## 21.2.1.16 ROM TimerLoadSet64

Sets the timer load value for a 64-bit timer.

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE [11].
ROM_TimerLoadSet 64 is a function pointer located at ROM_TIMERTABLE [23].
```

### Parameters:

ui32Base is the base address of the timer module.ui64Value is the load value.

## **Description:**

This function sets the timer load value for a 64-bit timer; if the timer is running then the value is immediately loaded into the timer.

#### Returns:

None.

## 21.2.1.17 ROM TimerMatchGet

Gets the timer match value.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].

ROM_TimerMatchGet is a function pointer located at ROM_TIMERTABLE[18].
```

#### Parameters:

ui32Base is the base address of the timer module.

ui32Timer specifies the timer; must be one of TIMER\_A or TIMER\_B. Only TIMER\_A should be used when the timer is configured for full-width operation.

## **Description:**

This function gets the match value for the specified timer.

#### Note:

This function can be used for both full- and half-width modes of 16/32-bit timers, and for half-width modes of 32/64-bit timers. Use ROM\_TimerMatchGet64() for full-width modes of 32/64-bit timers.

#### Returns:

Returns the match value for the timer.

## 21.2.1.18 ROM TimerMatchGet64

Gets the timer match value for a 64-bit timer.

## Prototype:

```
uint64_t
ROM_TimerMatchGet64(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].

ROM_TimerMatchGet64 is a function pointer located at ROM_TIMERTABLE[27].
```

#### Parameters:

ui32Base is the base address of the timer module.

## **Description:**

This function gets the match value for the specified timer.

#### Returns:

Returns the match value for the timer.

## 21.2.1.19 ROM TimerMatchSet

Sets the timer match value.

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].

ROM_TimerMatchSet is a function pointer located at ROM_TIMERTABLE[17].
```

#### Parameters:

ui32Base is the base address of the timer module.

ui32Timer specifies the timer(s) to adjust; must be one of TIMER\_A, TIMER\_B, or TIMER\_BOTH. Only TIMER\_A should be used when the timer is configured for full-width operation.

ui32Value is the match value.

#### **Description:**

This function sets the match value for a timer. This value is used in capture count mode to determine when to interrupt the processor and in PWM mode to determine the duty cycle of the output signal.

#### Note:

This function can be used for both full- and half-width modes of 16/32-bit timers, and for half-width modes of 32/64-bit timers. Use ROM\_TimerMatchSet64() for full-width modes of 32/64-bit timers.

#### Returns:

None.

## 21.2.1.20 ROM\_TimerMatchSet64

Sets the timer match value for a 64-bit timer.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].

ROM_TimerMatchSet64 is a function pointer located at ROM_TIMERTABLE[26].
```

## Parameters:

ui32Base is the base address of the timer module.
ui64Value is the match value.

### **Description:**

This function sets the match value for a timer. This value is used in capture count mode to determine when to interrupt the processor and in PWM mode to determine the duty cycle of the output signal.

#### Returns:

None.

## 21.2.1.21 ROM TimerPrescaleGet

Get the timer prescale value.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].

ROM_TimerPrescaleGet is a function pointer located at ROM_TIMERTABLE[11].
```

#### Parameters:

ui32Base is the base address of the timer module.ui32Timer specifies the timer; must be one of TIMER\_A or TIMER\_B.

### **Description:**

This function gets the value of the input clock prescaler. The prescaler is only operational when in half-width mode and is used to extend the range of the half-width timer modes.

### Returns:

The value of the timer prescaler.

## 21.2.1.22 ROM TimerPrescaleMatchGet

Get the timer prescale match value.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].
ROM_TimerPrescaleMatchGet is a function pointer located at ROM_TIMERTABLE[13].
```

## Parameters:

ui32Base is the base address of the timer module.ui32Timer specifies the timer; must be one of TIMER A or TIMER B.

#### **Description:**

This function gets the value of the input clock prescaler match value. When in a half-width mode that uses the counter match and prescaler, the prescale match effectively extends the range of the match.

#### Returns:

The value of the timer prescale match.

## 21.2.1.23 ROM TimerPrescaleMatchSet

Set the timer prescale match value.

#### Prototype:

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].
ROM_TimerPrescaleMatchSet is a function pointer located at ROM_TIMERTABLE[12].
```

#### Parameters:

ui32Base is the base address of the timer module.

ui32Timer specifies the timer(s) to adjust; must be one of TIMER\_A, TIMER\_B, or TIMER BOTH.

*ui32Value* is the timer prescale match value which must be between 0 and 255 (inclusive) for 16/32-bit timers and between 0 and 65535 (inclusive) for 32/64-bit timers.

## **Description:**

This function sets the value of the input clock prescaler match value. When in a half-width mode that uses the counter match and the prescaler, the prescale match effectively extends the range of the match.

#### Returns:

None.

## 21.2.1.24 ROM\_TimerPrescaleSet

Set the timer prescale value.

## **Prototype:**

```
void
```

```
ROM_TimerPrescaleSet(uint32_t ui32Base, uint32_t ui32Timer, uint32_t ui32Value)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].

ROM_TimerPrescaleSet is a function pointer located at ROM_TIMERTABLE[10].
```

## Parameters:

ui32Base is the base address of the timer module.

ui32Timer specifies the timer(s) to adjust; must be one of TIMER\_A, TIMER\_B, or TIMER BOTH.

*ui32Value* is the timer prescale value which must be between 0 and 255 (inclusive) for 16/32-bit timers and between 0 and 65535 (inclusive) for 32/64-bit timers.

#### **Description:**

This function sets the value of the input clock prescaler. The prescaler is only operational when in half-width mode and is used to extend the range of the half-width timer modes.

#### Returns:

None.

## 21.2.1.25 ROM\_TimerRTCDisable

Disable RTC counting.

#### Prototype:

```
void
```

```
ROM_TimerRTCDisable(uint32_t ui32Base)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].

ROM_TimerRTCDisable is a function pointer located at ROM_TIMERTABLE[9].
```

#### Parameters:

ui32Base is the base address of the timer module.

#### **Description:**

This function causes the timer to stop counting when in RTC mode.

#### Returns:

None.

## 21.2.1.26 ROM TimerRTCEnable

Enable RTC counting.

## **Prototype:**

```
void
ROM_TimerRTCEnable(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].

ROM_TimerRTCEnable is a function pointer located at ROM_TIMERTABLE[8].
```

#### Parameters:

ui32Base is the base address of the timer module.

#### Description:

This function causes the timer to start counting when in RTC mode. If not configured for RTC mode, this will do nothing.

#### Returns:

None.

## 21.2.1.27 ROM TimerValueGet

Gets the current timer value.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].

ROM_TimerValueGet is a function pointer located at ROM_TIMERTABLE[16].
```

### Parameters:

ui32Base is the base address of the timer module.

ui32Timer specifies the timer; must be one of TIMER\_A or TIMER\_B. Only TIMER\_A should be used when the timer is configured for full-width operation.

#### **Description:**

This function reads the current value of the specified timer.

#### Note:

This function can be used for both full- and half-width modes of 16/32-bit timers, and for half-width modes of 32/64-bit timers. Use ROM\_TimerValueGet64() for full-width modes of 32/64-bit timers.

#### Returns:

Returns the current value of the timer.

## 21.2.1.28 ROM\_TimerValueGet64

Gets the current 64-bit timer value.

## Prototype:

```
uint64_t
ROM_TimerValueGet64(uint32_t ui32Base)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_TIMERTABLE is an array of pointers located at ROM_APITABLE[11].

ROM_TimerValueGet 64 is a function pointer located at ROM_TIMERTABLE[25].
```

#### Parameters:

ui32Base is the base address of the timer module.

## **Description:**

This function reads the current value of the specified timer.

#### Returns:

Returns the current value of the timer.

## **22 UART**

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## 22.1 Introduction

The Universal Asynchronous Receiver/Transmitter (UART) API provides a set of functions for using the UART modules. Functions are provided to configure and control the UART modules, to send and receive data, and to manage interrupts for the UART modules.

The UART performs the functions of parallel-to-serial and serial-to-parallel conversions. It is very similar in functionality to a 16C550 UART, but is not register-compatible.

Some of the features of the UART are:

- A 16x12 bit receive FIFO and a 16x8 bit transmit FIFO.
- Programmable baud rate generator.
- Automatic generation and stripping of start, stop, and parity bits.
- Line break generation and detection.
- Programmable serial interface
  - 5, 6, 7, or 8 data bits
  - even, odd, stick, or no parity bit generation and detection
  - 1 or 2 stop bit generation
  - baud rate generation, from DC to processor clock/16
- IrDA serial-IR (SIR) encoder/decoder.
- DMA interface

## 22.2 Functions

## **Functions**

- void ROM UART9BitAddrSend (uint32 t ui32Base, uint8 t ui8Addr)
- void ROM UART9BitAddrSet (uint32 t ui32Base, uint8 t ui8Addr, uint8 t ui8Mask)
- void ROM UART9BitDisable (uint32 t ui32Base)
- void ROM UART9BitEnable (uint32 t ui32Base)
- void ROM\_UARTBreakCtl (uint32\_t ui32Base, bool bBreakState)
- bool ROM UARTBusy (uint32 t ui32Base)
- int32\_t ROM\_UARTCharGet (uint32\_t ui32Base)
- int32 t ROM UARTCharGetNonBlocking (uint32 t ui32Base)
- void ROM UARTCharPut (uint32 t ui32Base, uint8 t ui8Data)
- bool ROM\_UARTCharPutNonBlocking (uint32\_t ui32Base, uint8\_t ui8Data)
- bool ROM UARTCharsAvail (uint32 t ui32Base)
- uint32\_t ROM\_UARTClockSourceGet (uint32\_t ui32Base)

- void ROM UARTClockSourceSet (uint32 t ui32Base, uint32 t ui32Source)
- void ROM\_UARTConfigGetExpClk (uint32\_t ui32Base, uint32\_t ui32UARTClk, uint32\_t \*pui32Baud, uint32\_t \*pui32Config)
- void ROM\_UARTConfigSetExpClk (uint32\_t ui32Base, uint32\_t ui32UARTClk, uint32\_t ui32Baud, uint32\_t ui32Config)
- void ROM\_UARTDisable (uint32\_t ui32Base)
- void ROM UARTDisableSIR (uint32 t ui32Base)
- void ROM UARTDMADisable (uint32 t ui32Base, uint32 t ui32DMAFlags)
- void ROM\_UARTDMAEnable (uint32\_t ui32Base, uint32\_t ui32DMAFlags)
- void ROM UARTEnable (uint32 t ui32Base)
- void ROM\_UARTEnableSIR (uint32\_t ui32Base, bool bLowPower)
- void ROM UARTFIFODisable (uint32 t ui32Base)
- void ROM UARTFIFOEnable (uint32 t ui32Base)
- void ROM\_UARTFIFOLevelGet (uint32\_t ui32Base, uint32\_t \*pui32TxLevel, uint32\_t \*pui32RxLevel)
- void ROM\_UARTFIFOLevelSet (uint32\_t ui32Base, uint32\_t ui32TxLevel, uint32\_t ui32RxLevel)
- void ROM\_UARTIntClear (uint32\_t ui32Base, uint32\_t ui32IntFlags)
- void ROM UARTIntDisable (uint32 t ui32Base, uint32 t ui32IntFlags)
- void ROM UARTIntEnable (uint32 t ui32Base, uint32 t ui32IntFlags)
- uint32 t ROM UARTIntStatus (uint32 t ui32Base, bool bMasked)
- uint32\_t ROM\_UARTParityModeGet (uint32\_t ui32Base)
- void ROM\_UARTParityModeSet (uint32\_t ui32Base, uint32\_t ui32Parity)
- void ROM\_UARTRxErrorClear (uint32\_t ui32Base)
- uint32 t ROM UARTRxErrorGet (uint32 t ui32Base)
- bool ROM UARTSpaceAvail (uint32 t ui32Base)
- uint32 t ROM UARTTxIntModeGet (uint32 t ui32Base)
- void ROM UARTTxIntModeSet (uint32 t ui32Base, uint32 t ui32Mode)
- void ROM UpdateUART (void)

## 22.2.1 Function Documentation

## 22.2.1.1 ROM UART9BitAddrSend

Sends an address character from the specified port when operating in 9-bit mode.

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UART9BitAddrSend is a function pointer located at ROM_UARTTABLE[36].
```

#### Parameters:

ui32Base is the base address of the UART port.

ui8Addr is the address to be transmitted.

## **Description:**

This function waits until all data has been sent from the specified port and then sends the given address as an address byte. It then waits until the address byte has been transmitted before returning.

The normal data functions (ROM\_UARTCharPut(), ROM\_UARTCharPutNonBlocking(), ROM\_UARTCharGet(), and ROM\_UARTCharGetNonBlocking()) are used to send and receive data characters in 9-bit mode.

#### Returns:

None.

## 22.2.1.2 ROM\_UART9BitAddrSet

Sets the device address(es) for 9-bit mode.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UART9BitAddrSet is a function pointer located at ROM_UARTTABLE[35].
```

### Parameters:

```
ui32Base is the base address of the UART port.ui8Addr is the device address.ui8Mask is the device address mask.
```

#### **Description:**

This function sets the device address, or range of device addresses, that respond to requests on the 9-bit UART port. The received address is masked with the mask and then compared against the given address, allowing either a single address (if **ui8Mask** is 0xff) or a set of addresses to be matched.

#### Returns:

None.

## 22.2.1.3 ROM\_UART9BitDisable

Disables 9-bit mode on the specified UART.

#### Prototype:

```
void
ROM_UART9BitDisable(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UART9BitDisable is a function pointer located at ROM_UARTTABLE[34].
```

#### Parameters:

ui32Base is the base address of the UART port.

## **Description:**

This function disables the 9-bit operational mode of the UART.

#### Returns:

None.

## 22.2.1.4 ROM UART9BitEnable

Enables 9-bit mode on the specified UART.

## Prototype:

```
void
ROM_UART9BitEnable(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UART9BitEnable is a function pointer located at ROM_UARTTABLE[33].
```

#### Parameters:

ui32Base is the base address of the UART port.

## **Description:**

This function enables the 9-bit operational mode of the UART.

#### Returns:

None.

## 22.2.1.5 ROM UARTBreakCtl

Causes a BREAK to be sent.

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTBreakCtl is a function pointer located at ROM_UARTTABLE[16].
```

## Parameters:

ui32Base is the base address of the UART port.

bBreakState controls the output level.

#### Description:

Calling this function with *bBreakState* set to **true** asserts a break condition on the UART. Calling this function with *bBreakState* set to **false** removes the break condition. For proper transmission of a break command, the break must be asserted for at least two complete frames.

#### Returns:

None.

## 22.2.1.6 ROM\_UARTBusy

Determines whether the UART transmitter is busy or not.

## Prototype:

```
bool
ROM UARTBusy(uint32 t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].
ROM_UARTBusy is a function pointer located at ROM_UARTTABLE[26].
```

#### Parameters:

ui32Base is the base address of the UART port.

### **Description:**

Allows the caller to determine whether all transmitted bytes have cleared the transmitter hardware. If **false** is returned, the transmit FIFO is empty and all bits of the last transmitted character, including all stop bits, have left the hardware shift register.

#### Returns:

Returns true if the UART is transmitting or false if all transmissions are complete.

## 22.2.1.7 ROM UARTCharGet

Waits for a character from the specified port.

#### Prototype:

```
int32_t
ROM_UARTCharGet(uint32_t ui32Base)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTCharGet is a function pointer located at ROM_UARTTABLE[14].
```

#### Parameters:

ui32Base is the base address of the UART port.

## **Description:**

Gets a character from the receive FIFO for the specified port. If there are no characters available, this function waits until a character is received before returning.

#### Returns:

Returns the character read from the specified port, cast as a *int32 t*.

## 22.2.1.8 ROM UARTCharGetNonBlocking

Receives a character from the specified port.

#### Prototype:

```
int32_t
ROM_UARTCharGetNonBlocking(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTCharGetNonBlocking is a function pointer located at ROM_UARTTABLE[13].
```

## Parameters:

ui32Base is the base address of the UART port.

## **Description:**

Gets a character from the receive FIFO for the specified port.

#### Returns:

Returns the character read from the specified port, cast as a *int32\_t*. A **-1** is returned if there are no characters present in the receive FIFO. The ROM\_UARTCharsAvail() function should be called before attempting to call this function.

## 22.2.1.9 ROM UARTCharPut

Waits to send a character from the specified port.

## Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010. ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1]. ROM_UARTCharPut is a function pointer located at ROM_UARTTABLE[0].
```

#### Parameters:

```
ui32Base is the base address of the UART port.
ui8Data is the character to be transmitted.
```

## **Description:**

Sends the character *ui8Data* to the transmit FIFO for the specified port. If there is no space available in the transmit FIFO, this function waits until there is space available before returning.

#### Returns:

None.

# 22.2.1.10 ROM UARTCharPutNonBlocking

Sends a character to the specified port.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTCharPutNonBlocking is a function pointer located at ROM_UARTTABLE[15].
```

#### Parameters:

ui32Base is the base address of the UART port.ui8Data is the character to be transmitted.

### **Description:**

Writes the character *ui8Data* to the transmit FIFO for the specified port. This function does not block, so if there is no space available, then a **false** is returned, and the application must retry the function later.

#### Returns:

Returns **true** if the character was successfully placed in the transmit FIFO or **false** if there was no space available in the transmit FIFO.

# 22.2.1.11 ROM UARTCharsAvail

Determines if there are any characters in the receive FIFO.

# Prototype:

```
bool
ROM_UARTCharsAvail(uint32_t ui32Base)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTCharsAvail is a function pointer located at ROM_UARTTABLE[11].
```

## Parameters:

ui32Base is the base address of the UART port.

### **Description:**

This function returns a flag indicating whether or not there is data available in the receive FIFO.

### Returns:

Returns true if there is data in the receive FIFO or false if there is no data in the receive FIFO.

# 22.2.1.12 ROM UARTClockSourceGet

Gets the baud clock source for the specified UART.

### Prototype:

```
uint32_t
ROM_UARTClockSourceGet(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTClockSourceGet is a function pointer located at ROM_UARTTABLE[32].
```

#### Parameters:

ui32Base is the base address of the UART port.

### **Description:**

This function returns the baud clock source for the specified UART. The possible baud clock source are the system clock (**UART\_CLOCK\_SYSTEM**) or the precision internal oscillator (**UART\_CLOCK\_PIOSC**).

### Returns:

None.

# 22.2.1.13 ROM\_UARTClockSourceSet

Sets the baud clock source for the specified UART.

#### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTClockSourceSet is a function pointer located at ROM_UARTTABLE[31].
```

#### Parameters:

```
ui32Base is the base address of the UART port.
ui32Source is the baud clock source for the UART.
```

#### **Description:**

This function allows the baud clock source for the UART to be selected. The possible clock source are the system clock (UART\_CLOCK\_SYSTEM) or the precision internal oscillator (UART CLOCK PIOSC).

Changing the baud clock source will change the baud rate generated by the UART. Therefore, the baud rate should be reconfigured after any change to the baud clock source.

# Returns:

None.

# 22.2.1.14 ROM UARTConfigGetExpClk

Gets the current configuration of a UART.

# Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTCOnfigGetExpClk is a function pointer located at ROM_UARTTABLE[6].
```

### Parameters:

```
ui32Base is the base address of the UART port.
ui32UARTCIk is the rate of the clock supplied to the UART module.
pui32Baud is a pointer to storage for the baud rate.
pui32Config is a pointer to storage for the data format.
```

### **Description:**

The baud rate and data format for the UART is determined, given an explicitly provided peripheral clock (hence the ExpClk suffix). The returned baud rate is the actual baud rate; it may not be the exact baud rate requested or an "official" baud rate. The data format returned in *pui32Config* is enumerated the same as the *ui32Config* parameter of ROM\_UARTConfigSetExpClk().

The peripheral clock is the same as the processor clock. This is the value returned by ROM\_SysCtlClockGet(), or it can be explicitly hard-coded if it is constant and known (to save the code/execution overhead of a call to ROM\_SysCtlClockGet()).

If the peripheral clock has been changed to PIOSC (via ROM\_UARTClockSourceSet()), the peripheral clock should be specified as 16,000,000 (the nominal rate of PIOSC).

#### Returns:

None.

# 22.2.1.15 ROM\_UARTConfigSetExpClk

Sets the configuration of a UART.

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTCOnfigSetExpClk is a function pointer located at ROM_UARTTABLE[5].
```

#### Parameters:

ui32Base is the base address of the UART port.

ui32UARTCIk is the rate of the clock supplied to the UART module.

ui32Baud is the desired baud rate.

ui32Config is the data format for the port (number of data bits, number of stop bits, and parity).

### **Description:**

This function configures the UART for operation in the specified data format. The baud rate is provided in the *ui32Baud* parameter and the data format in the *ui32Config* parameter.

The *ui32Config* parameter is the logical OR of three values: the number of data bits, the number of stop bits, and the parity. **UART CONFIG WLEN 8,** UART\_CONFIG\_WLEN\_6, UART CONFIG WLEN 7, and **UART CONFIG WLEN 5** select from eight to five data bits per byte (respectively). **UART CONFIG STOP ONE** UART CONFIG STOP TWO select one or two stop bits (respectively). UART CONFIG PAR NONE, UART CONFIG PAR EVEN, UART CONFIG PAR ODD, UART CONFIG PAR ONE, and UART CONFIG PAR ZERO select the parity mode (no parity bit, even parity bit, odd parity bit, parity bit always one, and parity bit always zero, respectively).

The peripheral clock is the same as the processor clock. This is the value returned by ROM\_SysCtlClockGet(), or it can be explicitly hard-coded if it is constant and known (to save the code/execution overhead of a call to ROM\_SysCtlClockGet()).

If the peripheral clock has been changed to PIOSC (via ROM\_UARTClockSourceSet()), the peripheral clock should be specified as 16,000,000 (the nominal rate of PIOSC).

### Returns:

None.

### 22.2.1.16 ROM UARTDisable

Disables transmitting and receiving.

#### Prototype:

void

ROM\_UARTDisable(uint32\_t ui32Base)

### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM UARTTABLE is an array of pointers located at ROM APITABLE[1].

ROM UARTDisable is a function pointer located at ROM UARTTABLE[8].

#### Parameters:

ui32Base is the base address of the UART port.

#### Description:

Clears the UARTEN, TXE, and RXE bits, then waits for the end of transmission of the current character, and flushes the transmit FIFO.

### Returns:

None.

# 22.2.1.17 ROM UARTDisableSIR

Disables SIR (IrDA) mode on the specified UART.

### Prototype:

```
void
ROM_UARTDisableSIR(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].
ROM_UARTDisableSIR is a function pointer located at ROM_UARTTABLE[10].
```

#### Parameters:

ui32Base is the base address of the UART port.

### **Description:**

Clears the SIREN (IrDA) and SIRLP (Low Power) bits.

#### Returns:

None.

# 22.2.1.18 ROM UARTDMADisable

Disable UART DMA operation.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTDMADisable is a function pointer located at ROM_UARTTABLE[23].
```

### Parameters:

```
ui32Base is the base address of the UART port.ui32DMAFlags is a bit mask of the DMA features to disable.
```

### **Description:**

This function is used to disable UART DMA features that were enabled by ROM\_UARTDMAEnable(). The specified UART DMA features are disabled. The ui32DMAFlags parameter is the logical OR of any of the following values:

- UART\_DMA\_RX disable DMA for receive
- UART\_DMA\_TX disable DMA for transmit
- UART\_DMA\_ERR\_RXSTOP do not disable DMA receive on UART error

### Returns:

None.

# 22.2.1.19 ROM UARTDMAEnable

Enable UART DMA operation.

# Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].
ROM_UARTDMAEnable is a function pointer located at ROM_UARTTABLE[22].
```

#### Parameters:

```
ui32Base is the base address of the UART port.ui32DMAFlags is a bit mask of the DMA features to enable.
```

### **Description:**

The specified UART DMA features are enabled. The UART can be configured to use DMA for transmit or receive, and to disable receive if an error occurs. The *ui32DMAFlags* parameter is the logical OR of any of the following values:

- UART\_DMA\_RX enable DMA for receive
- UART DMA TX enable DMA for transmit
- UART\_DMA\_ERR\_RXSTOP disable DMA receive on UART error

#### Note:

The uDMA controller must also be set up before DMA can be used with the UART.

### Returns:

None.

# 22.2.1.20 ROM UARTEnable

Enables transmitting and receiving.

### Prototype:

```
void
ROM_UARTEnable(uint32_t ui32Base)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].
ROM_UARTENable is a function pointer located at ROM_UARTTABLE[7].
```

#### Parameters:

ui32Base is the base address of the UART port.

#### Description

Sets the UARTEN, TXE, and RXE bits, and enables the transmit and receive FIFOs.

#### Returns:

None.

# 22.2.1.21 ROM UARTEnableSIR

Enables SIR (IrDA) mode on the specified UART.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTENableSIR is a function pointer located at ROM_UARTTABLE[9].
```

#### Parameters:

ui32Base is the base address of the UART port.bLowPower indicates if SIR Low Power Mode is to be used.

### **Description:**

Enables the SIREN control bit for IrDA mode on the UART. If the *bLowPower* flag is set, then SIRLP bit will also be set.

#### Returns:

None.

# 22.2.1.22 ROM UARTFIFODisable

Disables the transmit and receive FIFOs.

### Prototype:

```
void
ROM_UARTFIFODisable(uint32_t ui32Base)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].
ROM_UARTFIFODisable is a function pointer located at ROM_UARTTABLE[25].
```

#### Parameters:

ui32Base is the base address of the UART port.

### **Description:**

This functions disables the transmit and receive FIFOs in the UART.

### Returns:

None.

# 22.2.1.23 ROM UARTFIFOEnable

Enables the transmit and receive FIFOs.

# Prototype:

void

ROM\_UARTFIFOEnable(uint32\_t ui32Base)

#### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_UARTTABLE is an array of pointers located at ROM\_APITABLE[1].

ROM\_UARTFIFOEnable is a function pointer located at ROM\_UARTTABLE[24].

#### Parameters:

ui32Base is the base address of the UART port.

### **Description:**

This functions enables the transmit and receive FIFOs in the UART.

### Returns:

None.

# 22.2.1.24 ROM UARTFIFOLevelGet

Gets the FIFO level at which interrupts are generated.

# Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTFIFOLevelGet is a function pointer located at ROM_UARTTABLE[4].
```

#### Parameters:

ui32Base is the base address of the UART port.

```
pui32TxLevel is a pointer to storage for the transmit FIFO level, returned as one of
UART_FIFO_TX1_8, UART_FIFO_TX2_8, UART_FIFO_TX4_8, UART_FIFO_TX6_8, or
UART_FIFO_TX7_8.
```

pui32RxLevel is a pointer to storage for the receive FIFO level, returned as one of UART\_FIFO\_RX1\_8, UART\_FIFO\_RX2\_8, UART\_FIFO\_RX4\_8, UART\_FIFO\_RX6\_8, or UART\_FIFO\_RX7\_8.

### Description:

This function gets the FIFO level at which transmit and receive interrupts are generated.

### Returns:

None.

# 22.2.1.25 ROM UARTFIFOLevelSet

Sets the FIFO level at which interrupts are generated.

# **Prototype:**

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].
ROM_UARTFIFOLevelSet is a function pointer located at ROM_UARTTABLE[3].
```

### Parameters:

ui32Base is the base address of the UART port.

```
ui32TxLevel is the transmit FIFO interrupt level, specified as one of UART_FIFO_TX1_8, UART_FIFO_TX2_8, UART_FIFO_TX4_8, UART_FIFO_TX6_8, or UART_FIFO_TX7_8.
ui32RxLevel is the receive FIFO interrupt level, specified as one of UART_FIFO_RX1_8, UART_FIFO_RX2_8, UART_FIFO_RX4_8, UART_FIFO_RX6_8, or UART_FIFO_RX7_8.
```

### **Description:**

This function sets the FIFO level at which transmit and receive interrupts are generated.

# Returns:

None.

# 22.2.1.26 ROM\_UARTIntClear

Clears UART interrupt sources.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTINtClear is a function pointer located at ROM_UARTTABLE[20].
```

#### **Parameters:**

```
ui32Base is the base address of the UART port.ui32IntFlags is a bit mask of the interrupt sources to be cleared.
```

### **Description:**

The specified UART interrupt sources are cleared, so that they no longer assert. This function must be called in the interrupt handler to keep the interrupt from being recognized again immediately upon exit.

The *ui32IntFlags* parameter has the same definition as the *ui32IntFlags* parameter to ROM\_UARTIntEnable().

### Note:

Because there is a write buffer in the Cortex-M4 processor, it may take several clock cycles before the interrupt source is actually cleared. Therefore, it is recommended that the interrupt

source be cleared early in the interrupt handler (as opposed to the very last action) to avoid returning from the interrupt handler before the interrupt source is actually cleared. Failure to do so may result in the interrupt handler being immediately reentered (because the interrupt controller still sees the interrupt source asserted).

#### Returns:

None.

# 22.2.1.27 ROM UARTIntDisable

Disables individual UART interrupt sources.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTINEDisable is a function pointer located at ROM_UARTTABLE[18].
```

### Parameters:

ui32Base is the base address of the UART port.
ui32IntFlags is the bit mask of the interrupt sources to be disabled.

#### **Description:**

Disables the indicated UART interrupt sources. Only the sources that are enabled can be reflected to the processor interrupt; disabled sources have no effect on the processor.

The *ui32IntFlags* parameter has the same definition as the *ui32IntFlags* parameter to ROM\_UARTIntEnable().

#### Returns:

None.

# 22.2.1.28 ROM UARTIntEnable

Enables individual UART interrupt sources.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTINEEnable is a function pointer located at ROM_UARTTABLE[17].
```

### Parameters:

ui32Base is the base address of the UART port.

*ui32IntFlags* is the bit mask of the interrupt sources to be enabled.

### Description:

Enables the indicated UART interrupt sources. Only the sources that are enabled can be reflected to the processor interrupt; disabled sources have no effect on the processor.

The *ui32IntFlags* parameter is the logical OR of any of the following:

```
■ UART_INT_9BIT - 9-bit address match interrupt
```

```
■ UART INT OE - Overrun Error interrupt
```

■ UART\_INT\_BE - Break Error interrupt

■ UART INT PE - Parity Error interrupt

■ UART INT FE - Framing Error interrupt

■ UART\_INT\_RT - Receive Timeout interrupt

■ UART INT TX - Transmit interrupt

■ UART INT RX - Receive interrupt

■ UART INT DSR - DSR interrupt

■ UART INT DCD - DCD interrupt

■ UART INT CTS - CTS interrupt

■ UART\_INT\_RI - RI interrupt

#### Returns:

None.

# 22.2.1.29 ROM UARTIntStatus

Gets the current interrupt status.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTINtStatus is a function pointer located at ROM_UARTTABLE[19].
```

### Parameters:

ui32Base is the base address of the UART port.

**bMasked** is **false** if the raw interrupt status is required and **true** if the masked interrupt status is required.

# Description:

This returns the interrupt status for the specified UART. Either the raw interrupt status or the status of interrupts that are allowed to reflect to the processor can be returned.

#### Returns:

Returns the current interrupt status, enumerated as a bit field of values described in ROM\_UARTIntEnable().

# 22.2.1.30 ROM UARTParityModeGet

Gets the type of parity currently being used.

### Prototype:

```
uint32_t
ROM_UARTParityModeGet(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTParityModeGet is a function pointer located at ROM_UARTTABLE[2].
```

#### Parameters:

ui32Base is the base address of the UART port.

### **Description:**

This function gets the type of parity used for transmitting data and expected when receiving

#### Returns:

Returns the current parity settings, specified as one of **UART\_CONFIG\_PAR\_NONE**, **UART\_CONFIG\_PAR\_EVEN**, **UART\_CONFIG\_PAR\_ODD**, **UART\_CONFIG\_PAR\_ONE**, or **UART\_CONFIG\_PAR\_ZERO**.

# 22.2.1.31 ROM\_UARTParityModeSet

Sets the type of parity.

### Prototype:

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTParityModeSet is a function pointer located at ROM_UARTTABLE[1].
```

### Parameters:

```
ui32Base is the base address of the UART port.
ui32Parity specifies the type of parity to use.
```

### **Description:**

Sets the type of parity to use for transmitting and expect when receiving. The *ui32Parity* parameter must be one of **UART\_CONFIG\_PAR\_NONE**, **UART\_CONFIG\_PAR\_EVEN**, **UART\_CONFIG\_PAR\_ODD**, **UART\_CONFIG\_PAR\_ONE**, or **UART\_CONFIG\_PAR\_ZERO**. The last two allow direct control of the parity bit; it is always either one or zero based on the mode.

#### Returns:

None.

# 22.2.1.32 ROM UARTRxErrorClear

Clears all reported receiver errors.

### Prototype:

```
void
ROM UARTRxErrorClear(uint32 t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTRXErrorClear is a function pointer located at ROM_UARTTABLE[30].
```

#### Parameters:

ui32Base is the base address of the UART port.

### **Description:**

This function is used to clear all receiver error conditions reported via ROM\_UARTRxErrorGet(). If using the overrun, framing error, parity error or break interrupts, this function must be called after clearing the interrupt to ensure that later errors of the same type trigger another interrupt.

#### Returns:

None.

# 22.2.1.33 ROM UARTRxErrorGet

Gets current receiver errors.

#### Prototype:

```
uint32_t
ROM_UARTRxErrorGet(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTRXErrorGet is a function pointer located at ROM_UARTTABLE[29].
```

### Parameters:

ui32Base is the base address of the UART port.

### **Description:**

This function returns the current state of each of the 4 receiver error sources. The returned errors are equivalent to the four error bits returned via the previous call to ROM\_UARTCharGet() or ROM\_UARTCharGetNonBlocking() with the exception that the overrun error is set immediately the overrun occurs rather than when a character is next read.

#### Returns:

Returns a logical OR combination of the receiver error flags, **UART\_RXERROR\_FRAMING**, **UART\_RXERROR\_PARITY**, **UART\_RXERROR\_BREAK** and **UART\_RXERROR\_OVERRUN**.

# 22.2.1.34 ROM UARTSpaceAvail

Determines if there is any space in the transmit FIFO.

### Prototype:

```
bool
ROM_UARTSpaceAvail(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTSpaceAvail is a function pointer located at ROM_UARTTABLE[12].
```

#### Parameters:

ui32Base is the base address of the UART port.

### **Description:**

This function returns a flag indicating whether or not there is space available in the transmit FIFO.

### Returns:

Returns **true** if there is space available in the transmit FIFO or **false** if there is no space available in the transmit FIFO.

# 22.2.1.35 ROM\_UARTTxIntModeGet

Returns the current operating mode for the UART transmit interrupt.

### Prototype:

```
uint32_t
ROM_UARTTxIntModeGet(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTTXIntModeGet is a function pointer located at ROM_UARTTABLE[28].
```

### Parameters:

ui32Base is the base address of the UART port.

#### **Description:**

This function returns the current operating mode for the UART transmit interrupt. The return value is **UART\_TXINT\_MODE\_EOT** if the transmit interrupt is currently set to be asserted once the transmitter is completely idle - the transmit FIFO is empty and all bits, including any stop bits, have cleared the transmitter. The return value is **UART\_TXINT\_MODE\_FIFO** if the interrupt is set to be asserted based upon the level of the transmit FIFO.

### Returns:

Returns UART TXINT MODE FIFO or UART TXINT MODE EOT.

# 22.2.1.36 ROM UARTTxIntModeSet

Sets the operating mode for the UART transmit interrupt.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].

ROM_UARTTXIntModeSet is a function pointer located at ROM_UARTTABLE[27].
```

#### Parameters:

*ui32Base* is the base address of the UART port.

ui32Mode is the operating mode for the transmit interrupt. It may be UART\_TXINT\_MODE\_EOT to trigger interrupts when the transmitter is idle or UART\_TXINT\_MODE\_FIFO to trigger based on the current transmit FIFO level.

### **Description:**

This function allows the mode of the UART transmit interrupt to be set. By default, the transmit interrupt is asserted when the FIFO level falls past a threshold set via a call to ROM\_UARTFIFOLevelSet(). Alternatively, if this function is called with *ui32Mode* set to **UART\_TXINT\_MODE\_EOT**, the transmit interrupt will only be asserted once the transmitter is completely idle - the transmit FIFO is empty and all bits, including any stop bits, have cleared the transmitter.

### Returns:

None.

# 22.2.1.37 ROM UpdateUART

Starts an update over the UART0 interface.

### Prototype:

```
void
ROM_UpdateUART(void)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_UARTTABLE is an array of pointers located at ROM_APITABLE[1].
ROM_UpdateUART is a function pointer located at ROM_UARTTABLE[21].
```

### Description:

Calling this function commences an update of the firmware via the UART0 interface. This function assumes that the UART0 interface has already been configured and is currently operational.

### Returns:

Never returns.

# 23 uDMA Controller

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# 23.1 Introduction

The microDMA (uDMA) API provides functions to configure the uDMA (Direct Memory Access) controller. The uDMA controller is designed to work with the ARM Cortex-M4 processor and provides an efficient and low-overhead means of transferring blocks of data in the system.

The uDMA controller has the following features:

- dedicated channels for supported peripherals
- one channel each for receive and transmit for devices with receive and transmit paths
- dedicated channel for software initiated data transfers
- channels can be independently configured and operated
- an arbitration scheme that is configurable per channel
- two levels of priority
- subordinate to Cortex-M4 processor bus usage
- data sizes of 8, 16, or 32 bits
- address increment of byte, half-word, word, or none
- maskable device requests
- optional software initiated transfers on any channel
- interrupt on transfer completion

The uDMA controller supports several different transfer modes, allowing for complex transfer schemes. The following transfer modes are provided:

- **Basic** mode performs a simple transfer when request is asserted by a device. This is appropriate to use with peripherals where the peripheral asserts the request line whenever data should be transferred. The transfer will stop if request is de-asserted, even if the transfer is not complete.
- Auto-request mode performs a simple transfer that is started by a request, but will always complete the entire transfer, even if request is de-asserted. This is appropriate to use with software initiated transfers.
- **Ping-Pong** mode is used to transfer data to or from two buffers, switching from one buffer to the other as each buffer fills. This mode is appropriate to use with peripherals as a way to ensure a continuous flow of data to or from the peripheral. However, it is more complex to set up and requires code to manage the ping-pong buffers in the interrupt handler.
- Memory scatter/gather mode is a complex mode that provides a way to set up a list of transfer "tasks" for the uDMA controller. Blocks of data can be transferred to and from arbitrary locations in memory.

■ Peripheral scatter/gather mode is similar to memory scatter/gather mode except that it is controlled by a peripheral request.

Detailed explanation of the various transfer modes is beyond the scope of this document. Please refer to the device data sheet for more information on the operation of the uDMA controller.

The naming convention for the microDMA controller is to use the Greek letter "mu" to represent "micro". For the purposes of this document, and in the software library function names, a lower case "u" will be used in place of "mu" when the controller is referred to as "uDMA".

The general order of function calls to set up and perform a uDMA transfer is the following:

- ROM\_uDMAEnable() is called once to enable the controller.
- ROM\_uDMAControlBaseSet() is called once to set the channel control table.
- ROM\_uDMAChannelAttributeEnable() is called once or infrequently to configure the behavior
  of the channel.
- ROM\_uDMAChannelControlSet() is used to set up characteristics of the data transfer. It only needs to be called once if the nature of the data transfer does not change.
- ROM\_uDMAChannelTransferSet() is used to set the buffer pointers and size for a transfer. It is called before each new transfer.
- ROM\_uDMAChannelEnable() enables a channel to perform data transfers.
- ROM\_uDMAChannelRequest() is used to initiate a software based transfer. This is normally not used for peripheral based transfers.

In order to use the uDMA controller, you must first enable it by calling ROM\_uDMAEnable(). You can later disable it, if no longer needed, by calling ROM\_uDMADisable().

Once the uDMA controller is enabled, you must tell it where to find the channel control structures in system memory. This is done by using the function ROM\_uDMAControlBaseSet() and passing a pointer to the base of the channel control structure. The control structure must be allocated by the application. One way to do this is to declare an array of data type int8\_t or uint8\_t. In order to support all channels and transfer modes, the control table array should be 1024 bytes, but it can be fewer depending on transfer modes used and number of channels actually used.

#### Note:

The control table must be aligned on a 1024 byte boundary.

The uDMA controller supports multiple channels. Each channel has a set of attribute flags to control certain uDMA features and channel behavior. The attribute flags are set with the function ROM\_uDMAChannelAttributeEnable() and cleared with ROM\_uDMAChannelAttributeDisable(). The setting of the channel attribute flags can be queried by using the function ROM\_uDMAChannelAttributeGet().

Next, the control parameters of the DMA transfer must be set. These parameters control the size and address increment of the data items to be transferred. The function ROM\_uDMAChannelControlSet() is used to set up these control parameters.

All of the functions mentioned so far are used only once or infrequently to set up the uDMA channel and transfer. In order to set the transfer addresses, transfer size, and transfer mode, use the function ROM\_uDMAChannelTransferSet(). This function must be called for each new transfer. Once everything is set up, then channel is enabled by calling ROM\_uDMAChannelEnable(), which must be done before each new transfer. The uDMA controller will automatically disable the channel at the completion of a transfer. A channel can be manually disabled by using ROM\_uDMAChannelDisable().

There are additional functions that can be used to query the status of a channel, either from an interrupt handler or in polling fashion. The function ROM\_uDMAChannelSizeGet() is used to find the amount of data remaining to transfer on a channel. This will be zero when a transfer is complete. The function ROM\_uDMAChannelModeGet() can be used to find the transfer mode of a uDMA channel. This is usually used to see if the mode indicates stopped which means that a transfer has completed on a channel that was previously running. The function ROM\_uDMAChannelIsEnabled() can be used to determine if a particular channel is enabled.

The uDMA interrupt handler is only for software initiated transfers or errors. uDMA interrupts for a peripheral occur on the peripheral's dedicated interrupt channel, and should be handled by the peripheral interrupt handler. It is not necessary to acknowledge or clear uDMA interrupt sources. They are cleared automatically when they are serviced.

The uDMA interrupt handler should use the function ROM\_uDMAErrorStatusGet() to test if a uDMA error occurred. If so, the interrupt must be cleared by calling ROM\_uDMAErrorStatusClear().

#### Note:

Many of the API functions take a channel parameter that includes the logical OR of one of the values **UDMA\_PRI\_SELECT** or **UDMA\_ALT\_SELECT** to choose the primary or alternate control structure. For Basic and Auto transfer modes, only the primary control structure is needed. The alternate control structure is only needed for complex transfer modes of Pingpong or Scatter/gather. Refer to the device data sheet for detailed information about transfer modes.

# 23.2 Functions

# **Functions**

- void ROM\_uDMAChannelAssign (uint32\_t ui32Mapping)
- void ROM uDMAChannelAttributeDisable (uint32 t ui32ChannelNum, uint32 t ui32Attr)
- void ROM uDMAChannelAttributeEnable (uint32 t ui32ChannelNum, uint32 t ui32Attr)
- uint32\_t ROM\_uDMAChannelAttributeGet (uint32\_t ui32ChannelNum)
- void ROM uDMAChannelControlSet (uint32 t ui32ChannelStructIndex, uint32 t ui32Control)
- void ROM uDMAChannelDisable (uint32 t ui32ChannelNum)
- void ROM uDMAChannelEnable (uint32 t ui32ChannelNum)
- bool ROM uDMAChannellsEnabled (uint32 t ui32ChannelNum)
- uint32\_t ROM\_uDMAChannelModeGet (uint32\_t ui32ChannelStructIndex)
- void ROM uDMAChannelRequest (uint32 t ui32ChannelNum)
- void ROM\_uDMAChannelScatterGatherSet (uint32\_t ui32ChannelNum, uint32\_t ui32TaskCount, void \*pvTaskList, uint32\_t ui32IsPeriphSG)
- void ROM\_uDMAChannelSelectDefault (uint32\_t ui32DefPeriphs)
- void ROM uDMAChannelSelectSecondary (uint32 t ui32SecPeriphs)
- uint32\_t ROM\_uDMAChannelSizeGet (uint32\_t ui32ChannelStructIndex)
- void ROM\_uDMAChannelTransferSet (uint32\_t ui32ChannelStructIndex, uint32\_t ui32Mode, void \*pvSrcAddr, void \*pvDstAddr, uint32\_t ui32TransferSize)
- void \* ROM\_uDMAControlAlternateBaseGet (void)
- void \* ROM uDMAControlBaseGet (void)
- void ROM uDMAControlBaseSet (void \*pControlTable)

- void ROM uDMADisable (void)
- void ROM\_uDMAEnable (void)
- void ROM uDMAErrorStatusClear (void)
- uint32 t ROM uDMAErrorStatusGet (void)
- void ROM uDMAIntClear (uint32 t ui32ChanMask)
- uint32 t ROM uDMAIntStatus (void)

# 23.2.1 Function Documentation

# 23.2.1.1 ROM uDMAChannelAssign

Assigns a peripheral mapping for a uDMA channel.

# Prototype:

void

ROM\_uDMAChannelAssign(uint32\_t ui32Mapping)

### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_UDMATABLE is an array of pointers located at ROM\_APITABLE[17].

ROM\_uDMAChannelAssign is a function pointer located at ROM\_UDMATABLE[23].

#### Parameters:

ui32Mapping is a macro specifying the peripheral assignment for a channel

### **Description:**

This function assigns a peripheral mapping to a uDMA channel. It is used to select which peripheral is used for a uDMA channel. The parameter *ui32Mapping* should be one of the macros named **UDMA\_CHn\_tttt** from the header file *udma.h*. For example, to assign uDMA channel 0 to the UART2 RX channel, the parameter should be the macro **UDMA\_CHO\_UART2RX**.

### Returns:

None.

### 23.2.1.2 ROM uDMAChannelAttributeDisable

Disables attributes of a uDMA channel.

#### Prototype:

void

### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_UDMATABLE is an array of pointers located at ROM\_APITABLE[17].

ROM\_uDMAChannelAttributeDisable is a function pointer located at ROM\_UDMATABLE[12].

### Parameters:

ui32ChannelNum is the channel to configure.

ui32Attr is a combination of attributes for the channel.

### **Description:**

This function is used to disable attributes of a uDMA channel.

The *ui32ChannelNum* parameter must be only one of the following values:

- **UDMA CHANNEL ADC0**
- UDMA CHANNEL ADC1
- UDMA\_CHANNEL\_ADC2
- UDMA CHANNEL ADC3
- UDMA\_SEC\_CHANNEL\_ADC10
- UDMA\_SEC\_CHANNEL\_ADC11
- UDMA\_SEC\_CHANNEL\_ADC12
- UDMA SEC CHANNEL ADC13
- UDMA\_CHANNEL\_SSIORX
- UDMA CHANNEL SSI0TX
- UDMA\_CHANNEL\_SSI1RX
- UDMA CHANNEL SSI1TX
- UDMA\_SEC\_CHANNEL\_SSI1RX
- UDMA SEC CHANNEL SSI1TX
- **UDMA CHANNEL TMR0A**
- **UDMA CHANNEL TMR0B**
- UDMA CHANNEL TMR1A
- UDMA\_CHANNEL\_TMR1B
- UDMA\_SEC\_CHANNEL\_TMR1A
- UDMA SEC CHANNEL TMR1B
- UDMA SEC CHANNEL TMR2A 4
- UDMA\_SEC\_CHANNEL\_TMR2B\_5
- UDMA SEC CHANNEL TMR2A 6
- UDMA SEC CHANNEL TMR2B 7
- UDMA\_SEC\_CHANNEL\_TMR2A\_14
- UDMA\_SEC\_CHANNEL\_TMR2B\_15
- UDMA SEC CHANNEL TMR3A
- UDMA SEC CHANNEL TMR3B
- UDMA CHANNEL UARTORX
- UDMA\_CHANNEL\_UART0TX
- UDMA\_CHANNEL\_UART1RX
- UDMA CHANNEL UART1TX
- **UDMA SEC CHANNEL UART1RX**
- UDMA SEC CHANNEL UART1TX
- UDMA SEC CHANNEL UART2RX 0
- UDMA SEC CHANNEL UART2TX 1
- UDMA\_SEC\_CHANNEL\_UART2RX\_12
- UDMA\_SEC\_CHANNEL\_UART2TX\_13
- UDMA\_CHANNEL\_USBEP1RX

- UDMA CHANNEL USBEP1TX
- **UDMA CHANNEL USBEP2RX**
- UDMA CHANNEL USBEP2TX
- **UDMA CHANNEL USBEP3RX**
- **UDMA CHANNEL USBEP3TX**
- **UDMA CHANNEL SW**
- UDMA\_SEC\_CHANNEL\_SW

The *ui32Attr* parameter is the logical OR of any of the following:

- UDMA\_ATTR\_USEBURST is used to restrict transfers to use only a burst mode.
- UDMA\_ATTR\_ALTSELECT is used to select the alternate control structure for this channel.
- UDMA\_ATTR\_HIGH\_PRIORITY is used to set this channel to high priority.
- UDMA\_ATTR\_REQMASK is used to mask the hardware request signal from the peripheral for this channel.

#### Returns:

None.

# 23.2.1.3 ROM uDMAChannelAttributeEnable

Enables attributes of a uDMA channel.

#### Prototype:

```
void
```

### **ROM Location:**

ROM\_APITABLE is an array of pointers located at  $0 \times 0100.0010$ . ROM\_UDMATABLE is an array of pointers located at ROM\_APITABLE[17]. ROM\_uDMAChannelAttributeEnable is a function pointer located at ROM\_UDMATABLE[11].

## Parameters:

ui32ChannelNum is the channel to configure.

ui32Attr is a combination of attributes for the channel.

### **Description:**

This function is used to enable attributes of a uDMA channel.

The *ui32ChannelNum* parameter must be only one of the following values:

- UDMA CHANNEL ADC0
- UDMA CHANNEL ADC1
- UDMA\_CHANNEL\_ADC2
- UDMA CHANNEL ADC3
- UDMA SEC CHANNEL ADC10
- UDMA SEC CHANNEL ADC11
- UDMA\_SEC\_CHANNEL\_ADC12

- UDMA SEC CHANNEL ADC13
- UDMA CHANNEL SSIORX
- UDMA CHANNEL SSI0TX
- **UDMA CHANNEL SSI1RX**
- **UDMA CHANNEL SSI1TX**
- UDMA SEC CHANNEL SSI1RX
- UDMA\_SEC\_CHANNEL\_SSI1TX
- UDMA\_CHANNEL\_TMR0A
- UDMA\_CHANNEL\_TMR0B
- UDMA\_CHANNEL\_TMR1A
- UDMA CHANNEL TMR1B
- UDMA SEC CHANNEL TMR1A
- UDMA\_SEC\_CHANNEL\_TMR1B
- UDMA\_SEC\_CHANNEL\_TMR2A\_4
- UDMA\_SEC\_CHANNEL\_TMR2B\_5
- UDMA\_SEC\_CHANNEL\_TMR2A\_6
- UDMA\_SEC\_CHANNEL\_TMR2B\_7
- UDMA\_SEC\_CHANNEL\_TMR2A\_14
- UDMA SEC CHANNEL TMR2B 15
- UDMA SEC CHANNEL TMR3A
- UDMA\_SEC\_CHANNEL\_TMR3B
- UDMA\_CHANNEL\_UARTORX
- **UDMA CHANNEL UARTOTX**
- UDMA\_CHANNEL\_UART1RX
- UDMA CHANNEL UART1TX
- UDMA\_SEC\_CHANNEL\_UART1RX
- UDMA SEC CHANNEL UART1TX
- UDMA\_SEC\_CHANNEL\_UART2RX\_0
- UDMA\_SEC\_CHANNEL\_UART2TX\_1
- UDMA SEC CHANNEL UART2RX 12
- UDMA\_SEC\_CHANNEL\_UART2TX\_13
- UDMA CHANNEL USBEP1RX
- UDMA CHANNEL USBEP1TX
- **UDMA CHANNEL USBEP2RX**
- UDMA\_CHANNEL\_USBEP2TX
- **UDMA CHANNEL USBEP3RX**
- UDMA CHANNEL USBEP3TX
- UDMA CHANNEL SW
- UDMA\_SEC\_CHANNEL\_SW

The *ui32Attr* parameter is the logical OR of any of the following:

- UDMA\_ATTR\_USEBURST is used to restrict transfers to use only a burst mode.
- UDMA\_ATTR\_ALTSELECT is used to select the alternate control structure for this channel (it is very unlikely that this flag should be used).
- UDMA\_ATTR\_HIGH\_PRIORITY is used to set this channel to high priority.

■ UDMA\_ATTR\_REQMASK is used to mask the hardware request signal from the peripheral for this channel.

#### Returns:

None.

# 23.2.1.4 ROM uDMAChannelAttributeGet

Gets the enabled attributes of a uDMA channel.

# Prototype:

```
uint32_t
ROM_uDMAChannelAttributeGet(uint32_t ui32ChannelNum)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UDMATABLE is an array of pointers located at ROM_APITABLE[17].

ROM_uDMAChannelAttributeGet is a function pointer located at ROM_UDMATABLE[13].
```

#### Parameters:

ui32ChannelNum is the channel to configure.

### **Description:**

This function returns a combination of flags representing the attributes of the uDMA channel.

The *ui32ChannelNum* parameter must be only one of the following values:

- UDMA\_CHANNEL\_ADC0
- UDMA CHANNEL ADC1
- UDMA\_CHANNEL\_ADC2
- UDMA\_CHANNEL\_ADC3
- UDMA\_SEC\_CHANNEL\_ADC10
- UDMA SEC CHANNEL ADC11
- UDMA SEC CHANNEL ADC12
- UDMA\_SEC\_CHANNEL\_ADC13
- UDMA CHANNEL SSIORX
- UDMA\_CHANNEL\_SSI0TX
- UDMA\_CHANNEL\_SSI1RX
- UDMA\_CHANNEL\_SSI1TX
- UDMA SEC CHANNEL SSI1RX
- UDMA\_SEC\_CHANNEL\_SSI1TX
- UDMA\_CHANNEL\_TMR0A
- UDMA\_CHANNEL\_TMR0B
- UDMA CHANNEL TMR1A
- UDMA\_CHANNEL\_TMR1B
- UDMA SEC CHANNEL TMR1A
- UDMA\_SEC\_CHANNEL\_TMR1B
- UDMA\_SEC\_CHANNEL\_TMR2A\_4
- UDMA SEC CHANNEL TMR2B 5

- UDMA SEC CHANNEL TMR2A 6
- UDMA\_SEC\_CHANNEL\_TMR2B\_7
- UDMA SEC CHANNEL TMR2A 14
- UDMA SEC CHANNEL TMR2B 15
- UDMA SEC CHANNEL TMR3A
- UDMA\_SEC\_CHANNEL\_TMR3B
- **UDMA CHANNEL UARTORX**
- UDMA\_CHANNEL\_UART0TX
- UDMA CHANNEL UART1RX
- UDMA CHANNEL UART1TX
- UDMA SEC CHANNEL UART1RX
- **UDMA SEC CHANNEL UART1TX**
- UDMA\_SEC\_CHANNEL\_UART2RX\_0
- UDMA SEC CHANNEL UART2TX 1
- UDMA SEC CHANNEL UART2RX 12
- UDMA SEC CHANNEL UART2TX 13
- UDMA CHANNEL USBEP1RX
- **UDMA CHANNEL USBEP1TX**
- UDMA CHANNEL USBEP2RX
- **UDMA CHANNEL USBEP2TX**
- **UDMA CHANNEL USBEP3RX**
- UDMA CHANNEL USBEP3TX
- **UDMA CHANNEL SW**
- **UDMA SEC CHANNEL SW**

#### Returns:

Returns the logical OR of the attributes of the uDMA channel, which can be any of the following:

- UDMA\_ATTR\_USEBURST is used to restrict transfers to use only a burst mode.
- UDMA\_ATTR\_ALTSELECT is used to select the alternate control structure for this channel.
- UDMA\_ATTR\_HIGH\_PRIORITY is used to set this channel to high priority.
- UDMA\_ATTR\_REQMASK is used to mask the hardware request signal from the peripheral for this channel.

### 23.2.1.5 ROM uDMAChannelControlSet

Sets the control parameters for a uDMA channel control structure.

### Prototype:

```
void
```

#### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_UDMATABLE is an array of pointers located at ROM\_APITABLE[17].

ROM\_uDMAChannelControlSet is a function pointer located at ROM\_UDMATABLE[14].

#### Parameters:

ui32ChannelStructIndex is the logical OR of the uDMA channel number with UDMA\_PRI\_SELECT or UDMA\_ALT\_SELECT.

ui32Control is logical OR of several control values to set the control parameters for the channel.

## **Description:**

This function is used to set control parameters for a uDMA transfer. These are typically parameters that are not changed often.

The *ui32ChannelStructIndex* parameter should be the logical OR of the channel number with one of **UDMA\_PRI\_SELECT** or **UDMA\_ALT\_SELECT** to choose whether the primary or alternate data structure is used.

The *ui32Control* parameter is the logical OR of five values: the data size, the source address increment, the destination address increment, the arbitration size, and the use burst flag. The choices available for each of these values is described below.

Choose the data size from one of **UDMA\_SIZE\_8**, **UDMA\_SIZE\_16**, or **UDMA\_SIZE\_32** to select a data size of 8, 16, or 32 bits.

Choose the source address increment from one of **UDMA\_SRC\_INC\_8**, **UDMA\_SRC\_INC\_16**, **UDMA\_SRC\_INC\_32**, or **UDMA\_SRC\_INC\_NONE** to select an address increment of 8-bit bytes, 16-bit halfwords, 32-bit words, or to select non-incrementing.

Choose the destination address increment from one of **UDMA\_DST\_INC\_8**, **UDMA\_DST\_INC\_16**, **UDMA\_DST\_INC\_32**, or **UDMA\_DST\_INC\_NONE** to select an address increment of 8-bit bytes, 16-bit halfwords, 32-bit words, or to select non-incrementing.

The arbitration size determines how many items are transferred before the uDMA controller rearbitrates for the bus. Choose the arbitration size from one of **UDMA\_ARB\_1**, **UDMA\_ARB\_2**, **UDMA\_ARB\_4**, **UDMA\_ARB\_8**, through **UDMA\_ARB\_1024** to select the arbitration size from 1 to 1024 items, in powers of 2.

The value **UDMA\_NEXT\_USEBURST** is used to force the channel to only respond to burst requests at the tail end of a scatter-gather transfer.

### Note:

The address increment cannot be smaller than the data size.

### Returns:

None.

# 23.2.1.6 ROM uDMAChannelDisable

Disables a uDMA channel for operation.

#### Prototype:

void

ROM\_uDMAChannelDisable(uint32\_t ui32ChannelNum)

### **ROM Location:**

ROM\_APITABLE is an array of pointers located at  $0 \times 0100.0010$ . ROM\_UDMATABLE is an array of pointers located at ROM\_APITABLE[17]. ROM\_uDMAChannelDisable is a function pointer located at ROM\_UDMATABLE[6].

#### Parameters:

ui32ChannelNum is the channel number to disable.

### **Description:**

This function disables a specific uDMA channel. Once disabled, a channel will not respond to uDMA transfer requests until re-enabled via ROM\_uDMAChannelEnable().

The *ui32ChannelNum* parameter must be only one of the following values:

- UDMA CHANNEL ADC0
- UDMA CHANNEL ADC1
- UDMA CHANNEL ADC2
- UDMA\_CHANNEL\_ADC3
- UDMA SEC CHANNEL ADC10
- UDMA SEC CHANNEL ADC11
- UDMA\_SEC\_CHANNEL\_ADC12
- UDMA\_SEC\_CHANNEL\_ADC13
- **UDMA CHANNEL SSIORX**
- **UDMA CHANNEL SSI0TX**
- UDMA\_CHANNEL\_SSI1RX
- UDMA\_CHANNEL\_SSI1TX
- UDMA\_SEC\_CHANNEL\_SSI1RX
- UDMA SEC CHANNEL SSI1TX
- UDMA CHANNEL TMR0A
- UDMA CHANNEL TMR0B
- UDMA CHANNEL TMR1A
- UDMA CHANNEL TMR1B
- UDMA\_SEC\_CHANNEL\_TMR1A
- UDMA SEC CHANNEL TMR1B
- UDMA\_SEC\_CHANNEL\_TMR2A\_4
- UDMA SEC CHANNEL TMR2B 5
- UDMA\_SEC\_CHANNEL\_TMR2A\_6
- UDMA SEC CHANNEL TMR2B 7
- UDMA\_SEC\_CHANNEL\_TMR2A\_14
- UDMA\_SEC\_CHANNEL\_TMR2B\_15
- UDMA\_SEC\_CHANNEL\_TMR3A
- UDMA\_SEC\_CHANNEL\_TMR3B
- **UDMA CHANNEL UARTORX**
- UDMA\_CHANNEL\_UART0TX
- UDMA\_CHANNEL\_UART1RX
- UDMA CHANNEL UART1TX
- UDMA\_SEC\_CHANNEL\_UART1RX
- UDMA SEC CHANNEL UART1TX
- UDMA SEC CHANNEL UART2RX 0
- UDMA SEC CHANNEL UART2TX 1
- UDMA SEC CHANNEL UART2RX 12
- UDMA\_SEC\_CHANNEL\_UART2TX\_13
- UDMA\_CHANNEL\_USBEP1RX

- UDMA CHANNEL USBEP1TX
- **UDMA CHANNEL USBEP2RX**
- UDMA CHANNEL USBEP2TX
- **UDMA CHANNEL USBEP3RX**
- UDMA CHANNEL USBEP3TX
- UDMA CHANNEL SW
- UDMA\_SEC\_CHANNEL\_SW

#### Returns:

None.

# 23.2.1.7 ROM\_uDMAChannelEnable

Enables a uDMA channel for operation.

# Prototype:

void

ROM\_uDMAChannelEnable(uint32\_t ui32ChannelNum)

### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_UDMATABLE is an array of pointers located at ROM\_APITABLE[17].

ROM\_uDMAChannelEnable is a function pointer located at ROM\_UDMATABLE[5].

### Parameters:

ui32ChannelNum is the channel number to enable.

### **Description:**

This function enables a specific uDMA channel for use. This function must be used to enable a channel before it can be used to perform a uDMA transfer.

When a uDMA transfer is completed, the channel is automatically disabled by the uDMA controller. Therefore, this function should be called prior to starting up any new transfer.

The *ui32ChannelNum* parameter must be only one of the following values:

- UDMA CHANNEL ADC0
- **UDMA CHANNEL ADC1**
- UDMA\_CHANNEL\_ADC2
- UDMA\_CHANNEL\_ADC3
- UDMA\_SEC\_CHANNEL\_ADC10
- UDMA\_SEC\_CHANNEL\_ADC11
- UDMA\_SEC\_CHANNEL\_ADC12
- UDMA\_SEC\_CHANNEL\_ADC13
- UDMA\_CHANNEL\_SSIORX
- UDMA\_CHANNEL\_SSI0TX
- UDMA CHANNEL SSI1RX
- **UDMA CHANNEL SSI1TX**
- UDMA SEC CHANNEL SSI1RX
- UDMA\_SEC\_CHANNEL\_SSI1TX

- UDMA CHANNEL TMR0A
- UDMA CHANNEL TMR0B
- UDMA CHANNEL TMR1A
- UDMA CHANNEL TMR1B
- UDMA SEC CHANNEL TMR1A
- UDMA\_SEC\_CHANNEL\_TMR1B
- UDMA SEC CHANNEL TMR2A 4
- UDMA\_SEC\_CHANNEL\_TMR2B\_5
- UDMA SEC CHANNEL TMR2A 6
- UDMA SEC CHANNEL TMR2B 7
- UDMA SEC CHANNEL TMR2A 14
- UDMA SEC CHANNEL TMR2B 15
- UDMA\_SEC\_CHANNEL\_TMR3A
- UDMA SEC CHANNEL TMR3B
- UDMA\_CHANNEL\_UARTORX
- **UDMA CHANNEL UARTOTX**
- UDMA CHANNEL UART1RX
- UDMA\_CHANNEL\_UART1TX
- UDMA SEC CHANNEL UART1RX
- UDMA SEC CHANNEL UART1TX
- **UDMA SEC CHANNEL UART2RX 0**
- UDMA SEC CHANNEL UART2TX 1
- UDMA\_SEC\_CHANNEL\_UART2RX\_12
- UDMA\_SEC\_CHANNEL\_UART2TX\_13
- UDMA CHANNEL USBEP1RX
- **UDMA CHANNEL USBEP1TX**
- UDMA\_CHANNEL\_USBEP2RX
- **UDMA CHANNEL USBEP2TX**
- **UDMA CHANNEL USBEP3RX**
- **UDMA CHANNEL USBEP3TX**
- UDMA\_CHANNEL SW
- UDMA\_SEC\_CHANNEL\_SW

#### Returns:

None.

# 23.2.1.8 ROM\_uDMAChannellsEnabled

Checks if a uDMA channel is enabled for operation.

### Prototype:

boo l

ROM\_uDMAChannelIsEnabled(uint32\_t ui32ChannelNum)

#### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_UDMATABLE is an array of pointers located at ROM\_APITABLE[17].

ROM\_uDMAChannelIsEnabled is a function pointer located at ROM\_UDMATABLE[7].

### Parameters:

ui32ChannelNum is the channel number to check.

### **Description:**

This function checks to see if a specific uDMA channel is enabled. This can be used to check the status of a transfer, since the channel will be automatically disabled at the end of a transfer.

The *ui32ChannelNum* parameter must be only one of the following values:

- UDMA CHANNEL ADC0
- UDMA CHANNEL ADC1
- UDMA CHANNEL ADC2
- UDMA\_CHANNEL\_ADC3
- UDMA SEC CHANNEL ADC10
- UDMA SEC CHANNEL ADC11
- UDMA\_SEC\_CHANNEL\_ADC12
- UDMA\_SEC\_CHANNEL\_ADC13
- **UDMA CHANNEL SSIORX**
- **UDMA CHANNEL SSI0TX**
- UDMA\_CHANNEL\_SSI1RX
- UDMA\_CHANNEL\_SSI1TX
- UDMA\_SEC\_CHANNEL\_SSI1RX
- UDMA SEC CHANNEL SSI1TX
- UDMA CHANNEL TMR0A
- UDMA CHANNEL TMR0B
- UDMA CHANNEL TMR1A
- UDMA CHANNEL TMR1B
- UDMA\_SEC\_CHANNEL\_TMR1A
- UDMA SEC CHANNEL TMR1B
- UDMA\_SEC\_CHANNEL\_TMR2A\_4
- UDMA\_SEC\_CHANNEL\_TMR2B\_5
- UDMA\_SEC\_CHANNEL\_TMR2A\_6
- UDMA\_SEC\_CHANNEL\_TMR2B\_7
- UDMA\_SEC\_CHANNEL\_TMR2A\_14
- UDMA\_SEC\_CHANNEL\_TMR2B\_15
- UDMA\_SEC\_CHANNEL\_TMR3A
- UDMA\_SEC\_CHANNEL\_TMR3B
- UDMA\_CHANNEL\_UARTORX
- UDMA\_CHANNEL\_UART0TX
- UDMA\_CHANNEL\_UART1RX
- UDMA\_CHANNEL\_UART1TX
- UDMA\_SEC\_CHANNEL\_UART1RX
- UDMA\_SEC\_CHANNEL\_UART1TX
- UDMA\_SEC\_CHANNEL\_UART2RX\_0
- UDMA\_SEC\_CHANNEL\_UART2TX\_1
- UDMA\_SEC\_CHANNEL\_UART2RX\_12
- UDMA\_SEC\_CHANNEL\_UART2TX\_13
- UDMA\_CHANNEL\_USBEP1RX

- UDMA CHANNEL USBEP1TX
- UDMA CHANNEL USBEP2RX
- UDMA CHANNEL USBEP2TX
- **UDMA CHANNEL USBEP3RX**
- UDMA CHANNEL USBEP3TX
- **UDMA CHANNEL SW**
- **UDMA SEC CHANNEL SW**

#### Returns:

Returns true if the channel is enabled, false if disabled.

# 23.2.1.9 ROM uDMAChannelModeGet

Gets the transfer mode for a uDMA channel control structure.

### **Prototype:**

```
uint32_t
ROM_uDMAChannelModeGet(uint32_t ui32ChannelStructIndex)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UDMATABLE is an array of pointers located at ROM_APITABLE[17].

ROM_uDMAChannelModeGet is a function pointer located at ROM_UDMATABLE[16].
```

### Parameters:

ui32ChannelStructIndex is the logical OR of the uDMA channel number with either UDMA\_PRI\_SELECT or UDMA\_ALT\_SELECT.

#### **Description:**

This function is used to get the transfer mode for the uDMA channel. It can be used to query the status of a transfer on a channel. When the transfer is complete the mode is **UDMA MODE STOP**.

### Returns:

Returns the transfer mode of the specified channel and control structure, which is one of the following values: UDMA\_MODE\_STOP, UDMA\_MODE\_BASIC, UDMA\_MODE\_AUTO, UDMA\_MODE\_PINGPONG, UDMA\_MODE\_MEM\_SCATTER\_GATHER, or UDMA\_MODE\_PER\_SCATTER\_GATHER.

# 23.2.1.10 ROM\_uDMAChannelRequest

Requests a uDMA channel to start a transfer.

### Prototype:

void

ROM\_uDMAChannelRequest(uint32\_t ui32ChannelNum)

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UDMATABLE is an array of pointers located at ROM_APITABLE[17].

ROM_uDMAChannelRequest is a function pointer located at ROM_UDMATABLE[10].
```

### Parameters:

ui32ChannelNum is the channel number on which to request a uDMA transfer.

### **Description:**

This function allows software to request a uDMA channel to begin a transfer. This could be used for performing a memory to memory transfer, or if for some reason a transfer needs to be initiated by software instead of the peripheral associated with that channel.

The *ui32ChannelNum* parameter must be only one of the following values:

- UDMA CHANNEL ADC0
- UDMA CHANNEL ADC1
- UDMA\_CHANNEL\_ADC2
- **UDMA CHANNEL ADC3**
- UDMA SEC CHANNEL ADC10
- UDMA\_SEC\_CHANNEL\_ADC11
- UDMA\_SEC\_CHANNEL\_ADC12
- UDMA SEC CHANNEL ADC13
- **UDMA CHANNEL SSIORX**
- UDMA\_CHANNEL\_SSI0TX
- UDMA\_CHANNEL\_SSI1RX
- UDMA CHANNEL SSI1TX
- UDMA SEC CHANNEL SSI1RX
- UDMA SEC CHANNEL SSI1TX
- UDMA CHANNEL TMR0A
- UDMA\_CHANNEL\_TMR0B
- UDMA CHANNEL TMR1A
- UDMA\_CHANNEL\_TMR1B
- UDMA SEC CHANNEL TMR1A
- UDMA\_SEC\_CHANNEL\_TMR1B
- UDMA\_SEC\_CHANNEL\_TMR2A\_4
- UDMA\_SEC\_CHANNEL\_TMR2B\_5
- UDMA\_SEC\_CHANNEL\_TMR2A\_6
- UDMA\_SEC\_CHANNEL\_TMR2B\_7
- UDMA\_SEC\_CHANNEL\_TMR2A\_14
- UDMA\_SEC\_CHANNEL\_TMR2B\_15
- UDMA\_SEC\_CHANNEL\_TMR3A
- UDMA\_SEC\_CHANNEL\_TMR3B
- UDMA\_CHANNEL\_UARTORX
- UDMA\_CHANNEL\_UART0TX
- UDMA\_CHANNEL\_UART1RXUDMA\_CHANNEL\_UART1TX
- UDMA\_SEC\_CHANNEL\_UART1RX
- UDMA SEC CHANNEL UART1TX
- UDMA SEC CHANNEL UART2RX 0
- UDMA SEC CHANNEL UART2TX 1
- UDMA\_SEC\_CHANNEL\_UART2RX\_12
- UDMA\_SEC\_CHANNEL\_UART2TX\_13

- UDMA CHANNEL USBEP1RX
- UDMA CHANNEL USBEP1TX
- UDMA CHANNEL USBEP2RX
- **UDMA CHANNEL USBEP2TX**
- **UDMA CHANNEL USBEP3RX**
- UDMA CHANNEL USBEP3TX
- UDMA\_CHANNEL\_SW
- UDMA\_SEC\_CHANNEL\_SW

#### Note:

If the channel is **UDMA\_CHANNEL\_SW** and interrupts are used, then the completion is signaled on the uDMA dedicated interrupt. If a peripheral channel is used, then the completion is signaled on the peripheral's interrupt.

#### Returns:

None.

# 23.2.1.11 ROM uDMAChannelScatterGatherSet

Configures a uDMA channel for scatter-gather mode.

# Prototype:

uint32\_t ui32IsPeriphSG)

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_UDMATABLE is an array of pointers located at ROM_APITABLE[17].
ROM_uDMAChannelScatterGatherSet is a function pointer located at ROM_UDMATABLE[22].
```

#### Parameters:

ui32ChannelNum is the uDMA channel number.

ui32TaskCount is the number of scatter-gather tasks to execute.

pvTaskList is a pointer to the beginning of the scatter-gather task list.

**ui32IsPeriphSG** is a flag to indicate it is a peripheral scatter-gather transfer (else it is memory scatter-gather transfer).

### **Description:**

This function is used to configure a channel for scatter-gather mode. The caller must have already set up a task list, and pass a pointer to the start of the task list as the *pvTaskList* parameter. The *ui32TaskCount* parameter is the count of tasks in the task list, not the size of the task list. The flag *blsPeriphSG* should be used to indicate if the scatter-gather should be configured for a peripheral or memory scatter-gather operation.

#### Returns:

None.

# 23.2.1.12 ROM uDMAChannelSelectDefault

Selects the default peripheral for a set of uDMA channels.

### Prototype:

void

ROM uDMAChannelSelectDefault(uint32 t ui32DefPeriphs)

#### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_UDMATABLE is an array of pointers located at ROM\_APITABLE[17].

ROM\_uDMAChannelSelectDefault is a function pointer located at ROM\_UDMATABLE[18].

#### Parameters:

*ui32DefPeriphs* is the logical or of the uDMA channels for which to use the default peripheral, instead of the secondary peripheral.

### **Description:**

This function is used to select the default peripheral assignment for a set of uDMA channels.

The parameter *ui32DefPeriphs* can be the logical OR of any of the following macros. If one of the macros below is in the list passed to this function, then the default peripheral (marked as **DEF** ) is selected.

- UDMA DEF USBEP1RX SEC UART2RX
- UDMA DEF USBEP1TX SEC UART2TX
- UDMA DEF USBEP2RX SEC TMR3A
- UDMA\_DEF\_USBEP2TX\_SEC\_TMR3B
- UDMA DEF USBEP3RX SEC TMR2A
- UDMA DEF USBEP3TX SEC TMR2B
- **UDMA DEF UARTORX SEC UART1RX**
- UDMA DEF UARTOTX SEC UART1TX
- UDMA DEF SSIORX SEC SSI1RX
- UDMA\_DEF\_SSI0TX\_SEC\_SSI1TX
- UDMA DEF ADC00 SEC TMR2A
- UDMA\_DEF\_ADC01\_SEC\_TMR2B
- UDMA\_DEF\_ADC02\_SEC\_RESERVED
- UDMA DEF ADC03 SEC RESERVED
- UDMA DEF TMR0A SEC TMR1A
- UDMA DEF TMR0B SEC TMR1B
- UDMA\_DEF\_TMR1A\_SEC\_EPIORX
- UDMA DEF TMR1B SEC EPI0TX
- UDMA DEF UART1RX SEC RESERVED
- UDMA\_DEF\_UART1TX\_SEC\_RESERVED
- UDMA DEF SSI1RX SEC ADC10
- UDMA\_DEF\_SSI1TX\_SEC\_ADC11

### Returns:

None.

# 23.2.1.13 ROM uDMAChannelSelectSecondary

Selects the secondary peripheral for a set of uDMA channels.

### Prototype:

void

ROM\_uDMAChannelSelectSecondary(uint32\_t ui32SecPeriphs)

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.

ROM_UDMATABLE is an array of pointers located at ROM_APITABLE[17].

ROM_uDMAChannelSelectSecondary is a function pointer located at ROM_UDMATABLE[17].
```

#### Parameters:

ui32SecPeriphs is the logical or of the uDMA channels for which to use the secondary peripheral, instead of the default peripheral.

### **Description:**

This function is used to select the secondary peripheral assignment for a set of uDMA channels. By selecting the secondary peripheral assignment for a channel, the default peripheral assignment is no longer available for that channel.

The parameter *ui32SecPeriphs* can be the logical OR of any of the following macros. If one of the macros below is in the list passed to this function, then the secondary peripheral (marked as **\_SEC\_**) is selected.

- UDMA\_DEF\_USBEP1RX\_SEC\_UART2RX
- UDMA DEF USBEP1TX SEC UART2TX
- UDMA DEF USBEP2RX SEC TMR3A
- UDMA DEF USBEP2TX SEC TMR3B
- UDMA DEF USBEP3RX SEC TMR2A
- UDMA\_DEF\_USBEP3TX\_SEC\_TMR2B
- UDMA\_DEF\_ETH0RX\_SEC\_TMR2A
- UDMA DEF ETH0TX SEC TMR2B
- **UDMA DEF UARTORX SEC UART1RX**
- UDMA DEF UARTOTX SEC UART1TX
- UDMA DEF SSIORX SEC SSI1RX
- UDMA DEF SSI0TX SEC SSI1TX
- **UDMA DEF RESERVED SEC UART2RX**
- UDMA DEF RESERVED SEC UART2TX
- UDMA DEF ADC00 SEC TMR2A
- UDMA\_DEF\_ADC01\_SEC\_TMR2B
- UDMA DEF TMR0A SEC TMR1A
- UDMA DEF TMR0B SEC TMR1B
- UDMA\_DEF\_SSI1RX\_SEC\_ADC10
- UDMA\_DEF\_SSI1TX\_SEC\_ADC11
- UDMA DEF RESERVED SEC ADC12
- UDMA DEF RESERVED SEC ADC13

#### Returns:

None.

# 23.2.1.14 ROM uDMAChannelSizeGet

Gets the current transfer size for a uDMA channel control structure.

### Prototype:

```
uint32_t
ROM_uDMAChannelSizeGet(uint32_t ui32ChannelStructIndex)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UDMATABLE is an array of pointers located at ROM_APITABLE[17].

ROM_uDMAChannelSizeGet is a function pointer located at ROM_UDMATABLE[15].
```

#### Parameters:

ui32ChannelStructIndex is the logical OR of the uDMA channel number with either UDMA PRI SELECT or UDMA ALT SELECT.

### **Description:**

This function is used to get the uDMA transfer size for a channel. The transfer size is the number of items to transfer, where the size of an item might be 8, 16, or 32 bits. If a partial transfer has already occurred, then the number of remaining items is returned. If the transfer is complete, then 0 is returned.

### Returns:

Returns the number of items remaining to transfer.

# 23.2.1.15 ROM uDMAChannelTransferSet

Sets the transfer parameters for a uDMA channel control structure.

#### Prototype:

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UDMATABLE is an array of pointers located at ROM_APITABLE[17].

ROM_uDMAChannelTransferSet is a function pointer located at ROM_UDMATABLE[0].
```

### Parameters:

ui32ChannelStructIndex is the logical OR of the uDMA channel number with either UDMA\_PRI\_SELECT or UDMA\_ALT\_SELECT.

ui32Mode is the type of uDMA transfer.

*pvSrcAddr* is the source address for the transfer.

**pvDstAddr** is the destination address for the transfer.

ui32TransferSize is the number of data items to transfer.

## **Description:**

This function is used to set the parameters for a uDMA transfer. These are typically parameters that are changed often. The function ROM\_uDMAChannelControlSet() MUST be called at least once for this channel prior to calling this function.

The *ui32ChannelStructIndex* parameter should be the logical OR of the channel number with one of **UDMA\_PRI\_SELECT** or **UDMA\_ALT\_SELECT** to choose whether the primary or alternate data structure is used.

The *ui32Mode* parameter should be one of the following values:

- **UDMA\_MODE\_STOP** stops the uDMA transfer. The controller sets the mode to this value at the end of a transfer.
- UDMA\_MODE\_BASIC to perform a basic transfer based on request.
- **UDMA\_MODE\_AUTO** to perform a transfer that will always complete once started even if request is removed.
- UDMA\_MODE\_PINGPONG to set up a transfer that switches between the primary and alternate control structures for the channel. This allows use of ping-pong buffering for uDMA transfers.
- UDMA\_MODE\_MEM\_SCATTER\_GATHER to set up a memory scatter-gather transfer.
- UDMA\_MODE\_PER\_SCATTER\_GATHER to set up a peripheral scatter-gather transfer.

The *pvSrcAddr* and *pvDstAddr* parameters are pointers to the first location of the data to be transferred. These addresses should be aligned according to the item size. The compiler will take care of this if the pointers are pointing to storage of the appropriate data type.

The ui32TransferSize parameter is the number of data items, not the number of bytes.

The two scatter/gather modes, memory and peripheral, are actually different depending on whether the primary or alternate control structure is selected. This function will look for the **UDMA\_PRI\_SELECT** and **UDMA\_ALT\_SELECT** flag along with the channel number and will set the scatter/gather mode as appropriate for the primary or alternate control structure.

The channel must also be enabled using ROM\_uDMAChannelEnable() after calling this function. The transfer will not begin until the channel has been set up and enabled. Note that the channel is automatically disabled after the transfer is completed, meaning that ROM uDMAChannelEnable() must be called again after setting up the next transfer.

### Note:

Great care must be taken to not modify a channel control structure that is in use or else the results are unpredictable, including the possibility of undesired data transfers to or from memory or peripherals. For BASIC and AUTO modes, it is safe to make changes when the channel is disabled, or the ROM\_uDMAChannelModeGet() returns UDMA\_MODE\_STOP. For PING-PONG or one of the SCATTER\_GATHER modes, it is safe to modify the primary or alternate control structure only when the other is being used. The ROM\_uDMAChannelModeGet() function will return UDMA\_MODE\_STOP when a channel control structure is inactive and safe to modify.

## Returns:

None.

## 23.2.1.16 ROM uDMAControlAlternateBaseGet

Gets the base address for the channel control table alternate structures.

## Prototype:

void \*

ROM\_uDMAControlAlternateBaseGet (void)

### **ROM Location:**

ROM\_APITABLE is an array of pointers located at  $0 \times 0100.0010$ . ROM\_UDMATABLE is an array of pointers located at ROM\_APITABLE[17]. ROM\_uDMAControlAlternateBaseGet is a function pointer located at ROM\_UDMATABLE[21].

#### **Description:**

This function gets the base address of the second half of the channel control table that holds the alternate control structures for each channel.

#### Returns:

Returns a pointer to the base address of the second half of the channel control table.

## 23.2.1.17 ROM uDMAControlBaseGet

Gets the base address for the channel control table.

## Prototype:

void \*
ROM uDMAControlBaseGet(void)

### **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_UDMATABLE is an array of pointers located at ROM\_APITABLE[17].

ROM\_uDMAControlBaseGet is a function pointer located at ROM\_UDMATABLE[9].

### **Description:**

This function gets the base address of the channel control table. This table resides in system memory and holds control information for each uDMA channel.

#### Returns:

Returns a pointer to the base address of the channel control table.

## 23.2.1.18 ROM uDMAControlBaseSet

Sets the base address for the channel control table.

#### Prototype:

void

ROM\_uDMAControlBaseSet(void \*pControlTable)

## **ROM Location:**

ROM\_APITABLE is an array of pointers located at  $0 \times 0100.0010$ .

ROM\_UDMATABLE is an array of pointers located at ROM\_APITABLE[17].

ROM\_uDMAControlBaseSet is a function pointer located at ROM\_UDMATABLE[8].

### Parameters:

**pControlTable** is a pointer to the 1024 byte aligned base address of the uDMA channel control table.

## **Description:**

This function sets the base address of the channel control table. This table resides in system memory and holds control information for each uDMA channel. The table must be aligned on a 1024 byte boundary. The base address must be set before any of the channel functions can be used.

The size of the channel control table depends on the number of uDMA channels, and which transfer modes are used. Refer to the introductory text and the microcontroller data sheet for more information about the channel control table.

#### Returns:

None.

## 23.2.1.19 ROM uDMADisable

Disables the uDMA controller for use.

## Prototype:

```
void
ROM uDMADisable(void)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UDMATABLE is an array of pointers located at ROM_APITABLE[17].

ROM_uDMADisable is a function pointer located at ROM_UDMATABLE[2].
```

## **Description:**

This function disables the uDMA controller. Once disabled, the uDMA controller will not operate until re-enabled with ROM\_uDMAEnable().

## Returns:

None.

## 23.2.1.20 ROM uDMAEnable

Enables the uDMA controller for use.

## Prototype:

```
void
ROM_uDMAEnable(void)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UDMATABLE is an array of pointers located at ROM_APITABLE[17].

ROM_uDMAEnable is a function pointer located at ROM_UDMATABLE[1].
```

### **Description:**

This function enables the uDMA controller. The uDMA controller must be enabled before it can be configured and used.

### Returns:

None.

## 23.2.1.21 ROM uDMAErrorStatusClear

Clears the uDMA error interrupt.

## Prototype:

void

ROM\_uDMAErrorStatusClear(void)

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UDMATABLE is an array of pointers located at ROM_APITABLE[17].

ROM_uDMAErrorStatusClear is a function pointer located at ROM_UDMATABLE[4].
```

## **Description:**

This function clears a pending uDMA error interrupt. It should be called from within the uDMA error interrupt handler to clear the interrupt.

#### Returns:

None.

## 23.2.1.22 ROM uDMAErrorStatusGet

Gets the uDMA error status.

## Prototype:

```
uint32_t
ROM_uDMAErrorStatusGet(void)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UDMATABLE is an array of pointers located at ROM_APITABLE[17].

ROM_uDMAErrorStatusGet is a function pointer located at ROM_UDMATABLE[3].
```

## **Description:**

This function returns the uDMA error status. It should be called from within the uDMA error interrupt handler to determine if a uDMA error occurred.

#### Returns:

Returns non-zero if a uDMA error is pending.

## 23.2.1.23 ROM uDMAIntClear

Clears uDMA interrupt status.

## Prototype:

```
void
```

ROM\_uDMAIntClear(uint32\_t ui32ChanMask)

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UDMATABLE is an array of pointers located at ROM_APITABLE[17].

ROM_uDMAIntClear is a function pointer located at ROM_UDMATABLE[20].
```

### Parameters:

ui32ChanMask is a 32-bit mask with one bit for each uDMA channel.

### **Description:**

Clears bits in the uDMA interrupt status register according to which bits are set in *ui32ChanMask*. There is one bit for each channel. If a a bit is set in *ui32ChanMask*, then that corresponding channel's interrupt status is cleared (if it was set).

#### Returns:

None.

## 23.2.1.24 ROM uDMAIntStatus

Gets the uDMA controller channel interrupt status.

## Prototype:

```
uint32_t
ROM uDMAIntStatus(void)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_UDMATABLE is an array of pointers located at ROM_APITABLE[17].

ROM_uDMAIntStatus is a function pointer located at ROM_UDMATABLE[19].
```

### **Description:**

This function is used to get the interrupt status of the uDMA controller. The returned value is a 32-bit bit mask that indicates which channels are requesting an interrupt. This function can be used from within an interrupt handler to determine or confirm which uDMA channel has requested an interrupt.

## Returns:

Returns a 32-bit mask which indicates requesting uDMA channels. There is a bit for each channel, and a 1 in a bit indicates that channel is requesting an interrupt. Multiple bits can be set.

# 24 USB Controller

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# 24.1 Introduction

The USB APIs provide a set of functions that are used to access the USB device or host controllers. The APIs are split into groups according to the functionality provided by the USB controller present in the microcontroller. Because of this, the driver has to handle microcontrollers that have only a USB device interface, a host and/or device interface, or microcontrollers that have an OTG interface, The groups are the following: USBDev, USBHost, USBOTG, USBEndpoint, and USBFIFO. The APIs in the USBDev group are only used with microcontrollers that have a USB device controller. The APIs in the USBHost group can only be used with microcontrollers that have a USB host controller. The USBOTG APIs are used by microcontrollers with an OTG interface. With USB OTG controllers, once the mode of the USB controller is configured, the device or host APIs should be used. The remainder of the APIs are used for both USB host and USB device controllers. The USBEndpoint APIs are used to configure and access the endpoints while the USBFIFO APIs are used to configure the size and location of the FIFOs.

The USB APIs abstract the IN/OUT nature of endpoints based on the type of USB controller that is in use. Any API that uses the IN/OUT terminology will comply with the standard USB interpretation of these terms. For example, an OUT endpoint on a microcontroller that has only a device interface will actually receive data on this endpoint, while a microcontroller that has a host interface will actually transmit data on an OUT endpoint.

Another important fact to understand is that all endpoints in the USB controller, whether host or device, have two "sides" to them. This allows each endpoint to both transmit and receive data. An application can use a single endpoint for both and IN and OUT transactions. For example: In device mode, endpoint 1 could be configured to have BULK IN and BULK OUT handled by endpoint 1. It is important to note that the endpoint number used is the endpoint number reported to the host. For microcontrollers with host controllers, the application can use an endpoint communicate with both IN and OUT endpoints of different types as well. For example: Endpoint 2 could be used to communicate with one device's interrupt IN endpoint and another device's bulk OUT endpoint at the same time. This effectively gives the application one dedicated control endpoint for IN or OUT control transactions on endpoint 0, and three IN endpoints and three OUT endpoints.

The USB controller has a configurable FIFOs in devices that have a USB device controller as well as those that have a host controller. The overall size of the FIFO RAM is 4096 bytes. It is important to note that the first 64 bytes of this memory are dedicated to endpoint 0 for control transactions. The remaining 4032 bytes are configurable however the application desires. The FIFO configuration is usually set at the beginning of the application and not modified once the USB controller is in use. The FIFO configuration uses the ROM\_USBFIFOConfigSet() API to set the starting address and the size of the FIFOs that are dedicated to each endpoint.

Example: FIFO Configuration

```
//
// 0-64 - endpoint 0 IN/OUT (64 bytes).
```

```
// 64-576
             - endpoint 1 IN
                                  (512 bytes).
// 576-1088
              - endpoint 1 OUT
                                  (512 bytes).
//
// 1088-1600
             - endpoint 2 IN
                                  (512 bytes).
// FIFO for endpoint 1 IN starts at address 64 and is 512 bytes in size.
ROM_USBFIFOConfigSet(USB0_BASE, USB_EP_1, 64, USB_FIFO_SZ_512,
                    USB_EP_DEV_IN);
// FIFO for endpoint 1 OUT starts at address 576 and is 512 bytes in size.
ROM_USBFIFOConfigSet(USB0_BASE, USB_EP_1, 576, USB_FIFO_SZ_512,
                    USB_EP_DEV_OUT);
// FIFO for endpoint 2 IN starts at address 1088 and is 512 bytes in size.
ROM_USBFIFOConfigSet(USB0_BASE, USB_EP_2, 1088, USB_FIF0_SZ_512,
                    USB_EP_DEV_IN);
```

# 24.2 Using USB with the uDMA Controller

The USB controller can be used with the uDMA for either sending or receiving data with both host and device controllers. The uDMA controller cannot be used to access endpoint 0, however all other endpoints are capable of using the uDMA controller. The uDMA channel numbers for USB are defined by the following values:

- UDMA CHANNEL USBEP1RX
- UDMA\_CHANNEL\_USBEP1TX
- UDMA CHANNEL USBEP2RX
- **UDMA CHANNEL USBEP2TX**
- UDMA\_CHANNEL\_USBEP3RX
- UDMA\_CHANNEL\_USBEP3TX

Since the uDMA controller views transfers as either transmit or receive, and the USB controller operates on IN/OUT transactions, some care must be taken to use the correct uDMA channel with the correct endpoint. USB host IN and USB device OUT endpoints both use receive uDMA channels while USB host OUT and USB device IN endpoints will use transmit uDMA channels.

When configuring the endpoint there are additional DMA settings needed. When calling ROM\_USBDevEndpointConfigSet() for an endpoint that will use uDMA, extra flags need to be added to the *ui32Flags* parameter. These flags are one of **USB\_EP\_DMA\_MODE\_0** or **USB\_EP\_DMA\_MODE\_1** to control the mode of the DMA transaction, and likely **USB\_EP\_AUTO\_SET** to allow the data to be transmitted automatically once a packet is ready. **USB\_EP\_DMA\_MODE\_0** will generate an interrupt whenever there is more space available in the FIFO. This allows the application code to perform operations between each packet. **USB\_EP\_DMA\_MODE\_1** will only interrupt when the DMA transfer complete or there is some type of error condition. This can be used for larger transmissions that require no interaction between packets. **USB\_EP\_AUTO\_SET** should normally be specified when using uDMA to prevent the need for application code to start the actual transfer of data.

Example: Endpoint configuration for a device IN endpoint:

The application must provide the configuration of the actual uDMA controller. First, to clear out any previous settings, the application should call ROM\_uDMAChannelAttributeDisable(). Then the application should call ROM\_uDMAChannelAttributeEnable() for the uDMA channel that corresponds to the endpoint, and specify the **UDMA ATTR USEBURST** flag.

#### Note:

All uDMA transfers used by the USB controller must enable burst mode.

The application needs to indicate the size of each uDMA transactions, combined with the source and destination increments and the arbitration level for the uDMA controller.

Example: Configure endpoint 1 transmit channel.

The next step is to actually start the uDMA transfer once the data is ready to be sent. There are the only two calls that the application needs to call to start a new transfer. Normally all of the previous uDMA configuration can stay the same. The first call, ROM\_uDMAChannelTransferSet(), resets the source and destination addresses for the DMA transfer and specifies how much data will be sent. The next call, ROM\_uDMAChannelEnable() actually allows the uDMA controller to begin requesting data.

Example: Start the transfer of data on endpoint 1.

Because the uDMA interrupt occurs on the same interrupt vector as any other USB interrupt, the application must perform an extra check to determine what was the actual source of the interrupt. It is important to note that this DMA interrupt does not mean that the USB transfer is complete, but that the data has been transferred to the USB controller's FIFO. There will also be an interrupt indicating that the USB transfer is complete. However, both events need to be handled in the same interrupt routine. This because if other code in the system holds off the USB interrupt routine, both the uDMA complete and transfer complete can occur before the USB interrupt handler is called. The USB has no status bit indicating that the interrupt was due to a DMA complete, which means that the application must remember if a uDMA transaction was in progress. The example below shows the g\_ui32Flags global variable being used to remember that a uDMA transfer was pending.

Example: Interrupt handling with uDMA.

To use the USB device controller with an OUT endpoint, the application must use a receive uDMA channel. When calling ROM\_USBDevEndpointConfigSet() for an endpoint that uses uDMA, the application must set extra flags in the *ui32Flags* parameter. The USB\_EP\_DMA\_MODE\_0 and USB\_EP\_DMA\_MODE\_1 control the mode of the transaction, USB\_EP\_AUTO\_CLEAR allows the data to be received automatically without needing to manually acknowledge that the data has been read. USB\_EP\_DMA\_MODE\_0 will not generate an interrupt when each packet is sent over USB and will only interrupt when the uDMA transfer is complete. USB\_EP\_DMA\_MODE\_1 will interrupt when the uDMA transfer complete or a short packet is received. This is useful for BULK endpoints that may not have prior knowledge of how much data is being received. USB\_EP\_AUTO\_CLEAR should normally be specified when using uDMA to prevent the need for application code to acknowledge that the data has been read from the FIFO. The example below configures endpoint 1 as a Device mode Bulk OUT endpoint using DMA mode 1 with a max packet size of 64 bytes.

Example: Configure endpoint 1 receive channel:

Next the configuration of the actual uDMA controller is needed. Like the transmit case, the first a call to ROM\_uDMAChannelAttributeDisable() is made to clear any previous settings. This is followed

by a call to ROM\_uDMAChannelAttributeEnable() with the DMA\_ATTR\_USEBURST value.

#### Note:

All uDMA transfers used by the USB controller must use burst mode.

The final call sets the read access size to 8 bits wide, the source address increment to 0, the destination address increment to 8 bits and the uDMA arbitration size to 64 bytes.

Example: Configure endpoint 1 transmit channel.

The next step is to actually start the uDMA transfer. Unlike the transfer side, if the application is ready, this can be set up right away to wait for incoming data. Like the transmit case, these are the only calls needed to start a new transfer, normally all of the previous uDMA configuration can remain the same.

Example: Start requesting of data on endpoint 1.

The uDMA interrupt occurs on the same interrupt vector as any other USB interrupt, this means that the application needs to check to see what was the actual source of the interrupt. It is possible that the USB interrupt does not indicate that the USB transfer was complete. The interrupt could also have been caused by a short packet, error, or even a transmit complete. This requires that the application check both receive cases to determine if this is related to receiving data on the endpoint. Because the USB has no status bit indicating that the interrupt was due to a uDMA complete, the application must remember if a uDMA transaction was in progress.

Example: Interrupt handling with uDMA.

```
//
// Get the current interrupt status.
//
ui32Status = ROM_USBIntStatusEndpoint(USB0_BASE);
if(ui32Status & USB_INT_DEV_OUT_EP1)
{
    //
```

# 24.3 Functions

## **Functions**

- void ROM\_UpdateUSB (uint8\_t \*pui8USBBootROMInfo)
- uint32 t ROM USBDevAddrGet (uint32 t ui32Base)
- void ROM\_USBDevAddrSet (uint32\_t ui32Base, uint32\_t ui32Address)
- void ROM USBDevConnect (uint32 t ui32Base)
- void ROM USBDevDisconnect (uint32 t ui32Base)
- void ROM\_USBDevEndpointConfigGet (uint32\_t ui32Base, uint32\_t ui32Endpoint, uint32\_t \*pui32MaxPacketSize, uint32\_t \*pui32Flags)
- void ROM\_USBDevEndpointConfigSet (uint32\_t ui32Base, uint32\_t ui32Endpoint, uint32\_t ui32MaxPacketSize, uint32\_t ui32Flags)
- void ROM\_USBDevEndpointDataAck (uint32\_t ui32Base, uint32\_t ui32Endpoint, bool blsLast-Packet)
- void ROM\_USBDevEndpointStall (uint32\_t ui32Base, uint32\_t ui32Endpoint, uint32\_t ui32Flags)
- void ROM\_USBDevEndpointStallClear (uint32\_t ui32Base, uint32\_t ui32Endpoint, uint32\_t ui32Flags)
- void ROM\_USBDevEndpointStatusClear (uint32\_t ui32Base, uint32\_t ui32Endpoint, uint32\_t ui32Flags)
- void ROM\_USBDevMode (uint32\_t ui32Base)
- uint32 t ROM USBEndpointDataAvail (uint32 t ui32Base, uint32 t ui32Endpoint)
- int32\_t ROM\_USBEndpointDataGet (uint32\_t ui32Base, uint32\_t ui32Endpoint, uint8\_t \*pui8Data, uint32\_t \*pui32Size)
- int32\_t ROM\_USBEndpointDataPut (uint32\_t ui32Base, uint32\_t ui32Endpoint, uint8\_t \*pui8Data, uint32\_t ui32Size)
- int32\_t ROM\_USBEndpointDataSend (uint32\_t ui32Base, uint32\_t ui32Endpoint, uint32\_t ui32TransType)
- void ROM\_USBEndpointDataToggleClear (uint32\_t ui32Base, uint32\_t ui32Endpoint, uint32\_t ui32Flags)
- void ROM\_USBEndpointDMAChannel (uint32\_t ui32Base, uint32\_t ui32Endpoint, uint32\_t ui32Channel)

- void ROM\_USBEndpointDMADisable (uint32\_t ui32Base, uint32\_t ui32Endpoint, uint32\_t ui32Flags)
- void ROM\_USBEndpointDMAEnable (uint32\_t ui32Base, uint32\_t ui32Endpoint, uint32\_t ui32Flags)
- uint32\_t ROM\_USBEndpointStatus (uint32\_t ui32Base, uint32\_t ui32Endpoint)
- uint32 t ROM USBFIFOAddrGet (uint32 t ui32Base, uint32 t ui32Endpoint)
- void ROM\_USBFIFOConfigGet (uint32\_t ui32Base, uint32\_t ui32Endpoint, uint32\_t \*pui32FIFOAddress, uint32\_t \*pui32FIFOSize, uint32\_t ui32Flags)
- void ROM\_USBFIFOConfigSet (uint32\_t ui32Base, uint32\_t ui32FIFOAddress, uint32\_t ui32FIFOSize, uint32\_t ui32Flags)
- void ROM\_USBFIFOFlush (uint32\_t ui32Base, uint32\_t ui32Endpoint, uint32\_t ui32Flags)
- uint32\_t ROM\_USBFrameNumberGet (uint32\_t ui32Base)
- uint32\_t ROM\_USBHostAddrGet (uint32\_t ui32Base, uint32\_t ui32Endpoint, uint32\_t ui32Flags)
- void ROM\_USBHostAddrSet (uint32\_t ui32Base, uint32\_t ui32Endpoint, uint32\_t ui32Addr, uint32\_t ui32Flags)
- void ROM\_USBHostEndpointConfig (uint32\_t ui32Base, uint32\_t ui32Endpoint, uint32\_t ui32MaxPayload, uint32\_t ui32NAKPollInterval, uint32\_t ui32TargetEndpoint, uint32\_t ui32Flags)
- void ROM USBHostEndpointDataAck (uint32 t ui32Base, uint32 t ui32Endpoint)
- void ROM\_USBHostEndpointDataToggle (uint32\_t ui32Base, uint32\_t ui32Endpoint, bool bDataToggle, uint32\_t ui32Flags)
- void ROM\_USBHostEndpointStatusClear (uint32\_t ui32Base, uint32\_t ui32Endpoint, uint32\_t ui32Flags)
- uint32\_t ROM\_USBHostHubAddrGet (uint32\_t ui32Base, uint32\_t ui32Endpoint, uint32\_t ui32Flags)
- void ROM\_USBHostHubAddrSet (uint32\_t ui32Base, uint32\_t ui32Endpoint, uint32\_t ui32Addr, uint32 t ui32Flags)
- void ROM\_USBHostMode (uint32\_t ui32Base)
- void ROM USBHostPwrConfig (uint32 t ui32Base, uint32 t ui32Flags)
- void ROM USBHostPwrDisable (uint32 t ui32Base)
- void ROM\_USBHostPwrEnable (uint32\_t ui32Base)
- void ROM USBHostPwrFaultDisable (uint32 t ui32Base)
- void ROM USBHostPwrFaultEnable (uint32 t ui32Base)
- void ROM USBHostRequestIN (uint32 t ui32Base, uint32 t ui32Endpoint)
- void ROM USBHostRequestINClear (uint32 t ui32Base, uint32 t ui32Endpoint)
- void ROM USBHostRequestStatus (uint32 t ui32Base)
- void ROM USBHostReset (uint32 t ui32Base, bool bStart)
- void ROM\_USBHostResume (uint32\_t ui32Base, bool bStart)
- uint32 t ROM USBHostSpeedGet (uint32 t ui32Base)
- void ROM USBHostSuspend (uint32 t ui32Base)
- void ROM USBIntDisableControl (uint32 t ui32Base, uint32 t ui32Flags)
- void ROM USBIntDisableEndpoint (uint32 t ui32Base, uint32 t ui32Flags)
- void ROM USBIntEnableControl (uint32 t ui32Base, uint32 t ui32Flags)
- void ROM USBIntEnableEndpoint (uint32 t ui32Base, uint32 t ui32Flags)
- uint32 t ROM USBIntStatusControl (uint32 t ui32Base)
- uint32\_t ROM\_USBIntStatusEndpoint (uint32\_t ui32Base)

- uint32 t ROM USBModeGet (uint32 t ui32Base)
- uint32\_t ROM\_USBNumEndpointsGet (uint32\_t ui32Base)
- void ROM USBOTGMode (uint32 t ui32Base)
- void ROM USBPHYPowerOff (uint32 t ui32Base)
- void ROM\_USBPHYPowerOn (uint32\_t ui32Base)

## 24.3.1 Function Documentation

## 24.3.1.1 ROM UpdateUSB

Starts an update over the USB interface.

## Prototype:

```
void
ROM_UpdateUSB(uint8_t *pui8USBBootROMInfo)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_UpdateUSB is a function pointer located at ROM_USBTABLE[58].
```

#### Parameters:

pui8USBBootROMInfo is a pointer to an array containing the values that are used to customize the USB interface.

## Description:

Calling this function commences an update of the firmware via the USB interface. This function assumes that the USB interface has already been configured and the device is being clocked by the PLL. By using the *pui8USBBootROMInfo*, the vendor ID, proudct ID, bus- versus self-powered, maximum power, device version, and USB strings can be customized.

#### Returns:

Never returns.

## 24.3.1.2 ROM\_USBDevAddrGet

Returns the current device address in device mode.

### Prototype:

```
uint32_t
ROM_USBDevAddrGet(uint32_t ui32Base)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBDevAddrGet is a function pointer located at ROM_USBTABLE[1].
```

#### Parameters:

ui32Base specifies the USB module base address.

## **Description:**

This function will return the current device address. This address was set by a call to ROM USBDevAddrSet().

#### Note:

This function should only be called in device mode.

#### Returns:

The current device address.

## 24.3.1.3 ROM\_USBDevAddrSet

Sets the address in device mode.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBDevAddrSet is a function pointer located at ROM_USBTABLE[2].
```

## Parameters:

ui32Base specifies the USB module base address.ui32Address is the address to use for a device.

#### **Description:**

This function will set the device address on the USB bus. This address was likely received via a SET ADDRESS command from the host controller.

#### Note:

This function should only be called in device mode.

#### Returns:

None.

## 24.3.1.4 ROM USBDevConnect

Connects the USB controller to the bus in device mode.

## Prototype:

```
void
ROM_USBDevConnect(uint32_t ui32Base)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBDevConnect is a function pointer located at ROM_USBTABLE[3].
```

### Parameters:

ui32Base specifies the USB module base address.

## **Description:**

This function will cause the soft connect feature of the USB controller to be enabled. Call ROM\_USBDevDisconnect() to remove the USB device from the bus.

#### Note:

This function should only be called in device mode.

## Returns:

None.

## 24.3.1.5 ROM\_USBDevDisconnect

Removes the USB controller from the bus in device mode.

### Prototype:

```
void
ROM_USBDevDisconnect(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBDevDisconnect is a function pointer located at ROM_USBTABLE[4].
```

#### Parameters:

ui32Base specifies the USB module base address.

## **Description:**

This function will cause the soft connect feature of the USB controller to remove the device from the USB bus. A call to ROM USBDevConnect() is needed to reconnect to the bus.

#### Note:

This function should only be called in device mode.

#### Returns:

None.

## 24.3.1.6 ROM\_USBDevEndpointConfigGet

Gets the current configuration for an endpoint.

## **Prototype:**

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBDevEndpointConfigGet is a function pointer located at ROM_USBTABLE[41].
```

#### Parameters:

ui32Base specifies the USB module base address.

ui32Endpoint is the endpoint to access.

pui32MaxPacketSize is a pointer which is written with the maximum packet size for this end-point.

pui32Flags is a pointer which is written with the current endpoint settings. On entry to the function, this pointer must contain either USB\_EP\_DEV\_IN or USB\_EP\_DEV\_OUT to indicate whether the IN or OUT endpoint is to be queried.

## **Description:**

This function will return the basic configuration for an endpoint in device mode. The values returned in \*pui32MaxPacketSize and \*pui32Flags are equivalent to the ui32MaxPacketSize and ui32Flags previously passed to ROM\_USBDevEndpointConfigSet() for this endpoint.

#### Note:

This function should only be called in device mode.

#### Returns:

None.

# 24.3.1.7 ROM USBDevEndpointConfigSet

Sets the configuration for an endpoint.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBDevEndpointConfigSet is a function pointer located at ROM_USBTABLE[5].
```

## Parameters:

ui32Base specifies the USB module base address.

ui32Endpoint is the endpoint to access.

ui32MaxPacketSize is the maximum packet size for this endpoint.

*ui32Flags* are used to configure other endpoint settings.

#### **Description:**

This function will set the basic configuration for an endpoint in device mode. Endpoint zero does not have a dynamic configuration, so this function should not be called for endpoint zero. The *ui32Flags* parameter determines some of the configuration while the other parameters provide the rest.

The **USB EP MODE** flags define what the type is for the given endpoint.

- USB EP MODE CTRL is a control endpoint.
- USB EP MODE ISOC is an isochronous endpoint.
- USB\_EP\_MODE\_BULK is a bulk endpoint.
- USB\_EP\_MODE\_INT is an interrupt endpoint.

The **USB\_EP\_DMA\_MODE**\_ flags determines the type of DMA access to the endpoint data FIFOs. The choice of the DMA mode depends on how the DMA controller is configured and how it is being used. See the "Using USB with the uDMA Controller" section for more information on DMA configuration.

When configuring an IN endpoint, the **USB\_EP\_AUTO\_SET** bit can be specified to cause the automatic transmission of data on the USB bus as soon as *ui32MaxPacketSize* bytes of data are written into the FIFO for this endpoint. This is commonly used with DMA as no interaction is required to start the transmission of data.

When configuring an OUT endpoint, the **USB\_EP\_AUTO\_REQUEST** bit is specified to trigger the request for more data once the FIFO has been drained enough to receive *ui32MaxPacketSize* more bytes of data. Also for OUT endpoints, the **USB\_EP\_AUTO\_CLEAR** bit can be used to clear the data packet ready flag automatically once the data has been read from the FIFO. If this is not used, this flag must be manually cleared via a call to ROM\_USBDevEndpointStatusClear(). Both of these settings can be used to remove the need for extra calls when using the controller in DMA mode.

#### Note:

This function should only be called in device mode.

#### Returns:

None.

## 24.3.1.8 ROM USBDevEndpointDataAck

Acknowledge that data was read from the given endpoint's FIFO in device mode.

### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBDevEndpointDataAck is a function pointer located at ROM_USBTABLE[6].
```

### Parameters:

ui32Base specifies the USB module base address.ui32Endpoint is the endpoint to access.blsLastPacket indicates if this is the last packet.

## **Description:**

This function acknowledges that the data was read from the endpoint's FIFO. The *blsLast-Packet* parameter is set to a **true** value if this is the last in a series of data packets on endpoint

zero. The *blsLastPacket* parameter is not used for endpoints other than endpoint zero. This call can be used if processing is required between reading the data and acknowledging that the data has been read.

#### Note:

This function should only be called in device mode.

#### Returns:

None.

## 24.3.1.9 ROM USBDevEndpointStall

Stalls the specified endpoint in device mode.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBDevEndpointStall is a function pointer located at ROM_USBTABLE[7].
```

### Parameters:

```
ui32Base specifies the USB module base address.ui32Endpoint specifies the endpoint to stall.ui32Flags specifies whether to stall the IN or OUT endpoint.
```

#### **Description:**

This function will cause to endpoint number passed in to go into a stall condition. If the *ui32Flags* parameter is **USB\_EP\_DEV\_IN** then the stall is issued on the IN portion of this endpoint. If the *ui32Flags* parameter is **USB\_EP\_DEV\_OUT** then the stall is issued on the OUT portion of this endpoint.

#### Note:

This function should only be called in device mode.

#### Returns:

None.

## 24.3.1.10 ROM\_USBDevEndpointStallClear

Clears the stall condition on the specified endpoint in device mode.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBDevEndpointStallClear is a function pointer located at ROM_USBTABLE[8].
```

#### Parameters:

ui32Base specifies the USB module base address.

ui32Endpoint specifies which endpoint to remove the stall condition.

ui32Flags specifies whether to remove the stall condition from the IN or the OUT portion of this endpoint.

## **Description:**

This function will cause the endpoint number passed in to exit the stall condition. If the *ui32Flags* parameter is **USB\_EP\_DEV\_IN** then the stall is cleared on the IN portion of this endpoint. If the *ui32Flags* parameter is **USB\_EP\_DEV\_OUT** then the stall is cleared on the OUT portion of this endpoint.

## Note:

This function should only be called in device mode.

#### Returns:

None.

## 24.3.1.11 ROM USBDevEndpointStatusClear

Clears the status bits in this endpoint in device mode.

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBDevEndpointStatusClear is a function pointer located at ROM_USBTABLE[9].
```

#### Parameters:

```
ui32Base specifies the USB module base address.ui32Endpoint is the endpoint to access.
```

ui32Flags are the status bits that should be cleared.

### **Description:**

This function will clear the status of any bits that are passed in the *ui32Flags* parameter. The *ui32Flags* parameter can take the value returned from the ROM\_USBEndpointStatus() call.

#### Note:

This function should only be called in device mode.

## Returns:

None.

## 24.3.1.12 ROM USBDevMode

Change the mode of the USB controller to device.

## Prototype:

```
void
ROM_USBDevMode(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].
ROM_USBDevMode is a function pointer located at ROM_USBTABLE[55].
```

#### Parameters:

ui32Base specifies the USB module base address.

## **Description:**

This function changes the mode of the USB controller to device mode.

#### Returns:

None.

## 24.3.1.13 ROM USBEndpointDataAvail

Determine the number of bytes of data available in a given endpoint's FIFO.

## Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBEndpointDataAvail is a function pointer located at ROM_USBTABLE[44].
```

## Parameters:

ui32Base specifies the USB module base address.ui32Endpoint is the endpoint to access.

### Description:

This function will return the number of bytes of data currently available in the FIFO for the given receive (OUT) endpoint. It may be used prior to calling ROM\_USBEndpointDataGet() to determine the size of buffer required to hold the newly-received packet.

#### Returns:

This call will return the number of bytes available in a given endpoint FIFO.

## 24.3.1.14 ROM USBEndpointDataGet

Retrieves data from the given endpoint's FIFO.

## Prototype:

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBEndpointDataGet is a function pointer located at ROM_USBTABLE[10].
```

#### Parameters:

ui32Base specifies the USB module base address.

ui32Endpoint is the endpoint to access.

pui8Data is a pointer to the data area used to return the data from the FIFO.

**pui32Size** is initially the size of the buffer passed into this call via the *pui8Data* parameter. It is set to the amount of data returned in the buffer.

## **Description:**

This function will return the data from the FIFO for the given endpoint. The *pui32Size* parameter should indicate the size of the buffer passed in the *pui32Data* parameter. The data in the *pui32Size* parameter is changed to match the amount of data returned in the *pui8Data* parameter. If a zero byte packet was received this call will not return a error but will instead just return a zero in the *pui32Size* parameter. The only error case occurs when there is no data packet available.

#### Returns:

This call will return 0, or -1 if no packet was received.

## 24.3.1.15 ROM USBEndpointDataPut

Puts data into the given endpoint's FIFO.

## Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBEndpointDataPut is a function pointer located at ROM_USBTABLE[11].
```

## Parameters:

ui32Base specifies the USB module base address.

ui32Endpoint is the endpoint to access.

*pui8Data* is a pointer to the data area used as the source for the data to put into the FIFO. *ui32Size* is the amount of data to put into the FIFO.

## **Description:**

This function will put the data from the *pui8Data* parameter into the FIFO for this endpoint. If a packet is already pending for transmission then this call will not put any of the data into the FIFO and will return -1. Care should be taken to not write more data than can fit into the FIFO allocated by the call to ROM\_USBFIFOConfigSet().

#### Returns:

This call will return 0 on success, or -1 to indicate that the FIFO is in use and cannot be written.

## 24.3.1.16 ROM USBEndpointDataSend

Starts the transfer of data from an endpoint's FIFO.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBEndpointDataSend is a function pointer located at ROM_USBTABLE[12].
```

#### Parameters:

ui32Base specifies the USB module base address.ui32Endpoint is the endpoint to access.ui32TransType is set to indicate what type of data is being sent.

## **Description:**

This function will start the transfer of data from the FIFO for a given endpoint. This is necessary if the **USB\_EP\_AUTO\_SET** bit was not enabled for the endpoint. Setting the *ui32TransType* parameter will allow the appropriate signaling on the USB bus for the type of transaction being requested. The *ui32TransType* parameter should be one of the following:

- USB\_TRANS\_OUT for OUT transaction on any endpoint in host mode.
- USB\_TRANS\_IN for IN transaction on any endpoint in device mode.
- USB\_TRANS\_IN\_LAST for the last IN transactions on endpoint zero in a sequence of IN transactions.
- USB\_TRANS\_SETUP for setup transactions on endpoint zero.
- USB\_TRANS\_STATUS for status results on endpoint zero.

### Returns:

This call will return 0 on success, or -1 if a transmission is already in progress.

## 24.3.1.17 ROM USBEndpointDataToggleClear

Sets the Data toggle on an endpoint to zero.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBEndpointDataToggleClear is a function pointer located at ROM_USBTABLE[13].
```

#### Parameters:

```
ui32Base specifies the USB module base address.ui32Endpoint specifies the endpoint to reset the data toggle.ui32Flags specifies whether to access the IN or OUT endpoint.
```

## **Description:**

This function will cause the controller to clear the data toggle for an endpoint. This call is not valid for endpoint zero and can be made with host or device controllers.

The *ui32Flags* parameter should be one of **USB\_EP\_HOST\_OUT**, **USB\_EP\_HOST\_IN**, **USB\_EP\_DEV\_OUT**, or **USB\_EP\_DEV\_IN**.

#### Returns:

None.

## 24.3.1.18 ROM USBEndpointDMAChannel

Sets the DMA channel to use for a given endpoint.

### Prototype:

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBEndpointDMAChannel is a function pointer located at ROM_USBTABLE[47].
```

#### Parameters:

ui32Base specifies the USB module base address.ui32Endpoint specifies which endpoint's FIFO address to return.ui32Channel specifies which DMA channel to use for which endpoint.

## **Description:**

This function is used to configure which DMA channel to use with a given endpoint. Receive DMA channels can only be used with receive endpoints and transmit DMA channels can only

be used with transmit endpoints. This allows the 3 receive and 3 transmit DMA channels to be mapped to any endpoint other than 0. The values that should be passed into the *ui32Channel* value are the UDMA\_CHANNEL\_USBEP\* values defined in udma.h.

### Note:

This function only has an effect on microcontrollers that have the ability to change the DMA channel for an endpoint. Calling this function on other devices will have no effect.

#### Returns:

None.

## 24.3.1.19 ROM USBEndpointDMADisable

Disable DMA on a given endpoint.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBEndpointDMADisable is a function pointer located at ROM_USBTABLE[43].
```

#### Parameters:

```
ui32Base specifies the USB module base address.ui32Endpoint is the endpoint to access.ui32Flags specifies which direction to disable.
```

#### **Description:**

This function will disable DMA on a given end point to allow non-DMA USB transactions to generate interrupts normally. The *ui32Flags* should be **USB\_EP\_DEV\_IN** or **USB\_EP\_DEV\_OUT** all other bits are ignored.

#### Returns:

None.

## 24.3.1.20 ROM USBEndpointDMAEnable

Enable DMA on a given endpoint.

#### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBEndpointDMAEnable is a function pointer located at ROM_USBTABLE[42].
```

#### Parameters:

ui32Base specifies the USB module base address.

ui32Endpoint is the endpoint to access.

ui32Flags specifies which direction and what mode to use when enabling DMA.

## **Description:**

This function will enable DMA on a given endpoint and set the mode according to the values in the *ui32Flags* parameter. The *ui32Flags* parameter should have **USB\_EP\_DEV\_IN** or **USB\_EP\_DEV\_OUT** set.

#### Returns:

None.

## 24.3.1.21 ROM\_USBEndpointStatus

Returns the current status of an endpoint.

## Prototype:

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBEndpointStatus is a function pointer located at ROM_USBTABLE[14].
```

### Parameters:

ui32Base specifies the USB module base address.ui32Endpoint is the endpoint to access.

#### **Description:**

This function will return the status of a given endpoint. If any of these status bits need to be cleared, then these these values must be cleared by calling the ROM\_USBDevEndpointStatusClear() or ROM\_USBHostEndpointStatusClear() functions.

The following are the status flags for host mode:

- USB\_HOST\_IN\_PID\_ERROR PID error on the given endpoint.
- USB\_HOST\_IN\_NOT\_COMP The device failed to respond to an IN request.
- USB HOST IN STALL A stall was received on an IN endpoint.
- USB\_HOST\_IN\_DATA\_ERROR There was a CRC or bit-stuff error on an IN endpoint in Isochronous mode.
- USB\_HOST\_IN\_NAK\_TO NAKs received on this IN endpoint for more than the specified timeout period.
- USB HOST IN ERROR Failed to communicate with a device using this IN endpoint.
- USB\_HOST\_IN\_FIFO\_FULL This IN endpoint's FIFO is full.

- USB\_HOST\_IN\_PKTRDY Data packet ready on this IN endpoint.
- USB\_HOST\_OUT\_NAK\_TO NAKs received on this OUT endpoint for more than the specified timeout period.
- USB HOST OUT NOT COMP The device failed to respond to an OUT request.
- USB HOST OUT STALL A stall was received on this OUT endpoint.
- USB\_HOST\_OUT\_ERROR Failed to communicate with a device using this OUT endpoint.
- USB HOST OUT FIFO NE This endpoint's OUT FIFO is not empty.
- USB\_HOST\_OUT\_PKTPEND The data transfer on this OUT endpoint has not completed.
- USB\_HOST\_EP0\_NAK\_TO NAKs received on endpoint zero for more than the specified timeout period.
- USB HOST EP0 ERROR The device failed to respond to a request on endpoint zero.
- USB HOST EP0 IN STALL A stall was received on endpoint zero for an IN transaction.
- USB\_HOST\_EP0\_IN\_PKTRDY Data packet ready on endpoint zero for an IN transaction.

The following are the status flags for device mode:

- USB DEV OUT SENT STALL A stall was sent on this OUT endpoint.
- USB\_DEV\_OUT\_DATA\_ERROR There was a CRC or bit-stuff error on an OUT endpoint.
- USB DEV OUT OVERRUN An OUT packet was not loaded due to a full FIFO.
- USB\_DEV\_OUT\_FIFO\_FULL The OUT endpoint's FIFO is full.
- USB\_DEV\_OUT\_PKTRDY There is a data packet ready in the OUT endpoint's FIFO.
- USB\_DEV\_IN\_NOT\_COMP A larger packet was split up, more data to come.
- USB DEV IN SENT STALL A stall was sent on this IN endpoint.
- **USB\_DEV\_IN\_UNDERRUN** Data was requested on the IN endpoint and no data was ready.
- USB DEV IN FIFO NE The IN endpoint's FIFO is not empty.
- USB\_DEV\_IN\_PKTPEND The data transfer on this IN endpoint has not completed.
- USB\_DEV\_EP0\_SETUP\_END A control transaction ended before Data End condition was sent.
- USB\_DEV\_EP0\_SENT\_STALL A stall was sent on endpoint zero.
- USB DEV EP0 IN PKTPEND The data transfer on endpoint zero has not completed.
- USB\_DEV\_EP0\_OUT\_PKTRDY There is a data packet ready in endpoint zero's OUT FIFO.

#### Returns:

The current status flags for the endpoint depending on mode.

## 24.3.1.22 ROM\_USBFIFOAddrGet

Returns the absolute FIFO address for a given endpoint.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].
ROM_USBFIFOAddrGet is a function pointer located at ROM_USBTABLE[15].
```

#### Parameters:

ui32Base specifies the USB module base address.ui32Endpoint specifies which endpoint's FIFO address to return.

#### **Description:**

This function returns the actual physical address of the FIFO. This is needed when the USB is going to be used with the uDMA controller and the source or destination address needs to be set to the physical FIFO address for a given endpoint.

### Returns:

None.

## 24.3.1.23 ROM USBFIFOConfigGet

Returns the FIFO configuration for an endpoint.

## Prototype:

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBFIFOConfigGet is a function pointer located at ROM_USBTABLE[16].
```

### Parameters:

```
ui32Base specifies the USB module base address.
ui32Endpoint is the endpoint to access.
pui32FIFOAddress is the starting address for the FIFO.
pui32FIFOSize is the size of the FIFO in bytes.
ui32Flags specifies what information to retrieve from the FIFO configuration.
```

### **Description:**

This function will return the starting address and size of the FIFO for a given endpoint. Endpoint zero does not have a dynamically configurable FIFO so this function should not be called for endpoint zero. The *ui32Flags* parameter specifies whether the endpoint's OUT or IN FIFO should be read. If in host mode, the *ui32Flags* parameter should be **USB\_EP\_HOST\_OUT** or **USB\_EP\_HOST\_IN**, and if in device mode the *ui32Flags* parameter should be either **USB\_EP\_DEV\_OUT** or **USB\_EP\_DEV\_IN**.

## Returns:

None.

## 24.3.1.24 ROM USBFIFOConfigSet

Sets the FIFO configuration for an endpoint.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBFIFOConfigSet is a function pointer located at ROM_USBTABLE[17].
```

#### Parameters:

```
ui32Base specifies the USB module base address.
ui32Endpoint is the endpoint to access.
ui32FIFOAddress is the starting address for the FIFO.
ui32FIFOSize is the size of the FIFO in bytes.
ui32Flags specifies what information to set in the FIFO configuration.
```

## Description:

This function will set the starting FIFO RAM address and size of the FIFO for a given endpoint. Endpoint zero does not have a dynamically configurable FIFO so this function should not be called for endpoint zero. The *ui32FIFOSize* parameter should be one of the values in the **USB\_FIFO\_SZ\_** values. If the endpoint is going to use double buffering it should use the values with the **\_DB** at the end of the value. For example, use **USB\_FIFO\_SZ\_16\_DB** to configure an endpoint to have a 16 byte double buffered FIFO. If a double buffered FIFO is used, then the actual size of the FIFO is twice the size indicated by the *ui32FIFOSize* parameter. This means that the **USB\_FIFO\_SZ\_16\_DB** value will use 32 bytes of the USB controller's FIFO memory.

The *ui32FIFOAddress* value should be a multiple of 8 bytes and directly indicates the starting address in the USB controller's FIFO RAM. For example, a value of 64 indicates that the FIFO should start 64 bytes into the USB controller's FIFO memory. The *ui32Flags* value specifies whether the endpoint's OUT or IN FIFO should be configured. If in host mode, use USB\_EP\_HOST\_OUT or USB\_EP\_HOST\_IN, and if in device mode use USB\_EP\_DEV\_OUT or USB\_EP\_DEV\_IN.

#### Returns:

None.

## 24.3.1.25 ROM USBFIFOFlush

Forces a flush of an endpoint's FIFO.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBFIFOFlush is a function pointer located at ROM_USBTABLE[18].
```

#### Parameters:

ui32Base specifies the USB module base address.ui32Endpoint is the endpoint to access.ui32Flags specifies if the IN or OUT endpoint should be accessed.

## **Description:**

This function will force the controller to flush out the data in the FIFO. The function can be called with either host or device controllers and requires the *ui32Flags* parameter be one of **USB EP HOST OUT**, **USB EP HOST IN**, **USB EP DEV OUT**, or **USB EP DEV IN**.

#### Returns:

None.

## 24.3.1.26 ROM USBFrameNumberGet

Get the current frame number.

## Prototype:

```
uint32_t
ROM_USBFrameNumberGet(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBFrameNumberGet is a function pointer located at ROM_USBTABLE[19].
```

#### Parameters:

ui32Base specifies the USB module base address.

## **Description:**

This function returns the last frame number received.

#### Returns:

The last frame number received.

## 24.3.1.27 ROM\_USBHostAddrGet

Gets the current functional device address for an endpoint.

### Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].
ROM_USBHostAddrGet is a function pointer located at ROM_USBTABLE[20].
```

#### Parameters:

ui32Base specifies the USB module base address.ui32Endpoint is the endpoint to access.ui32Flags determines if this is an IN or an OUT endpoint.

#### Description:

This function returns the current functional address that an endpoint is using to communicate with a device. The *ui32Flags* parameter determines if the IN or OUT endpoint's device address is returned.

### Note:

This function should only be called in host mode.

#### Returns:

Returns the current function address being used by an endpoint.

## 24.3.1.28 ROM USBHostAddrSet

Sets the functional address for the device that is connected to an endpoint in host mode.

## Prototype:

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBHostAddrSet is a function pointer located at ROM_USBTABLE[21].
```

#### Parameters:

ui32Base specifies the USB module base address.

ui32Endpoint is the endpoint to access.

 ${\it ui32Addr}$  is the functional address for the controller to use for this endpoint.

ui32Flags determines if this is an IN or an OUT endpoint.

#### **Description:**

This function will set the functional address for a device that is using this endpoint for communication. This *ui32Addr* parameter is the address of the target device that this endpoint is used to communicate with. The *ui32Flags* parameter indicates if the IN or OUT endpoint should be set.

### Note:

This function should only be called in host mode.

#### Returns:

None.

## 24.3.1.29 ROM USBHostEndpointConfig

Sets the base configuration for a host endpoint.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBHostEndpointConfig is a function pointer located at ROM_USBTABLE[22].
```

#### Parameters:

ui32Base specifies the USB module base address.

ui32Endpoint is the endpoint to access.

ui32MaxPayload is the maximum payload for this endpoint.

*ui32NAKPollInterval* is the either the NAK timeout limit or the polling interval depending on the type of endpoint.

ui32TargetEndpoint is the endpoint that the host endpoint is targeting.

ui32Flags are used to configure other endpoint settings.

#### **Description:**

This function will set the basic configuration for the transmit or receive portion of an endpoint in host mode. The *ui32Flags* parameter determines some of the configuration while the other parameters provide the rest. The *ui32Flags* parameter determines whether this is an IN endpoint (USB\_EP\_HOST\_IN or USB\_EP\_DEV\_IN) or an OUT endpoint (USB\_EP\_HOST\_OUT or USB\_EP\_DEV\_OUT), whether this is a Full speed endpoint (USB\_EP\_SPEED\_FULL) or a Low speed endpoint (USB\_EP\_SPEED\_LOW).

The **USB\_EP\_MODE**\_ flags control the type of the endpoint.

- USB EP MODE CTRL is a control endpoint.
- USB EP MODE ISOC is an isochronous endpoint.
- USB\_EP\_MODE\_BULK is a bulk endpoint.
- USB\_EP\_MODE\_INT is an interrupt endpoint.

The *ui32NAKPollInterval* parameter has different meanings based on the **USB\_EP\_MODE** value and whether or not this call is being made for endpoint zero or another endpoint. For endpoint zero or any Bulk endpoints, this value always indicates the number of frames to allow a device to NAK before considering it a timeout. If this endpoint is an isochronous or interrupt endpoint, this value is the polling interval for this endpoint.

For interrupt endpoints the polling interval is simply the number of frames between polling an interrupt endpoint. For isochronous endpoints this value represents a polling interval of 2 ^ (ui32NAKPollInterval - 1) frames. When used as a NAK timeout, the ui32NAKPollInterval value specifies 2 ^ (ui32NAKPollInterval - 1) frames before issuing a time out. There are two special time out values that can be specified when setting the ui32NAKPollInterval value. The first is MAX NAK LIMIT which is the maximum value that can be passed in this variable. The

other is **DISABLE\_NAK\_LIMIT** which indicates that there should be no limit on the number of NAKs.

The **USB\_EP\_DMA\_MODE\_** flags enables the type of DMA used to access the endpoint's data FIFOs. The choice of the DMA mode depends on how the DMA controller is configured and how it is being used. See the "Using USB with the uDMA Controller" section for more information on DMA configuration.

When configuring the OUT portion of an endpoint, the **USB\_EP\_AUTO\_SET** bit is specified to cause the transmission of data on the USB bus to start as soon as the number of bytes specified by *ui32MaxPayload* have been written into the OUT FIFO for this endpoint.

When configuring the IN portion of an endpoint, the **USB\_EP\_AUTO\_REQUEST** bit can be specified to trigger the request for more data once the FIFO has been drained enough to fit *ui32MaxPayload* bytes. The **USB\_EP\_AUTO\_CLEAR** bit can be used to clear the data packet ready flag automatically once the data has been read from the FIFO. If this is not used, this flag must be manually cleared via a call to ROM\_USBDevEndpointStatusClear() or ROM\_USBHostEndpointStatusClear().

#### Note:

This function should only be called in host mode.

#### Returns:

None.

## 24.3.1.30 ROM USBHostEndpointDataAck

Acknowledge that data was read from the given endpoint's FIFO in host mode.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBHostEndpointDataAck is a function pointer located at ROM_USBTABLE[23].
```

## Parameters:

ui32Base specifies the USB module base address.ui32Endpoint is the endpoint to access.

#### Description:

This function acknowledges that the data was read from the endpoint's FIFO. This call is used if processing is required between reading the data and acknowledging that the data has been read.

#### Note:

This function should only be called in host mode.

### Returns:

None.

## 24.3.1.31 ROM USBHostEndpointDataToggle

Sets the value data toggle on an endpoint in host mode.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBHostEndpointDataToggle is a function pointer located at ROM_USBTABLE[24].
```

#### Parameters:

ui32Base specifies the USB module base address.
 ui32Endpoint specifies the endpoint to reset the data toggle.
 bDataToggle specifies whether to set the state to DATA0 or DATA1.
 ui32Flags specifies whether to set the IN or OUT endpoint.

### **Description:**

This function is used to force the state of the data toggle in host mode. If the value passed in the *bDataToggle* parameter is **false**, then the data toggle is set to the DATA0 state, and if it is **true** it is set to the DATA1 state. The *ui32Flags* parameter can be **USB\_EP\_HOST\_IN** or **USB\_EP\_HOST\_OUT** to access the desired portion of this endpoint. The *ui32Flags* parameter is ignored for endpoint zero.

#### Note

This function should only be called in host mode.

#### Returns:

None.

## 24.3.1.32 ROM\_USBHostEndpointStatusClear

Clears the status bits in this endpoint in host mode.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBHostEndpointStatusClear is a function pointer located at ROM_USBTABLE[25].
```

### Parameters:

ui32Base specifies the USB module base address.

ui32Endpoint is the endpoint to access.ui32Flags are the status bits that should be cleared.

## **Description:**

This function will clear the status of any bits that are passed in the *ui32Flags* parameter. The *ui32Flags* parameter can take the value returned from the ROM\_USBEndpointStatus() call.

#### Note:

This function should only be called in host mode.

#### Returns:

None.

## 24.3.1.33 ROM USBHostHubAddrGet

Get the current device hub address for this endpoint.

## Prototype:

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBHostHubAddrGet is a function pointer located at ROM_USBTABLE[26].
```

#### Parameters:

```
ui32Base specifies the USB module base address.ui32Endpoint is the endpoint to access.ui32Flags determines if this is an IN or an OUT endpoint.
```

#### **Description:**

This function will return the current hub address that an endpoint is using to communicate with a device. The *ui32Flags* parameter determines if the device address for the IN or OUT endpoint is returned.

#### Note:

This function should only be called in host mode.

#### Returns:

This function returns the current hub address being used by an endpoint.

## 24.3.1.34 ROM\_USBHostHubAddrSet

Set the hub address for the device that is connected to an endpoint.

### Prototype:

```
void
ROM_USBHostHubAddrSet(uint32_t ui32Base,
```

```
uint32_t ui32Endpoint,
uint32_t ui32Addr,
uint32_t ui32Flags)
```

### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBHostHubAddrSet is a function pointer located at ROM_USBTABLE[27].
```

### Parameters:

ui32Base specifies the USB module base address.
ui32Endpoint is the endpoint to access.
ui32Addr is the hub address for the device using this endpoint.
ui32Flags determines if this is an IN or an OUT endpoint.

## **Description:**

This function will set the hub address for a device that is using this endpoint for communication. The *ui32Flags* parameter determines if the device address for the IN or the OUT endpoint is set by this call.

### Note:

This function should only be called in host mode.

#### Returns:

None.

## 24.3.1.35 ROM USBHostMode

Change the mode of the USB controller to host.

## Prototype:

```
void
ROM_USBHostMode(uint32_t ui32Base)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].
ROM_USBHostMode is a function pointer located at ROM_USBTABLE[54].
```

## Parameters:

ui32Base specifies the USB module base address.

#### Description

This function changes the mode of the USB controller to host mode.

## Returns:

None.

# 24.3.1.36 ROM USBHostPwrConfig

Sets the configuration for USB power fault.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].
ROM_USBHostPwrConfig is a function pointer located at ROM_USBTABLE[30].
```

#### Parameters:

ui32Base specifies the USB module base address.ui32Flags specifies the configuration of the power fault.

## **Description:**

This function controls how the USB controller uses its external power control pins (USBnPFTL and USBnEPEN). The flags specify the power fault level sensitivity, the power fault action, and the power enable level and source.

One of the following can be selected as the power fault level sensitivity:

- USB\_HOST\_PWRFLT\_LOW An external power fault is indicated by the pin being driven low.
- USB\_HOST\_PWRFLT\_HIGH An external power fault is indicated by the pin being driven high.

One of the following can be selected as the power fault action:

- USB HOST PWRFLT EP NONE No automatic action when power fault detected.
- USB\_HOST\_PWRFLT\_EP\_TRI Automatically Tri-state the USBnEPEN pin on a power fault.
- USB\_HOST\_PWRFLT\_EP\_LOW Automatically drive USBnEPEN pin low on a power fault.
- USB\_HOST\_PWRFLT\_EP\_HIGH Automatically drive USBnEPEN pin high on a power fault.

One of the following can be selected as the power enable level and source:

- USB\_HOST\_PWREN\_MAN\_LOW USBEPEN is driven low by the USB controller when ROM\_USBHostPwrEnable() is called.
- USB\_HOST\_PWREN\_MAN\_HIGH USBEPEN is driven high by the USB controller when ROM\_USBHostPwrEnable() is called.
- **USB\_HOST\_PWREN\_AUTOLOW** USBEPEN is driven low by the USB controller automatically if USBOTGSessionRequest() has enabled a session.
- **USB\_HOST\_PWREN\_AUTOHIGH** USBEPEN is driven high by the USB controller automatically if USBOTGSessionRequest() has enabled a session.

The **USB\_HOST\_PWREN\_FILTER** flag can be added to enable the VBUS glitch filter, which ignores small, short drops in VBUS level caused by high power consumption. This is mainly used to avoid causing VBUS errors caused by devices with high in-rush current.

This function should only be called in host mode.

#### Returns:

None.

# 24.3.1.37 ROM USBHostPwrDisable

Disables the external power pin.

## Prototype:

```
void
```

ROM\_USBHostPwrDisable(uint32\_t ui32Base)

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBHostPwrDisable is a function pointer located at ROM_USBTABLE[28].
```

#### Parameters:

ui32Base specifies the USB module base address.

## **Description:**

This function disables the USBEPEN signal to disable an external power supply in host mode operation.

## Note:

This function should only be called in host mode.

## Returns:

None.

# 24.3.1.38 ROM USBHostPwrEnable

Enables the external power pin.

#### Prototype:

```
void
```

ROM\_USBHostPwrEnable(uint32\_t ui32Base)

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBHostPwrEnable is a function pointer located at ROM_USBTABLE[29].
```

#### Parameters:

ui32Base specifies the USB module base address.

## **Description:**

This function enables the USBEPEN signal to enable an external power supply in host mode operation.

This function should only be called in host mode.

#### Returns:

None.

# 24.3.1.39 ROM USBHostPwrFaultDisable

Disables power fault detection.

## Prototype:

void

ROM\_USBHostPwrFaultDisable(uint32\_t ui32Base)

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBHostPwrFaultDisable is a function pointer located at ROM_USBTABLE[31].
```

#### Parameters:

ui32Base specifies the USB module base address.

## **Description:**

This function disables power fault detection in the USB controller.

## Note:

This function should only be called in host mode.

## Returns:

None.

# 24.3.1.40 ROM USBHostPwrFaultEnable

Enables power fault detection.

## Prototype:

```
void
```

ROM\_USBHostPwrFaultEnable(uint32\_t ui32Base)

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBHostPwrFaultEnable is a function pointer located at ROM_USBTABLE[32].
```

#### Parameters:

ui32Base specifies the USB module base address.

# **Description:**

This function enables power fault detection in the USB controller. If the USBPFLT pin is not in use this function should not be used.

This function should only be called in host mode.

#### Returns:

None.

# 24.3.1.41 ROM USBHostRequestIN

Schedules a request for an IN transaction on an endpoint in host mode.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBHostRequestIN is a function pointer located at ROM_USBTABLE[33].
```

#### Parameters:

ui32Base specifies the USB module base address.ui32Endpoint is the endpoint to access.

## **Description:**

This function will schedule a request for an IN transaction. When the USB device being communicated with responds the data, the data can be retrieved by calling ROM USBEndpointDataGet() or via a DMA transfer.

#### Note:

This function should only be called in host mode.

#### Returns:

None.

# 24.3.1.42 ROM\_USBHostRequestINClear

Clears a scheduled IN transaction for an endpoint in host mode.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBHostRequestINClear is a function pointer located at ROM_USBTABLE[60].
```

## Parameters:

ui32Base specifies the USB module base address.

ui32Endpoint is the endpoint to access.

# Description:

This function clears a previously scheduled IN transaction if it is still pending. This function is used to safely disable any scheduled IN transactions if the endpoint specified by *ui32Endpoint* is reconfigured for communications with other devices.

#### Note:

This function must only be called in host mode and only for IN endpoints.

#### Returns:

None.

# 24.3.1.43 ROM USBHostRequestStatus

Issues a request for a status IN transaction on endpoint zero.

## Prototype:

```
void
ROM_USBHostRequestStatus(uint32_t ui32Base)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBHostRequestStatus is a function pointer located at ROM_USBTABLE[34].
```

## Parameters:

ui32Base specifies the USB module base address.

## **Description:**

This function is used to cause a request for an status IN transaction from a device on endpoint zero. This function can only be used with endpoint zero as that is the only control endpoint that supports this ability. This is used to complete the last phase of a control transaction to a device and an interrupt is signaled when the status packet has been received.

#### Returns:

None.

# 24.3.1.44 ROM USBHostReset

Handles the USB bus reset condition.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBHostReset is a function pointer located at ROM_USBTABLE[35].
```

## Parameters:

ui32Base specifies the USB module base address.

**bStart** specifies whether to start or stop signaling reset on the USB bus.

## **Description:**

When this function is called with the *bStart* parameter set to **true**, this function will cause the start of a reset condition on the USB bus. The caller should then delay at least 20ms before calling this function again with the *bStart* parameter set to **false**.

#### Note:

This function should only be called in host mode.

#### Returns:

None.

# 24.3.1.45 ROM USBHostResume

Handles the USB bus resume condition.

## Prototype:

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBHostResume is a function pointer located at ROM_USBTABLE[36].
```

#### Parameters:

ui32Base specifies the USB module base address.

**bStart** specifies if the USB controller is entering or leaving the resume signaling state.

#### Description:

When in device mode this function will bring the USB controller out of the suspend state. This call should first be made with the *bStart* parameter set to **true** to start resume signaling. The device application should then delay at least 10ms but not more than 15ms before calling this function with the *bStart* parameter set to **false**.

When in host mode this function will signal devices to leave the suspend state. This call should first be made with the *bStart* parameter set to **true** to start resume signaling. The host application should then delay at least 20ms before calling this function with the *bStart* parameter set to **false**. This will cause the controller to complete the resume signaling on the USB bus.

#### Returns:

None.

# 24.3.1.46 ROM\_USBHostSpeedGet

Returns the current speed of the USB device connected.

## Prototype:

```
uint32_t
ROM_USBHostSpeedGet(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBHostSpeedGet is a function pointer located at ROM_USBTABLE[37].
```

## Parameters:

ui32Base specifies the USB module base address.

## **Description:**

This function will return the current speed of the USB bus.

#### Note:

This function should only be called in host mode.

#### Returns:

Returns either USB\_LOW\_SPEED, USB\_FULL\_SPEED, or USB\_UNDEF\_SPEED.

# 24.3.1.47 ROM\_USBHostSuspend

Puts the USB bus in a suspended state.

## Prototype:

```
void
ROM_USBHostSuspend(uint32_t ui32Base)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].
ROM_USBHostSuspend is a function pointer located at ROM_USBTABLE[38].
```

#### Parameters:

ui32Base specifies the USB module base address.

## **Description:**

When used in host mode, this function will put the USB bus in the suspended state.

#### Note:

This function should only be called in host mode.

# Returns:

None.

# 24.3.1.48 ROM USBIntDisableControl

Disables control interrupts on a given USB controller.

## **Prototype:**

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBIntDisableControl is a function pointer located at ROM_USBTABLE[48].
```

#### Parameters:

ui32Base specifies the USB module base address.ui32Flags specifies which control interrupts to disable.

## **Description:**

This function will disable the control interrupts for the USB controller specified by the *ui32Base* parameter. The *ui32Flags* parameter specifies which control interrupts to disable. The flags passed in the *ui32Flags* parameters should be the definitions that start with **USB\_INTCTRL\_\*** and not any other **USB\_INT** flags.

#### Returns:

None.

# 24.3.1.49 ROM\_USBIntDisableEndpoint

Disables endpoint interrupts on a given USB controller.

#### Prototype:

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBIntDisableEndpoint is a function pointer located at ROM_USBTABLE[51].
```

#### Parameters:

```
ui32Base specifies the USB module base address.ui32Flags specifies which endpoint interrupts to disable.
```

## **Description:**

This function will disable endpoint interrupts for the USB controller specified by the *ui32Base* parameter. The *ui32Flags* parameter specifies which endpoint interrupts to disable. The flags passed in the *ui32Flags* parameters should be the definitions that start with **USB\_INTEP\_\*** and not any other **USB\_INT** flags.

## Returns:

None.

# 24.3.1.50 ROM USBIntEnableControl

Enables control interrupts on a given USB controller.

# Prototype:

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBIntEnableControl is a function pointer located at ROM_USBTABLE[49].
```

#### Parameters:

```
ui32Base specifies the USB module base address.ui32Flags specifies which control interrupts to enable.
```

## **Description:**

This function will enable the control interrupts for the USB controller specified by the *ui32Base* parameter. The *ui32Flags* parameter specifies which control interrupts to enable. The flags passed in the *ui32Flags* parameters should be the definitions that start with **USB\_INTCTRL\_\*** and not any other **USB\_INT** flags.

#### Returns:

None.

# 24.3.1.51 ROM USBIntEnableEndpoint

Enables endpoint interrupts on a given USB controller.

## Prototype:

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBIntEnableEndpoint is a function pointer located at ROM_USBTABLE[52].
```

#### **Parameters:**

```
ui32Base specifies the USB module base address.ui32Flags specifies which endpoint interrupts to enable.
```

#### **Description:**

This function will enable endpoint interrupts for the USB controller specified by the *ui32Base* parameter. The *ui32Flags* parameter specifies which endpoint interrupts to enable. The flags passed in the *ui32Flags* parameters should be the definitions that start with **USB\_INTEP\_\*** and not any other **USB\_INT** flags.

#### Returns:

None.

## 24.3.1.52 ROM USBIntStatusControl

Returns the control interrupt status on a given USB controller.

## Prototype:

```
uint32_t
ROM_USBIntStatusControl(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBIntStatusControl is a function pointer located at ROM_USBTABLE[50].
```

#### Parameters:

ui32Base specifies the USB module base address.

## **Description:**

This function will read control interrupt status for a USB controller. This call will return the current status for control interrupts only, the endpoint interrupt status is retrieved by calling ROM\_USBIntStatusEndpoint(). The bit values returned should be compared against the USB\_INTCTRL\_\* values.

The following are the meanings of all **USB\_INCTRL**\_ flags and the modes for which they are valid. These values apply to any calls to ROM\_USBIntStatusControl(), ROM\_USBIntEnableControl(), and ROM\_USBIntDisableControl(). Some of these flags are only valid in the following modes as indicated in the parenthesis: Host, Device, and OTG.

- USB INTCTRL ALL A full mask of all control interrupt sources.
- USB\_INTCTRL\_VBUS\_ERR A VBUS error has occurred (Host Only).
- USB INTCTRL SESSION Session Start Detected on A-side of cable (OTG Only).
- USB\_INTCTRL\_SESSION\_END Session End Detected (Device Only)
- USB INTCTRL DISCONNECT Device Disconnect Detected (Host Only)
- USB INTCTRL CONNECT Device Connect Detected (Host Only)
- USB INTCTRL SOF Start of Frame Detected.
- **USB\_INTCTRL\_BABBLE** USB controller detected a device signaling past the end of a frame. (Host Only)
- USB INTCTRL RESET Reset signaling detected by device. (Device Only)
- USB\_INTCTRL\_RESUME Resume signaling detected.
- USB INTCTRL SUSPEND Suspend signaling detected by device (Device Only)
- USB INTCTRL MODE DETECT OTG cable mode detection has completed (OTG Only)
- USB\_INTCTRL\_POWER\_FAULT Power Fault detected. (Host Only)

#### Note:

This call will clear the source of all of the control status interrupts.

## Returns:

Returns the status of the control interrupts for a USB controller.

## 24.3.1.53 ROM USBIntStatusEndpoint

Returns the endpoint interrupt status on a given USB controller.

## Prototype:

```
uint32_t
ROM_USBIntStatusEndpoint(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBIntStatusEndpoint is a function pointer located at ROM_USBTABLE[53].
```

#### Parameters:

ui32Base specifies the USB module base address.

#### **Description:**

This function will read endpoint interrupt status for a USB controller. This call will return the current status for endpoint interrupts only, the control interrupt status is retrieved by calling ROM\_USBIntStatusControl(). The bit values returned should be compared against the USB\_INTEP\_\* values. These are grouped into classes for USB\_INTEP\_HOST\_\* and USB\_INTEP\_DEV\_\* values to handle both host and device modes with all endpoints.

#### Note:

This call will clear the source of all of the endpoint interrupts.

#### Returns:

Returns the status of the endpoint interrupts for a USB controller.

# 24.3.1.54 ROM\_USBModeGet

Returns the current operating mode of the controller.

## Prototype:

```
uint32_t
ROM USBModeGet(uint32 t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].
ROM_USBModeGet is a function pointer located at ROM_USBTABLE[46].
```

#### **Parameters:**

ui32Base specifies the USB module base address.

#### **Description:**

This function returns the current operating mode on USB controllers with OTG or Dual mode functionality.

For OTG controllers:

The function will return on of the following values on OTG controllers: USB\_OTG\_MODE\_ASIDE\_HOST, USB\_OTG\_MODE\_ASIDE\_DEV, USB\_OTG\_MODE\_BSIDE\_DEV, USB\_OTG\_MODE\_BSIDE\_DEV, USB\_OTG\_MODE\_NONE.

**USB\_OTG\_MODE\_ASIDE\_HOST** indicates that the controller is in host mode on the A-side of the cable.

**USB\_OTG\_MODE\_ASIDE\_DEV** indicates that the controller is in device mode on the A-side of the cable.

**USB\_OTG\_MODE\_BSIDE\_HOST** indicates that the controller is in host mode on the B-side of the cable.

**USB\_OTG\_MODE\_BSIDE\_DEV** indicates that the controller is in device mode on the B-side of the cable. If and OTG session request is started with no cable in place this is the default mode for the controller.

**USB\_OTG\_MODE\_NONE** indicates that the controller is not attempting to determine its role in the system.

For Dual Mode controllers:

The function will return on of the following values: **USB\_DUAL\_MODE\_HOST**, **USB\_DUAL\_MODE\_DEVICE**, or **USB\_DUAL\_MODE\_NONE**.

USB\_DUAL\_MODE\_HOST indicates that the controller is acting as a host.

**USB\_DUAL\_MODE\_DEVICE** indicates that the controller acting as a device.

**USB DUAL MODE NONE** indicates that the controller is not active as either a host or device.

#### Returns:

Returns USB\_OTG\_MODE\_ASIDE\_HOST, USB\_OTG\_MODE\_ASIDE\_DEV, USB\_OTG\_MODE\_BSIDE\_HOST, USB\_OTG\_MODE\_BSIDE\_DEV, USB\_OTG\_MODE\_NONE, USB\_DUAL\_MODE\_HOST, USB\_DUAL\_MODE\_DEVICE, or USB\_DUAL\_MODE\_NONE.

# 24.3.1.55 ROM USBNumEndpointsGet

Returns the number of USB endpoint pairs on the device.

#### Prototype:

```
uint32_t
ROM_USBNumEndpointsGet(uint32_t ui32Base)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBNumEndpointsGet is a function pointer located at ROM_USBTABLE[61].
```

#### **Parameters:**

ui32Base specifies the USB module base address.

#### **Description:**

This function returns the number of endpoint pairs supported by the USB controller corresponding to the passed base address. The value returned is the number of IN or OUT endpoints available and does not include endpoint 0 (the control endpoint). For example, if 15 is returned, there are 15 IN and 15 OUT endpoints available in addition to endpoint 0.

#### Returns:

Returns the number of IN or OUT endpoints available.

# 24.3.1.56 ROM USBOTGMode

Change the mode of the USB controller to OTG.

## Prototype:

```
void
ROM_USBOTGMode(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.
ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].
ROM_USBOTGMode is a function pointer located at ROM_USBTABLE[59].
```

#### Parameters:

ui32Base specifies the USB module base address.

# **Description:**

This function changes the mode of the USB controller to OTG mode.

## Returns:

None.

# 24.3.1.57 ROM USBPHYPowerOff

Powers off the USB PHY.

## Prototype:

```
void
ROM_USBPHYPowerOff(uint32_t ui32Base)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_USBTABLE is an array of pointers located at ROM_APITABLE[16].

ROM_USBPHYPowerOff is a function pointer located at ROM_USBTABLE[56].
```

## Parameters:

ui32Base specifies the USB module base address.

## **Description:**

This function will power off the USB PHY, reducing the current consuption of the device. While in the powered off state, the USB controller is unable to operate.

## Returns:

None.

# 24.3.1.58 ROM USBPHYPowerOn

Powers on the USB PHY.

## Prototype:

```
void
```

ROM\_USBPHYPowerOn(uint32\_t ui32Base)

# **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_USBTABLE is an array of pointers located at ROM\_APITABLE[16].

ROM\_USBPHYPowerOn is a function pointer located at ROM\_USBTABLE[57].

## Parameters:

ui32Base specifies the USB module base address.

# **Description:**

This function will power on the USB PHY, enabling it return to normal operation. By default, the PHY is powered on, so this function only needs to be called if ROM\_USBPHYPowerOff() has previously been called.

# Returns:

None.

# 25 Watchdog Timer

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# 25.1 Introduction

The watchdog timer API provides a set of functions for using the watchdog timer module. Functions are provided to deal with the watchdog timer interrupts, and to handle status and configuration of the watchdog timer.

The watchdog timer module's function is to prevent system hangs. The watchdog timer module consists of a 32-bit down counter, a programmable load register, interrupt generation logic, and a locking register. Once the watchdog timer has been configured, the lock register can be written to prevent the timer configuration from being inadvertently altered.

The watchdog timer can be configured to generate an interrupt to the processor upon its first timeout, and to generate a reset signal upon its second timeout. The watchdog timer module generates the first timeout signal when the 32-bit counter reaches the zero state after being enabled; enabling the counter also enables the watchdog timer interrupt. After the first timeout event, the 32-bit counter is reloaded with the value of the watchdog timer load register, and the timer resumes counting down from that value. If the timer counts down to its zero state again before the first timeout interrupt is cleared, and the reset signal has been enabled, the watchdog timer asserts its reset signal to the system. If the interrupt is cleared before the 32-bit counter reaches its second timeout, the 32-bit counter is loaded with the value in the load register, and counting resumes from that value. If the load register is written with a new value while the watchdog timer counter is counting, then the counter is loaded with the new value and continues counting.

# 25.2 Functions

# **Functions**

- void ROM WatchdogEnable (uint32 t ui32Base)
- void ROM\_WatchdogIntClear (uint32\_t ui32Base)
- void ROM WatchdogIntEnable (uint32 t ui32Base)
- uint32\_t ROM\_WatchdogIntStatus (uint32\_t ui32Base, bool bMasked)
- void ROM\_WatchdogIntTypeSet (uint32\_t ui32Base, uint32\_t ui32Type)
- void ROM\_WatchdogLock (uint32\_t ui32Base)
- bool ROM WatchdogLockState (uint32 t ui32Base)
- uint32\_t ROM\_WatchdogReloadGet (uint32\_t ui32Base)
- void ROM\_WatchdogReloadSet (uint32\_t ui32Base, uint32\_t ui32LoadVal)
- void ROM WatchdogResetDisable (uint32 t ui32Base)
- void ROM WatchdogResetEnable (uint32 t ui32Base)
- bool ROM WatchdogRunning (uint32 t ui32Base)
- void ROM\_WatchdogStallDisable (uint32\_t ui32Base)
- void ROM\_WatchdogStallEnable (uint32\_t ui32Base)

- void ROM WatchdogUnlock (uint32 t ui32Base)
- uint32\_t ROM\_WatchdogValueGet (uint32\_t ui32Base)

# 25.2.1 Function Documentation

# 25.2.1.1 ROM WatchdogEnable

Enables the watchdog timer.

## Prototype:

void

ROM\_WatchdogEnable(uint32\_t ui32Base)

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_WATCHDOGTABLE is an array of pointers located at ROM_APITABLE[12].

ROM_WatchdogEnable is a function pointer located at ROM_WATCHDOGTABLE[2].
```

#### Parameters:

ui32Base is the base address of the watchdog timer module.

## **Description:**

This will enable the watchdog timer counter and interrupt.

#### Note:

This function will have no effect if the watchdog timer has been locked.

#### Returns:

None.

# 25.2.1.2 ROM\_WatchdogIntClear

Clears the watchdog timer interrupt.

## Prototype:

```
void
```

ROM\_WatchdogIntClear(uint32\_t ui32Base)

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_WATCHDOGTABLE is an array of pointers located at ROM_APITABLE[12].

ROM WatchdogIntClear is a function pointer located at ROM WATCHDOGTABLE[0].
```

## Parameters:

ui32Base is the base address of the watchdog timer module.

## **Description:**

The watchdog timer interrupt source is cleared, so that it no longer asserts.

Because there is a write buffer in the Cortex-M4 processor, it may take several clock cycles before the interrupt source is actually cleared. Therefore, it is recommended that the interrupt source be cleared early in the interrupt handler (as opposed to the very last action) to avoid returning from the interrupt handler before the interrupt source is actually cleared. Failure to do so may result in the interrupt handler being immediately reentered (because the interrupt controller still sees the interrupt source asserted).

#### Returns:

None.

# 25.2.1.3 ROM WatchdogIntEnable

Enables the watchdog timer interrupt.

#### Prototype:

```
void
ROM_WatchdogIntEnable(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_WATCHDOGTABLE is an array of pointers located at ROM_APITABLE[12].

ROM_WatchdogIntEnable is a function pointer located at ROM_WATCHDOGTABLE[11].
```

#### Parameters:

ui32Base is the base address of the watchdog timer module.

## **Description:**

Enables the watchdog timer interrupt.

## Note:

This function will have no effect if the watchdog timer has been locked.

## Returns:

None.

# 25.2.1.4 ROM\_WatchdogIntStatus

Gets the current watchdog timer interrupt status.

#### Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_WATCHDOGTABLE is an array of pointers located at ROM_APITABLE[12].

ROM_WatchdogIntStatus is a function pointer located at ROM_WATCHDOGTABLE[12].
```

## Parameters:

ui32Base is the base address of the watchdog timer module.

**bMasked** is **false** if the raw interrupt status is required and **true** if the masked interrupt status is required.

# Description:

This returns the interrupt status for the watchdog timer module. Either the raw interrupt status or the status of interrupt that is allowed to reflect to the processor can be returned.

#### Returns:

Returns the current interrupt status, where a 1 indicates that the watchdog interrupt is active, and a 0 indicates that it is not active.

# 25.2.1.5 ROM WatchdogIntTypeSet

Sets the type of interrupt generated by the watchdog.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_WATCHDOGTABLE is an array of pointers located at ROM_APITABLE[12].

ROM_WatchdogIntTypeSet is a function pointer located at ROM_WATCHDOGTABLE[15].
```

#### Parameters:

ui32Base is the base address of the watchdog timer module.ui32Type is the type of interrupt to generate.

## **Description:**

This function sets the type of interrupt that is generated if the watchdog timer expires. *ui32Type* can be either **WATCHDOG\_INT\_TYPE\_INT** to generate a standard interrupt (the default) or **WATCHDOG\_INT\_TYPE\_NMI** to generate a non-maskable interrupt (NMI).

When configured to generate an NMI, the watchdog interrupt must still be enabled with ROM\_WatchdogIntEnable(), and it must still be cleared inside the NMI handler with ROM\_WatchdogIntClear().

#### Returns:

None.

# 25.2.1.6 ROM WatchdogLock

Enables the watchdog timer lock mechanism.

# Prototype:

```
void
ROM_WatchdogLock(uint32_t ui32Base)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_WATCHDOGTABLE is an array of pointers located at ROM_APITABLE[12].
ROM_WatchdogLock is a function pointer located at ROM_WATCHDOGTABLE[5].
```

## Parameters:

ui32Base is the base address of the watchdog timer module.

## **Description:**

Locks out write access to the watchdog timer configuration registers.

#### Returns:

None.

# 25.2.1.7 ROM\_WatchdogLockState

Gets the state of the watchdog timer lock mechanism.

## Prototype:

```
bool
ROM_WatchdogLockState(uint32_t ui32Base)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_WATCHDOGTABLE is an array of pointers located at ROM_APITABLE[12].
ROM_WatchdogLockState is a function pointer located at ROM_WATCHDOGTABLE[7].
```

## Parameters:

ui32Base is the base address of the watchdog timer module.

#### **Description:**

Returns the lock state of the watchdog timer registers.

#### Returns:

Returns true if the watchdog timer registers are locked, and false if they are not locked.

# 25.2.1.8 ROM WatchdogReloadGet

Gets the watchdog timer reload value.

#### Prototype:

```
uint32_t
ROM_WatchdogReloadGet(uint32_t ui32Base)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_WATCHDOGTABLE is an array of pointers located at ROM_APITABLE[12].
ROM_WatchdogReloadGet is a function pointer located at ROM_WATCHDOGTABLE[9].
```

## Parameters:

*ui32Base* is the base address of the watchdog timer module.

## **Description:**

This function gets the value that is loaded into the watchdog timer when the count reaches zero for the first time.

#### Returns:

None.

# 25.2.1.9 ROM\_WatchdogReloadSet

Sets the watchdog timer reload value.

## Prototype:

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_WATCHDOGTABLE is an array of pointers located at ROM_APITABLE[12].

ROM_WatchdogReloadSet is a function pointer located at ROM_WATCHDOGTABLE[8].
```

#### Parameters:

ui32Base is the base address of the watchdog timer module.ui32LoadVal is the load value for the watchdog timer.

#### **Description:**

This function sets the value to load into the watchdog timer when the count reaches zero for the first time; if the watchdog timer is running when this function is called, then the value is immediately loaded into the watchdog timer counter. If the *ui32LoadVal* parameter is 0, then an interrupt is immediately generated.

#### Note:

This function will have no effect if the watchdog timer has been locked.

#### Returns:

None.

# 25.2.1.10 ROM WatchdogResetDisable

Disables the watchdog timer reset.

## Prototype:

```
void
ROM_WatchdogResetDisable(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_WATCHDOGTABLE is an array of pointers located at ROM_APITABLE[12].

ROM_WatchdogResetDisable is a function pointer located at ROM_WATCHDOGTABLE[4].
```

## Parameters:

ui32Base is the base address of the watchdog timer module.

# **Description:**

Disables the capability of the watchdog timer to issue a reset to the processor upon a second timeout condition.

#### Note:

This function will have no effect if the watchdog timer has been locked.

#### Returns:

None.

# 25.2.1.11 ROM\_WatchdogResetEnable

Enables the watchdog timer reset.

## Prototype:

```
void
```

ROM\_WatchdogResetEnable(uint32\_t ui32Base)

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_WATCHDOGTABLE is an array of pointers located at ROM_APITABLE[12].
ROM_WatchdogResetEnable is a function pointer located at ROM_WATCHDOGTABLE[3].
```

#### Parameters:

ui32Base is the base address of the watchdog timer module.

# **Description:**

Enables the capability of the watchdog timer to issue a reset to the processor upon a second timeout condition.

## Note:

This function will have no effect if the watchdog timer has been locked.

## Returns:

None.

# 25.2.1.12 ROM WatchdogRunning

Determines if the watchdog timer is enabled.

## Prototype:

```
bool
```

ROM\_WatchdogRunning(uint32\_t ui32Base)

# **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_WATCHDOGTABLE is an array of pointers located at ROM_APITABLE[12].

ROM_WatchdogRunning is a function pointer located at ROM_WATCHDOGTABLE[1].
```

#### Parameters:

ui32Base is the base address of the watchdog timer module.

## **Description:**

This will check to see if the watchdog timer is enabled.

## Returns:

Returns **true** if the watchdog timer is enabled, and **false** if it is not.

# 25.2.1.13 ROM WatchdogStallDisable

Disables stalling of the watchdog timer during debug events.

## Prototype:

```
void
ROM_WatchdogStallDisable(uint32_t ui32Base)
```

#### **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_WATCHDOGTABLE is an array of pointers located at ROM_APITABLE[12].

ROM_WatchdogStallDisable is a function pointer located at ROM_WATCHDOGTABLE[14].
```

#### **Parameters:**

ui32Base is the base address of the watchdog timer module.

## **Description:**

This function disables the debug mode stall of the watchdog timer. By doing so, the watchdog timer continues to count regardless of the processor debug state.

#### Returns:

None.

# 25.2.1.14 ROM\_WatchdogStallEnable

Enables stalling of the watchdog timer during debug events.

## Prototype:

```
void
ROM_WatchdogStallEnable(uint32_t ui32Base)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0x0100.0010.

ROM_WATCHDOGTABLE is an array of pointers located at ROM_APITABLE[12].

ROM_WatchdogStallEnable is a function pointer located at ROM_WATCHDOGTABLE[13].
```

#### Parameters:

ui32Base is the base address of the watchdog timer module.

## Description:

This function allows the watchdog timer to stop counting when the processor is stopped by the debugger. By doing so, the watchdog is prevented from expiring (typically almost immediately from a human time perspective) and resetting the system (if reset is enabled). The watchdog will instead expired after the appropriate number of processor cycles have been executed while debugging (or at the appropriate time after the processor has been restarted).

## Returns:

None.

# 25.2.1.15 ROM\_WatchdogUnlock

Disables the watchdog timer lock mechanism.

## Prototype:

void
ROM\_WatchdogUnlock(uint32\_t ui32Base)

## **ROM Location:**

ROM\_APITABLE is an array of pointers located at 0x0100.0010.

ROM\_WATCHDOGTABLE is an array of pointers located at ROM\_APITABLE[12].

ROM\_WatchdogUnlock is a function pointer located at ROM\_WATCHDOGTABLE[6].

#### Parameters:

ui32Base is the base address of the watchdog timer module.

## **Description:**

Enables write access to the watchdog timer configuration registers.

#### Returns:

None.

# 25.2.1.16 ROM WatchdogValueGet

Gets the current watchdog timer value.

## Prototype:

```
uint32_t
ROM_WatchdogValueGet(uint32_t ui32Base)
```

## **ROM Location:**

```
ROM_APITABLE is an array of pointers located at 0 \times 0100.0010.
ROM_WATCHDOGTABLE is an array of pointers located at ROM_APITABLE[12].
ROM_WatchdogValueGet is a function pointer located at ROM_WATCHDOGTABLE[10].
```

## Parameters:

ui32Base is the base address of the watchdog timer module.

## **Description:**

This function reads the current value of the watchdog timer.

#### Returns:

Returns the current value of the watchdog timer.

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